SIEMENS

SIMADYN D

Application Module FM 458

User Manual

Contents

Order No.: 6DD1904-0AE0

Safety guidelines

This Manual contains notices which you should observe to ensure your own personal safety, as well as to protect the product and connected equipment. These notices are highlighted in the Manual by a warning triangle and are marked as follows according to the level of danger:

DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

CAUTION used with the safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury.

CAUTION used without safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in property damage.

NOTICE used without the safety alert symbol indicates a potential situation which, if not avoided, may result in an undesireable result or state.

Correct usage

Note the following:

This device and its components may only be used for the applications described in the catalog or the technical description, and only in connection with devices or components from other manufacturers which have been approved or recommended by Siemens.

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Disclaimer of liability

We have checked the contents of this manual for agreement with the hardware and software described. Since deviations cannot be precluded entirely, we cannot guarantee full agreement. However, the data in this manual are reviewed regularly and any necessary corrections included in subsequent editions. Suggestions for improvement are welcomed.

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Contents

1 Definitions

General information

These Operating Instructions do not contain all of the detailed information for all product types for reasons of transparency. This means that they cannot take into account all conceivable situations regarding the configuration, operation or service. If you require additional information, or if specific problems occur, which are not handled in sufficient detail in the Operating Instructions, then you can request the necessary information from your local Siemens Office.

We would also like to point-out, that the contents of the operating instructions are neither part of an earlier or existing agreement, statement or legal relationship, nor do they change this. All of the contractual responsibilities of Siemens AG are specified in the purchase contract which includes the complete and exclusively valid warranty. The contractual warranty is neither expanded nor restricted by the information provided in these Operating Instructions.

Qualified personnel

For the purpose of these Operating Instructions and product labels, a „Qualified person“ is someone who is familiar with the installation, mounting, start-up and operation of the equipment and the hazards involved. He or she must have the following qualifications:

1. Trained and authorized to energize, de-energize, clear, ground and tag circuits and equipment in accordance with established safety procedures.
2. Trained in the proper care and use of protective equipment in accordance with established safety procedures.
3. Trained in rendering first aid

CAUTION

The boards contain components which can be destroyed by electrostatic discharge. Prior to touching any electronics board, your body must be electrically discharged. This can be simply done by touching a conductive, grounded object immediately beforehand (e.g. bare metal cabinet components, socket protective conductor contact).

2 Product description

2.1 Application module FM 458

Designation	Order No.
Application module FM 458	6DD1607-0AA0

2.1.1 Application and design

Application

The FM 458 (**F**unction **M**odule) application module is an application module which can be graphically freely configured and which can be used for sophisticated high-dynamic performance open-loop and closed-loop control functions. It is designed for use in a SIMATIC S7-400 station as a passive node which is connected to the SIMATIC backplane buses (P bus and K bus).

Applications include higher-level closed-loop drive controls for:

- Closed-loop tension control
- Closed-loop position control
- Winders and coilers
- Angular and synchronous controls
- Positioning
- Cross-cutters and flying saws
- Other closed-loop controls

Expansion modules

Designation	Order No.
Input/output expansion module EXM 438	6DD 1607-0CA0
Input/output expansion module EXM 438-1	6DD 1607-0CA1
Communications expansion module EXM 448	6DD 1607-0EA0

As the FM 458 is a passive node on the backplane bus, the S7-CPU module must read-in signals from the SIMATIC I/O, and send these to the FM 458. The FM can be supplemented by the following expansion modules for fast process coupling:

- The I/O expansion module EXM 438/EXM 438-1 provides additional digital and analog I/O as well as incremental and absolute value encoders.

- Communications via PROFIBUS-DP (master or slave) is realized using the EXM 448 communications expansion module. Optionally, MASTERDRIVES-plug-in modules, e.g. SLB for SIMOLINK, can increase their functionality.

A maximum of two expansion modules can be used together with the FM 458 application module. The following combinations are possible:

Application module	1st expansion module	2nd expansion module
FM 458	None	None
	EXM 438 or EXM 438-1	None
	EXM 448	None
	EXM 438 or EXM 438-1	EXM 438 or EXM 438-1
	EXM 448	EXM 448
	EXM 438 or EXM 438-1	EXM 448
	EXM 448	EXM 438 or EXM 438-1

Table 2-1 Possibilities of combining expansion modules

NOTE

When configuring the system, please note that the maximum load capability of the S7 power supply module may not be exceeded as a result of the current drawn by the FM 458 module.

When using an IM module, which is also used to transfer power to other modules, its maximum load capability must also be observed.

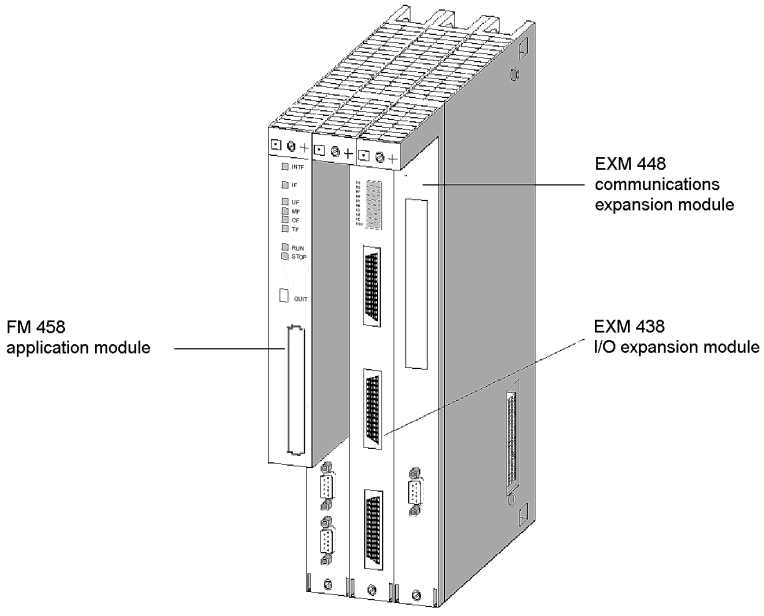


Fig. 2-1 View of the FM 458 application module with two expansion modules

Design

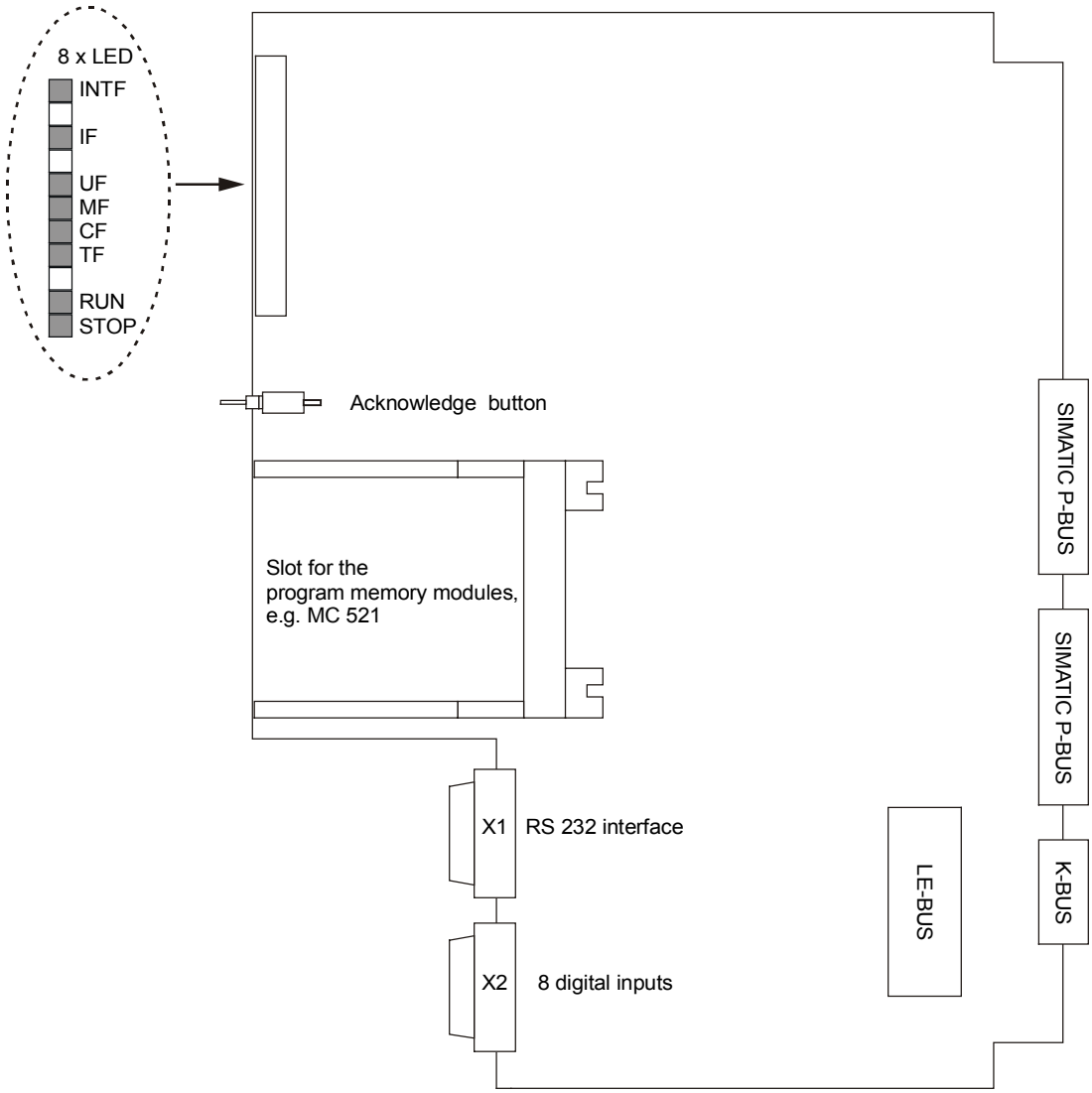


Fig. 2-2 Mechanical design of the FM 458 application module

2.1.2 Performance features

The FM 458 application module has the high-performance processor core of the PM6 SIMADYN D CPU module and has the following performance features:

- Computational performance
  - 128 MHz, 64 bit RISC floating-point-processor
  - fastest cycle times of 0.1 ms, typical 0.5 ms
- DRAM (8 MB)
  - Program code is loaded when the memory module is loaded and expanded when the memory module is initialized (boot flash is provided separately)
  - Data memory for the operating system, communications, message buffer, trace
- SRAM (256 KB)

  The buffered SRAM contains the following data, which should be saved (non-volatile) even when the power fails:
  - Error diagnostics of the operating system ("exception buffer")
  - max. 1000 process quantities, configured using the SAV function block
  - Data, traced using the message system or trace function (optional SRAM configuring)
- Replaceable program memories
  - MC 521 mit 2 MB Flash EPROM und 8 kByte EEPROM
  - MC 500 mit 4 MB Flash EPROM und 8 kByte EEPROM
- Two interfaces are available to load the user program into the program memory:
  - via a PCMCIA-IPC card slot (load offline)
  - directly from the PC via the serial service interface (loading online)
- 8 interrupt tasks can be called via 8 digital inputs.
- RS-232 interface (V.24) with service protocol DUST1 (19.2 kBd) for:
  - CFC test mode (incl. download)
  - "Service/IBS“/TELEMASTER [IBS = Start-up]
- 8 LEDs to display the operating status

- Acknowledge button
  Sporadically occurring faults (TF) or non-critical faults (MF) can be cancelled in the LED dispoay using the acknowledge button.
  If another fault/error exists, then it is displayed after the first has been acknowledged.

- LE bus

  The LE bus ensures fast data transfer between the FM 458 application module and its expansion modules EXM 438/EXM 438-1/EXM 448.

- P bus

  The peripheral (I/O) bus (P bus) is the parallel SIMATIC backplane bus which is designed for fast I/O signal transfer. Each SIMATIC subrack has a P bus.

2.1.3 Supplementary components

Components	Designation	Order No.
Program memory	MC 521	6DD1610-0AH3
Program memory	MC 500	6DD1610-0AH4
Cable for PC connection (9-pin/9-pin)	SC57	6DD1684-0FH0
Cable for digital inputs (9-pin/10-pin)	SC64	6DD1684-0GE0
Interface module	SU12	6DD1681-0AJ1
Interface module	SB10	6DD1681-0AE2
Interface module	SB60	6DD1681-0AF4
Interface module	SB61	6DD1681-0EB3

Table 2-2 Supplementary components for the FM 458 application module

2.1.4 Connections

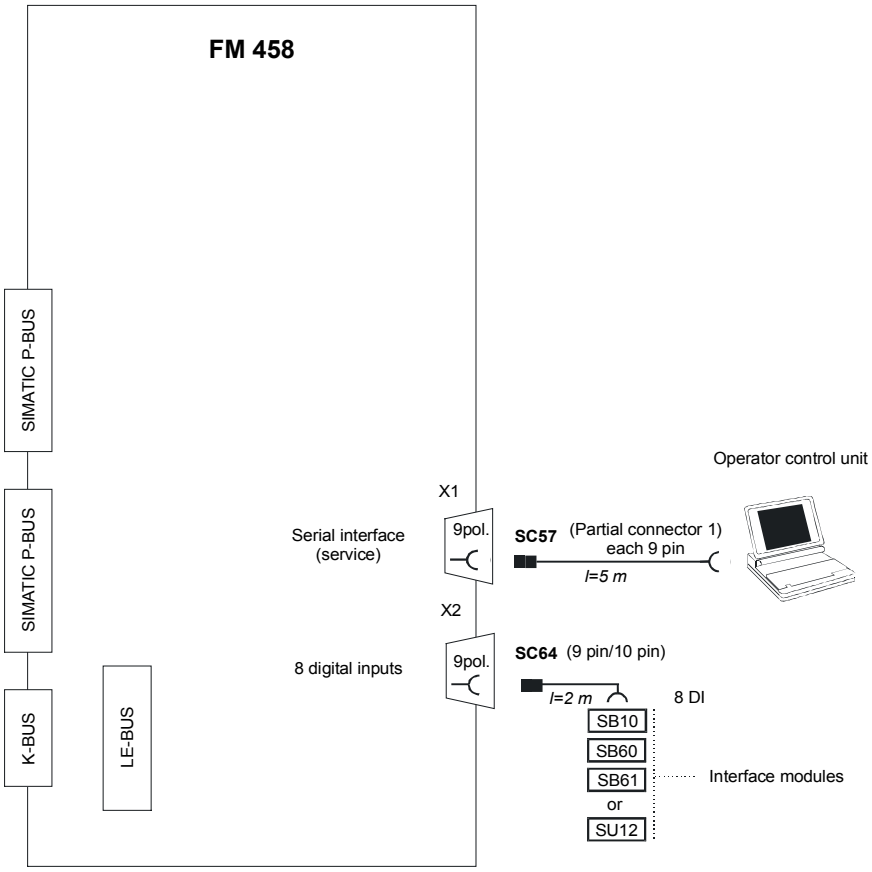
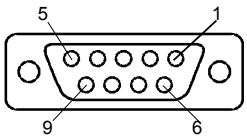


Fig. 2-3 Possibilities of connecting the FM 458 application module

Serial service interface (X1)

An operator control or configuring-PC is connected to the 9-pin sub-D socket via the SC57 PC cable.

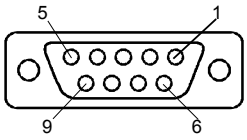


X1	
PIN	**Designation**
1	-
2	Receive Data In
3	Transmit Data Out
4	-
5	Ground 0V
6	-
7	Request to Send
8	Clear to Send
9	-

SC57	
PIN FM-side	**PIN** PC-side
-	-
2	3
3	2
-	-
5	5

Table 2-3 Connection assignment of X1 and SC57 cable

Digital inputs (X2)



The digital inputs are connected at the 9-pin sub-D socket via cable SC64.

PIN	Designation
1	Interrupt input 1
2	Interrupt input 3
3	Interrupt input 5
4	Interrupt input 7
5	Ground
6	Interrupt input 2
7	Interrupt input 4
8	Interrupt input 6
9	Interrupt input 8

Table 2-4 Connector assignment of X2

LE-bus connection

An expansion module (EXM 438/EXM 438-1 or EXM 448) can be inserted at this 5 x 24-pin socket connector.

P-bus connection

Two 5 x 17-pin socket connectors are used to connect to the SIMATIC S7 backplane bus.

K-bus connection

A 5 x 7-pin socket connector is provided for connection to the SIMATIC K bus.

Interface modules

The screw terminals for the digital inputs are available via the interface modules.

Interface modules	Function
SB10, SU12	Electrical 1:1 connection, no signal conversion
SB60, SB61	With electrical isolation and signal conversion

Refer to Catalog DA 99 for information on the interface modules.

2.1.5 Status displays

There are eight LED displays on the front panel of the FM 458. They provide information about its actual operating status and data for diagnostics.

LED	Color	Status	Significance
INTF	red	lit	**Internal error**, user program is not running
IF	red	lit	**Initialization error** For errors, which occur when initializing the system, the user program doesn't start. Initialization errors due to incorrect modules or modules which are incorrectly inserted with respect to how they were originally configured.
UF	yellow	lit	**User error** The user program runs, user-defined diagnostics event with the function block USF
MF	yellow	lit	**Monitoring error** User program runs, low-priority error during initialization which permits standard operation to start, e.g. missing or discharged buffer battery.
CF	yellow	lit	**Communications error** User program runs, erroneous configured communications or erroneous connection to SIMATIC S7 or EMX 448
TF	yellow	lit	**Task administration error** User program runs, the following error cases are possible: *Cycle error* a task was not able to be completed within the task sampling time. *Task back-up* If the task is not marked as a task to run with the highest priority, and it must be restarted. *No free local buffer* The data buffer is no longer enabled. Task start is bypassed. *Software Watchdog* if the basic sampling time is not processed four times one after the other. The basic clock cycle timer is re-initialized with the configured basic sampling time and processing continued.
RUN	green	lit	**RUN condition** User program runs, the module operates normally also if UF, MF, CF or TF = "lit“
		flashing	Initialization running
STOP	yellow	lit	**STOP status** User program is not running, module is in the stop condition, e.g. or fatal system-, initialization errors or the S7-CPU is in the stop condition.
		flashing	Download running in the STOP condition (is faster than the download in the run condition, which runs in the background)

Table 2-5 Significance of the LED status displays

Errors can be acknowledged by pressing the acknowledge button. If an additional error exists, it is displayed after the first error has been acknowledged.

More information on EMC and environment/ambient conditions, refer to the SIMADYN D Hardware Manual, Section "General Technical Data“ or the appropriate SIMATIC S7 documentation!

2.1.6 Technical data

Order No.

Application module FM 458	6DD1607-0AA0

Digital inputs

Number	8
Electrical isolation	No
Input voltage • Permissible range • Nominal voltage • For a 0 signal • For a 1 signal	 -1 V to +33 V 24 V -1 V to + 6 V +13,5 V to +33 V
Input current • For a 0 signal, typ. • For a 1 signal, typ.	 0 mA 3 mA
Delay time per channel, max	100 µs

Voltages, currents

Rated voltage	+5 V	3,4 V battery
Typical current drain	1,8 A	10 µA

Dimensions

Assignment, slots	1
Dimensions W x H x D [mm]	25 x 290 x 210
Weight	0,92 kg

2.2 I/O expansion module EXM 438

Designation	Order No.
I/O expansion module EXM 438	6DD1607-0CA0

2.2.1 Application and design

Application

The EXM 438 expansion module provides additional digital and analog I/O as well as incremental- and absolute value encoders. Fast data transfer with the FM 458 application module is realized via the internal LE bus. The power supply is obtained via the P bus of SIMATIC S7-400. It is not possible to directly transfer process data via the P bus.

Design

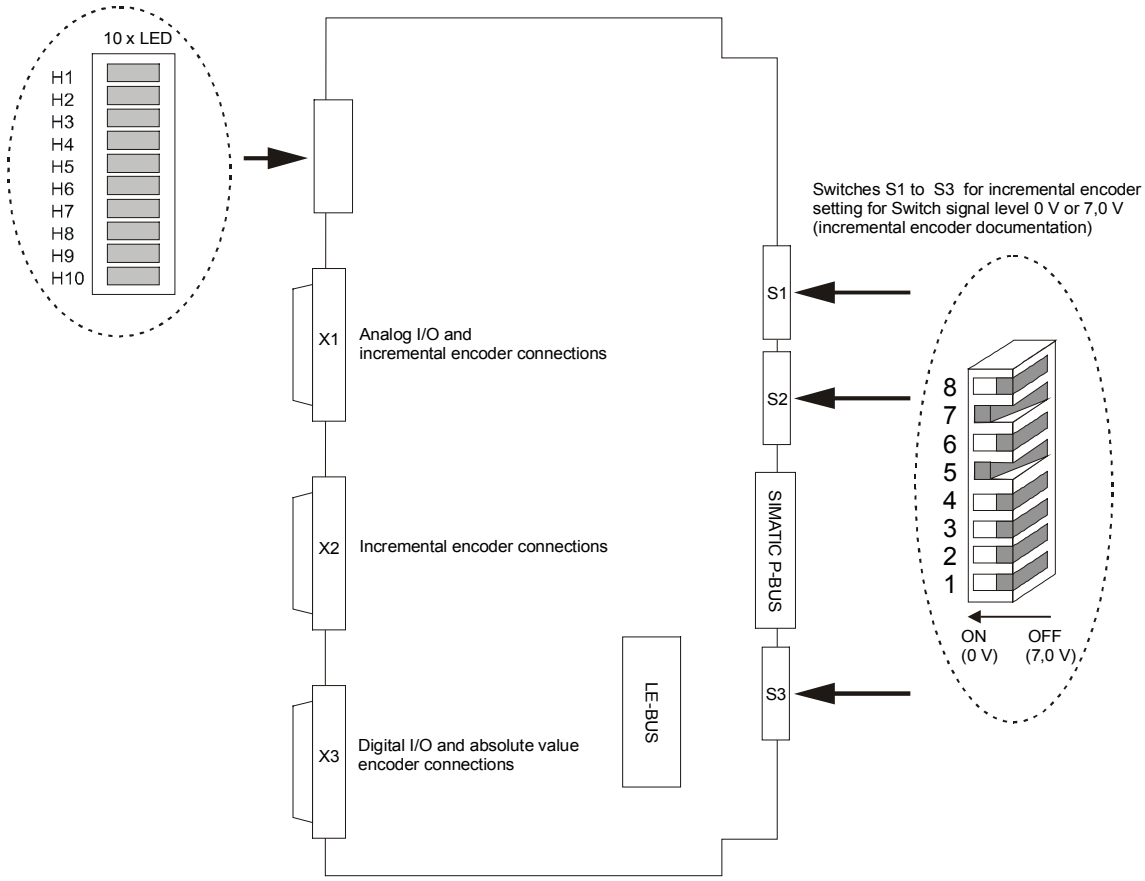


Fig. 2-4 Mechanical design of the I/O EXM 438 expansion module

2.2.2 Performance features

- 8 incremental encoders:
- 4 absolute value encoders (SSI or EnDat)
- 5 analog inputs
- 8 analog outputs (12 Bit)
- 16 digital inputs, 24 V
- 8 digital outputs, 24 V
- 8 LEDs which the user can configure as required

  LED displays H1 to H8, when required, can be controlled using function block BIQ8 (digital output).
  LEDs H9 and H10 have no function.

- LE bus

  The LE bus ensures fast data transfer between the FM 458 application module and its expansion modules EXM 438/EXM 438-1/EXM 448.

- P bus

  The peripheral bus (P bus) is the parallel SIMATIC backplane bus, which only provides the power supply for the EXM 438.

2.2.3 Supplementary components

Interface modules

All of the I/O signal cables are not directly connected to the module, but via interface modules. The interface modules are used as mechanical connecting elements (screw terminals) as well as to electrically adapt the plant/system signals and convert them (optional).

Components	Designation	Order No.
Interface module, electrical 1:1 connection	SU12	6DD1681-0AJ1
Interface module, electrical 1:1 connection	SU13	6DD1681-0GK0
Interface module, electrical 1:1 connection	SB10	6DD1681-0AE2
Interface module with electrical isolation and signal conversion	SB60	6DD1681-0AF4
Interface module with electrical isolation and signal conversion	SB61	6DD1681-0EB3
Interface module with electrical isolation and signal conversion	SB70	6DD1681-0AG2
Interface module with electrical isolation and signal conversion	SB71	6DD1681-0DH1

Table 2-6 Interface modules for the I/O expansion module EXM 438

Cables

The module is connected to the interface modules via the appropriate plug-in cables. Plug-in cable SC62 has five cable ends which can be connected to the appropriate number of suitable interface modules.

Components	Designation	Order No.
Connecting cable, 50-pin/5*10-pin	SC62	6DD1684-0GC0
Connecting cable, 50-pin/50-pin	SC63	6DD1684-0GD0

Table 2-7 Cables for the input/output expansion module EXM 438

2.2.4 Connection possibilities

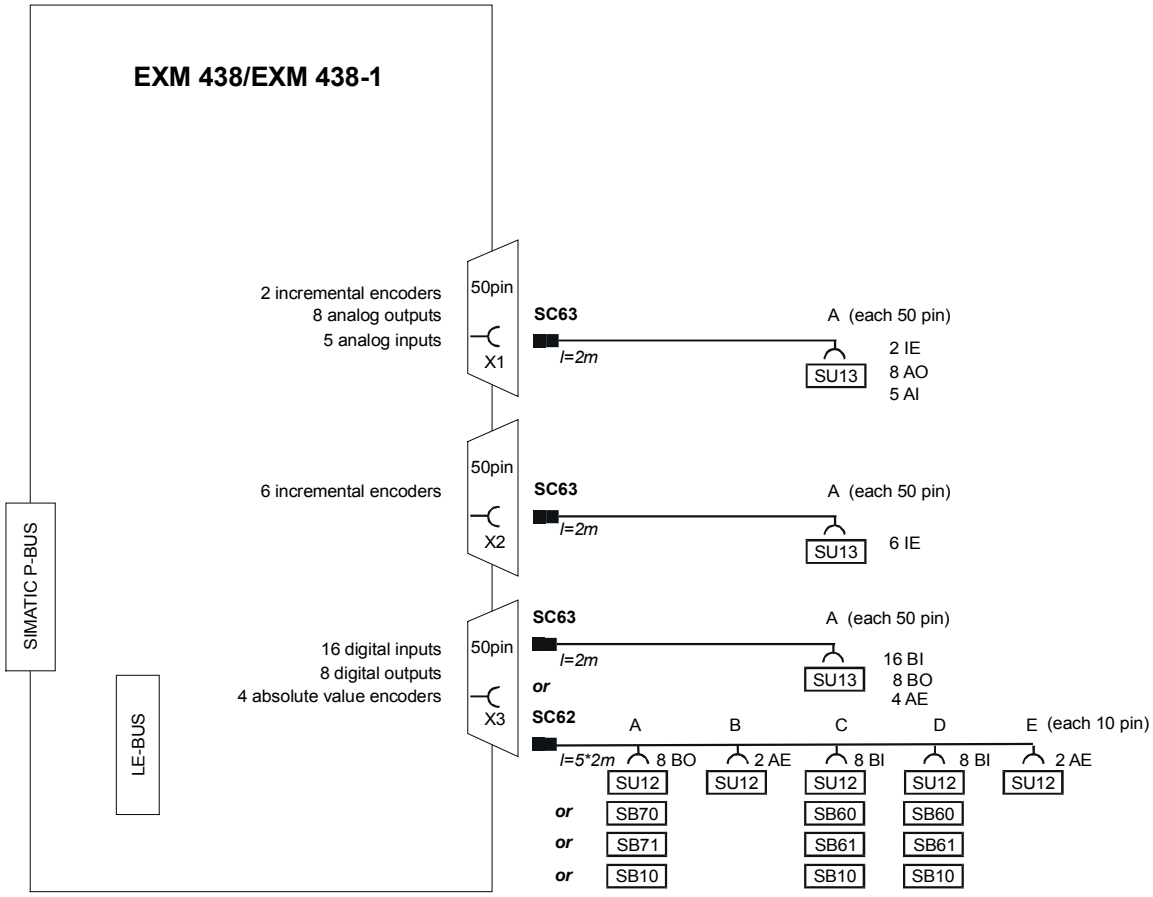


Fig. 2-5 Connection possibilities of the input/output expansion module EXM 438/EXM 438-1

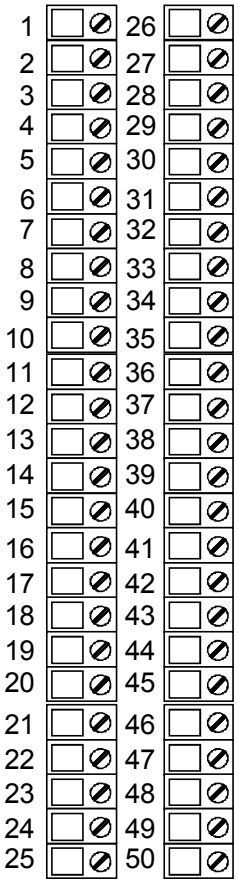
LE-bus connection An additional expansion module (EXM 438/438-1 or EXM 448) can be inserted at this 5 x 24 pin socket connector.

P-bus connection The 5 x 17 pin socket connector is used to connect to the SIMATIC S7 backplane (only power supply).

Connecting X1 with cable SC63

The analog inputs and outputs and a part of incremental encoders are available at the screw terminals of the SU13 interface module, which is connected via cable SC63 (1:1 connection).

The screw terminal assignment at interface module SU13 corresponds to the connector assignment of X1.



Screw terminals on SU13

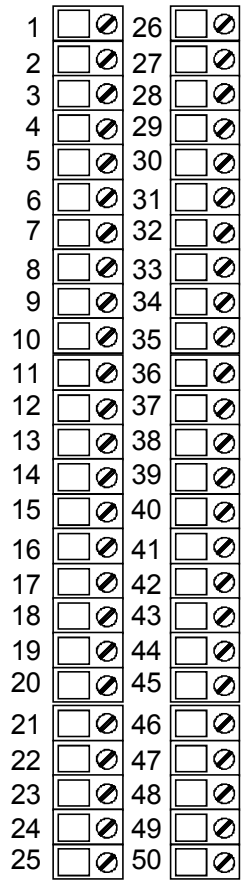
PIN	Significance	PIN	Significance
1	Incremental encoder 7 track A+	26	Incremental encoder 8 track A+
2	Incremental encoder 7 track A-	27	Incremental encoder 8 track A-
3	Incremental encoder 7 track B+	28	Incremental encoder 8 track B+
4	Incremental encoder 7 track B-	29	Incremental encoder 8 track B-
5	Incremental encoder 7 track N+	30	Incremental encoder 8 track N+
6	Incremental encoder 7 track N-	31	Incremental encoder 8 track N-
7	Ground, encoder	32	Ground, encoder
8	Monitoring input 7	33	Monitoring input 8
9	-	34	-
10	Ground, encoder	35	Ground, encoder
11	Analog output 1+	36	Analog output 5+
12	Analog output 1 -	37	Analog output 5 -
13	Analog output 2+	38	Analog output 6+
14	Analog output 2 -	39	Analog output 6 -
15	Analog output 3+	40	Analog output 7+
16	Analog output 3 -	41	Analog output 7 -
17	Analog output 4+	42	Analog output 8+
18	Analog output 4 -	43	Analog output 8 -
19	Analog input 5 +	44	Analog intput 5 -
20	Ground, AD converter	45	Ground, DA converter
21	Analog input 1 +	46	Analog input 3+
22	Analog input 1 -	47	Analog input 3-
23	Analog input 2+	48	Analog input 4 +
24	Analog input 2 -	49	Analog input 4 -
25	Ground DA converter	50	Ground AD converter

Table 2-8 Connector assignment of X1

Connecting X2 with cable SC63

The incremental encoders are available at the screw terminals of interface module SU13, which is connected via cable SC63 (1:1 connection).

The screw terminal assignment at interface module SU13 corresponds to the connector assignment of X2.



Screw terminals at SU13

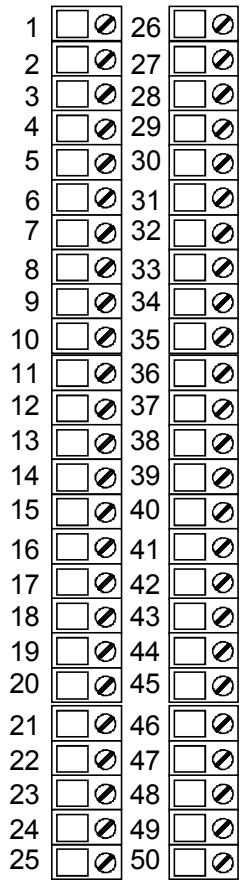
PIN	Significance	PIN	Significance
1	Increm. encoder 1 track A+	26	Increm. encoder 2 track A+
2	Increm. encoder 1 track A-	27	Increm. encoder 2 track A-
3	Increm. encoder 1 track B+	28	Increm. encoder 2 track B+
4	Increm. encoder 1 track B-	29	Increm. encoder 2 track B-
5	Increm. encoder 1 track N+	30	Increm. encoder 2 track N+
6	Increm. encoder 1 track N-	31	Increm. encoder 2 track N-
7	Increm. encoder 3 track A+	32	Increm. encoder 3 track B-
8	Increm. encoder 3 track A-	33	Increm. encoder 3 track N+
9	Increm. encoder 3 track B+	34	Increm. encoder 3 track N-
10	Ground, encoder	35	Ground, encoder
11	Increm. encoder 4 track A+	36	Increm. encoder 5 track A+
12	Increm. encoder 4 track A-	37	Increm. encoder 5 track A-
13	Increm. encoder 4 track B+	38	Increm. encoder 5 track B+
14	Increm. encoder 4 track B-	39	Increm. encoder 5 track B-
15	Increm. encoder 4 track N+	40	Increm. encoder 5 track N+
16	Increm. encoder 4 track N-	41	Increm. encoder 5 track N-
17	Increm. encoder 6 track A+	42	Increm. encoder 6 track B-
18	Increm. encoder 6 track A-	43	Increm. encoder 6 track N+
19	Increm. encoder 6 track B+	44	Increm. encoder 6 track N-
20	Ground, encoder	45	Ground, encoder
21	Monitoring input 1	46	Monitoring input 4
22	Monitoring input 2	47	Monitoring input 5
23	Monitoring input 3	48	Monitoring input 6
24	Ground, encoder	49	Ground, encoder
25	Ground, encoder	50	15 V encoder power supply

Table 2-9 Connector assignment of X2

Connecting X3 with cable SC63

The digital inputs and outputs and the absolute value encoder are available at the screw terminals of interface module SU13, which is connected via cable SC63 (1:1 connection).

The screw terminal assignment at interface module SU13 corresponds to the connector assignment of X3.



Screw terminals at SU13

PIN	Significance	PIN	Significance
1	Digital output 1	26	Digital input 1
2	Digital output 2	27	Digital input 2
3	Digital output 3	28	Digital input 3
4	Digital output 4	29	Digital input 4
5	Digital output 5	30	Digital input 5
6	Digital output 6	31	Digital input 6
7	Digital output 7	32	Digital input 7
8	Digital output 8	33	Digital input 8
9	Ext. +24V power supply	34	-
10	Ground, external	35	Ground, external
11	Abs. value encoder 1 data D+	36	Digital input 9
12	Abs. value encoder 1 data D-	37	Digital input 10
13	Abs. value encoder 1 clock cycle C+	38	Digital input 11
14	Abs. value encoder 1 clock cycle C-	39	Digital input 12
15	Ground, encoder SSI	40	Digital input 13
16	Abs. value encoder 2 data D+	41	Digital input 14
17	Abs. value encoder 2 data D-	42	Digital input 15
18	Abs. value encoder 2 clock cycle C+	43	Digital input 16
19	Abs. value encoder 2 clock cycle C-	44	-
20	Ground, encoder SSI	45	Ground, external
21	Abs. value encoder 3 data D+	46	Abs. value encoder 4 data D+
22	Abs. value encoder 3 data D-	47	Abs. value encoder 4 data D-
23	Abs. value encoder 3 clock cycle C+	48	Abs. value encoder 4 clock cycle C+
24	Abs. value encoder 3 clock cycle C-	49	Abs. value encoder 4 clock cycle C-
25	Ground, encoder SSI	50	Ground, encoder SSI

Table 2-10 Connector assignment of X3

Connecting X3 with cable SC62

Depending on the required function (signal conversion, LED display), different interface modules (max. 5) can be connected to the digital inputs and outputs as well as the absolute value encoder. For this particular case, cable SC62 must be used. This cable has five cable ends, which can be used to connect an appropriate number of interface modules. The following interface modules can be used:

Designation	Function
SB10	Direct connection (1:1 connection) of 8 digital I/O, LED, no signal conversion
SB60	8 digital inputs, conversion, 230V to 24V (signal level of the module), LED, electrical isolation
SB61	8 digital inputs, conversion 48V to 24V, LED, electrical isolation
SB70	8 digital outputs, conversion 24V to 230V (AC relay), LED, electrical isolation
SB71	8 digital outputs, conversion 25V to 48V (transistor)
SU12	10 signals can be directly connected, no signal conversion

Table 2-11 Interface modules which can be connected to X3 using SC62

Only specific signal types are available at the particular cable ends which can be used for the matching interface modules:

Module type	Terminal[1)]	Significance
SB10	x 5x	1:1 connection • Signal • Reference potential (Ground or P24)
SB60	x1 x2 x4	Digital inputs 115/230 V • Ground • 115 V digital input • 230 V digital input
SB61	x 1x 5x	Digital inputs 24/48 V • 24 V digital input • 48 V digital input • Reference
SB70	x1 x2 x4	Digital outputs (relay) • Common (center contact) • NC contact • NO contact
SB71	x 5x	Digital outputs (transistor) • Signal • Ground
SU12	x 9 10	1:1 connection • Signal • 24 V (for digital output) • Reference

[1)]Screw terminals X = 1 ... 8

Table 2-12 Terminal assignment of the interface modules

Terminal assignment at cable SC62, end A

X3	Designation	SU12	SB10	SB70	SB71
1	Digital output 1	1	1/51	12/11/14	1/51
2	Digital output 2	2	2/52	22/21/24	2/52
3	Digital output 3	3	3/53	32/31/34	3/53
4	Digital output 4	4	4/54	42/41/44	4/54
5	Digital output 5	5	5/55	52/51/54	5/55
6	Digital output 6	6	6/56	62/61/64	6/56
7	Digital output 7	7	7/57	72/71/74	7/57
8	Digital output 8	8	8/58	81/82/84	8/58
9	Ext.. +24V power supply	9	1P	1P	1P
10	Ground, external	10	1M	1M	1M

Table 2-13 Terminal assignments of the interface module at connector X3, SC62 cable end A

Terminal assignment at cable SC62, end B

X3	Designation	SU12
11	Abs. value encoder 1 data D+	1
12	Abs. value encoder 1 data D-	2
13	Abs. value encoder 1 clock cycle C+	3
14	Abs. value encoder 1 clock cycle C-	4
15	Ground, encoder SSI	5
16	Abs. value encoder 2 data D+	6
17	Abs. value encoder 2 data D-	7
18	Abs. value encoder 2 clock cycle C+	8
19	Abs. value encoder 2 clock cycle C-	9
20	Ground, encoder SSI	10

Table 2-14 Terminal assignments of interface module at connector X3, SC62 cable end B

Terminal assignment at cable SC62, end C

X3	Designation	SU12	SB10	SB60	SB61
26	Digital input 1	1	1/51	14,12/11	1,11/51
27	Digital input 2	2	2/52	24,22/21	2,12/52
28	Digital input 3	3	3/53	34,32/31	3,13/53
29	Digital input 4	4	4/54	44,42/41	4,14/54
30	Digital input 5	5	5/55	54,52/51	5,15/55
31	Digital input 6	6	6/56	64,62/61	6,16/56
32	Digital input 7	7	7/57	74,72/71	7,17/57
33	Digital input 8	8	8/58	84,82/81	8,18/58
34	-	9	1P	1P	1P
35	Ground, external	10	1M	1M	1M

Table 2-15 Terminal assignments of the interface module at connection X3, SC62 cable end C

Terminal assignment at cable SC62, end D

X3	Designation	SU12	SB10	SB60	SB61
36	Digital input 9	1	1/51	14,12/11	1,11/51
37	Digital input 10	2	2/52	24,22/21	2,12/52
38	Digital input 11	3	3/53	34,32/31	3,13/53
39	Digital input 12	4	4/54	44,42/41	4,14/54
40	Digital input 13	5	5/55	54,52/51	5,15/55
41	Digital input 14	6	6/56	64,62/61	6,16/56
42	Digital input 15	7	7/57	74,72/71	7,17/57
43	Digital input 16	8	8/58	84,82/81	8,18/58
44	-	9	1P	1P	1P
45	Ground, external	10	1M	1M	1M

Table 2-16 Terminal assignments of the interface module at connector X3, SC62 cable end D

Terminal assignment at cable SC62, end E

X3	Designation	SU12
21	Abs. value encoder 3 data D+	1
22	Abs. value encoder 3 data D-	2
23	Abs. val. encoder 3 clock cycle C+	3
24	Abs. val. encoder 3 clock cycle C-	4
25	Ground, encoder SSI	5
46	Abs. value encoder 4 data D+	6
47	Abs. value encoder 4 data D-	7
48	Abs. val. encoder 4 clock cycle C+	8
49	Abs. val.encoder 4 clock cycle C-	9
50	Ground, encoder SSI	10

Table 2-17 Terminal assignments of the interface module at connector X3, SC62 cable end E

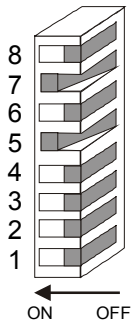
You will find additional information on the interface modules in Catalog DA 99.

2.2.5 Incremental encoder settings

Switches S1, S2 and S3 are used to toggle between 15V- and 5V-encoders. Each track (A/VW, B/RW, N/-) of a channel has a switch, which can be used to set the appropriate encoder type:

- Switch open (OFF): 15 V encoder: Switching threshold = 7 V
- Switch closed (ON): 5 V encoder: Switching threshold = 0 V

Switch S1 to S3



		15 V encoders		5 V encoders	
Encoder		**Switch**		**Switch**	
Channel	**Track**	**Numbr**	**Position**	**Numbr**	**Position**
Encoder 1	A / VW	S1, 1	OFF	S1, 1	ON
	B / RW	S2, 1	OFF	S2, 1	ON
	N / -	S3, 1	OFF	S3, 1	ON
Encoder 2	A / VW	S1, 2	OFF	S1, 2	ON
	B / RW	S2, 2	OFF	S2, 2	ON
	N / -	S3, 2	OFF	S3, 2	ON
Encoder 3	A / VW	S1, 3	OFF	S1, 3	ON
	B / RW	S2, 3	OFF	S2, 3	ON
	N / -	S3, 3	OFF	S3, 3	ON
Encoder 4	A / VW	S1, 4	OFF	S1, 4	ON
	B / RW	S2, 4	OFF	S2, 4	ON
	N / -	S3, 4	OFF	S3, 4	ON
Encoder 5	A / VW	S1, 5	OFF	S1, 5	ON
	B / RW	S2, 5	OFF	S2, 5	ON
	N / -	S3, 5	OFF	S3, 5	ON
Encoder 6	A / VW	S1, 6	OFF	S1, 6	ON
	B / RW	S2, 6	OFF	S2, 6	ON
	N / -	S3, 6	OFF	S3, 6	ON
Encoder 7	A / VW	S1, 7	OFF	S1, 7	ON
	B / RW	S2, 7	OFF	S2, 7	ON
	N / -	S3, 7	OFF	S3, 7	ON
Encoder 8	A / VW	S1, 8	OFF	S1, 8	ON
	B / RW	S2, 8	OFF	S2, 8	ON
	N / -	S3, 8	OFF	S3, 8	ON

Table 2-18 Switch settings for 5 V- and 15 V encoders

NOTE All of the tracks (A / VW, B / RW, N / -) of a channel must have the same switch position when operational!

2.2.6 Technical data

Order No.

/O expansion module EXM 438	6DD 1607 0CA0

Analog outputs

Number	8
Version	
Electrical isolation	No
Output voltage range	- 10 V to + 10 V
Output current	± 10 mA
Resolution	12 bit
Conversion time per channel, typ.	4 µs
Accuracy • Integral linearity error, max. • Gain error, max. • Offset error, max.	 ± 1 LSB ± 0.3 % ± 24 mV
Slew rate	approx. 3.5 V/µs
Voltage output • Short-circuit protection • Short-circuit current	 Yes (with respect to ground) approx. 100 mA

Analog inputs

Number	5
Version	Differential inputs
Electrical isolation	No
Input voltage range	- 10 V to + 10 V
Resolution	12 bit
Conversion time per channel, max	approx.10 µs – 100ksps sampling rate
Accuracy • Integral linearity error, max. • Gain error, max. • Offset error, max.	 ± 1/2 LSB ± 0.3 % ± 10 LSB
Input resistance	20 kΩ
Input filter	34 kHz
Incorrect polarity protection	No

Digital outputs

Number	8
Electrical isolation	No
External power supply • Nominal voltage • Permissible range • Briefly • Max. current drain, without load	 24 V 20 V to 30 V 35 V (for max. 0.5 sec.) 20 mA
Output voltage range • For a 0 signal, max. • For a 1 signal, min.	 3 V ext. power supply voltage, – 2.5 V

Output current
• For a 0 signal, min.
• For a 1 signal
  • Nominal value
  • Permissible range, max.
	
	-20 µA
	
	50 mA
	100 mA

Delay time	100 µs
Switching frequency of the outputs for ohmic load, max.	6 kHz
Short-circuit protection with respect to • Ground • External power supply	 Yes No
Short-circuit current, max.	250 mA
Total currents of the outputs (up to 60 °C)	8 x 50 mA
Limiting inductive switch-off voltages	ext. power supply voltage +1 V

Digital inputs

Number	16
Electrical isolation	No
Input voltage • Permissible range • Nominal voltage • For a 0 signal • For a 1 signal	 -1 V to +33 V 24 V -1 V to + 6 V +13.5 V to +33 V
Input current • For a 0 signal, typ. • For a 1 signal, typ.	 0 mA 3 mA
Delay time per channel, max	100 µs

Incremental encoders

The encoder types, corresponding to the technical data can be freely connected to the incremental encoder inputs.

Number	8	
Types which can be connected		
Version	Differential inputs, either 15V or 5V encoder signals can be selected	Differential inputs, either 15V or 5V encoder signals can be selected
Track signals	Tracks A, B displaced through 90° and with zero pulse	Forwards, reverse track
Phase difference of the track signals, min.	200 ns	200 ns
Pulse frequency, max.	1 MHz	2.5 MHz
Noise pulse suppression	Can be configured	Can be configured
Electrical isolation	No	No

Input voltage
• 15 V encoder:
  • Permissible range
  • For a 0 signal
  • For a 1 signal
• 5 V encoder
  • Permissible range
  • For a 0 signal
  • For a 1 signal
	
	-30 V to +30 V
	-30 V to +4 V
	+8V to +30 V
	
	-7 V to + 7 V
	-7 V to -0.7 V
	+1.5 V to +7 V
		
		-30 V to +30 V
		-30 V to +4 V
		+8V to +30 V
		
		-7 V to + 7 V
		-7 V to -0.7 V
		+1.5 V to +7 V

Input current • 15 V encoder (typ., abs.) • 5 V encoder (typ., abs.)	5 mA 1.5 mA	5 mA 1.5 mA

Monitoring output (alarm reset output not available)
• Short-circuit protection with respect to
  • Ground
  • External power supply
• Short-circuit current, max.
	Not available	Not available

Monitoring inputs, Input voltage • Permissible range • Nominal voltage • 0 signal, max. • 1 signal, min.	 -1 V to 33V 24 V -1 V to +6 V +13.5 V to +33 V	
Monitoring input, Input current • 0 signal, min. • 1 signal, min.	 0 mA 3 mA	

Absolute value encoders

Number	4
Version	Differential inputs, RS485 signal level
Types which can be connected	
Protocols	SSI, EnDat
Data formats	Gray, binary
Data direction • Uni-directional • Bi-directional	 SSI : uni-directional EnDat : bi-directional
Data bits	SSI: 13 + parity, 25 + parity EnDat: variable
Pulse frequency, max.	2 MHz
Electrical isolation	No
Input voltage	RS485 signal level

Power supply voltage for the encoders

Version	
Output voltage, typ.	13.5 V
Output current, max.	150 mA (short-circuit proof, short-current, approx. 250 mA)

Voltage, currents

Rated voltages at 25° C	Typical current drain
+5 V	2.8 A

Power loss/ fan

Power loss, typ.	14.0 W
Fan required	Yes

Dimensions

Number of slots required in the subrack	1
Dimensions W x H x D [mm]	24 x 290 x 210
Weight, approx.	0.76 kg

2.3 I/O expansion module EXM 438-1

Designation	Order No.
I/O expansion module EXM 438-1	6DD1607-0CA1

2.3.1 Application and design

Application

The EXM 438-1 expansion module provides additional digital and analog I/O as well as incremental- and absolute value encoders. Fast data transfer with the FM 458 application module is realized via the internal LE bus. The power supply is obtained via the P bus of SIMATIC S7-400. It is not possible to directly transfer process data via the P bus.

Design

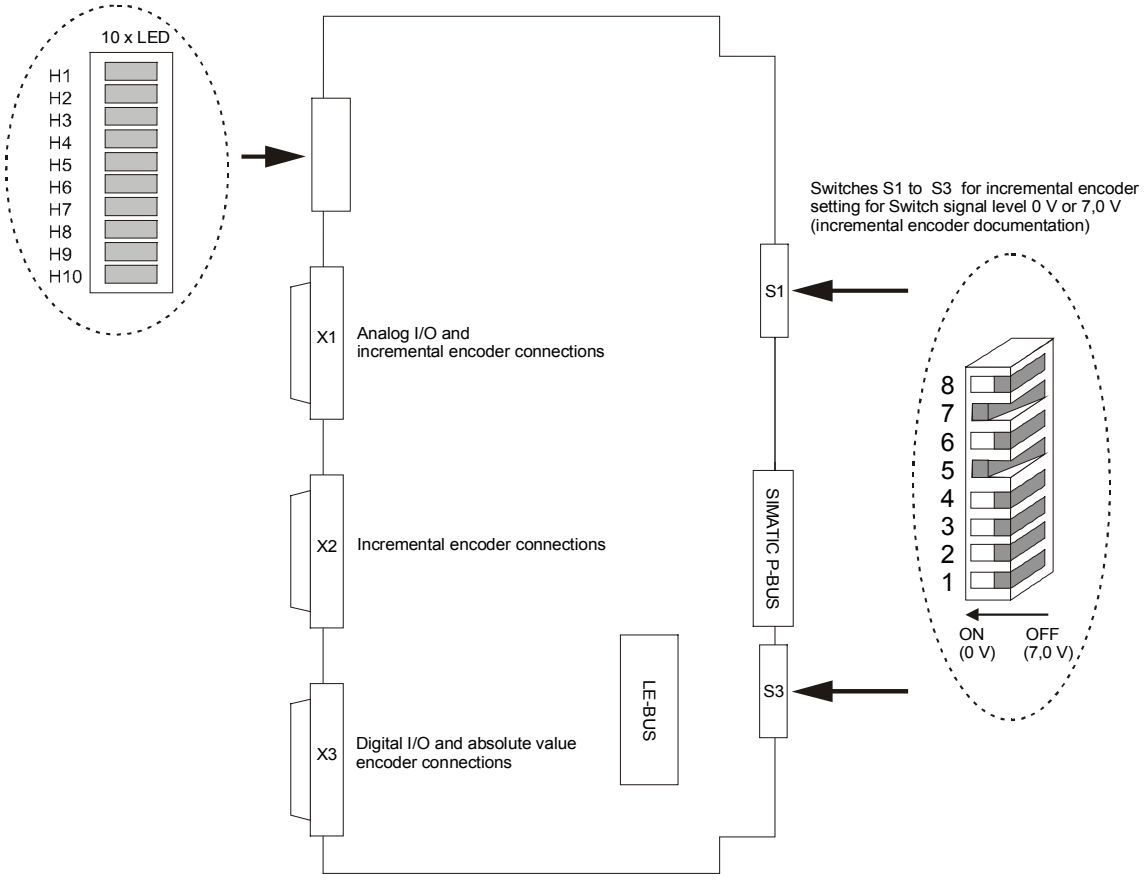


Fig. 2-6 Mechanical design of the I/O EXM 438 expansion module

2.3.2 Performance features

- 8 incremental encoders:
- 4 absolute value encoders (SSI or EnDat)
- 5 analog inputs
- 4 analog outputs 12 Bit (analog outputs 5 - 8)
- 4 analog outputs 16 Bit (analog outputs 1 - 4)
- 16 digital inputs, 24 V
- 8 digital outputs, 24 V
- Fanless operation up to 40° C air intake temperature (ambient temperature) possible.
- 8 LEDs which the user can configure as required

  LED displays H1 to H8, when required, can be controlled using function block BIQ8 (digital output).
  LEDs H9 and H10 have no function.
- LE bus

  The LE bus ensures fast data transfer between the FM 458 application module and its expansion modules EXM 438/EXM 438-1/EXM 448.
- P bus

  The peripheral bus (P bus) is the parallel SIMATIC backplane bus, which only provides the power supply for the EXM 438-1.

2.3.3 Supplementary components

NOTE The supplementary components are identical with those of the I/O expansion module EXM 438 (refer to Section 2.2.3).

2.3.4 Connection possibilities

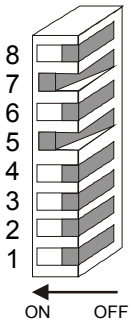
NOTE The connection possibilities are identical with those of the I/O expansion module EXM 438 (refer to Section 2.2.4).

2.3.5 Incremental encoder settings

Switches S1 and S3 are used to change over between 15V and 5V encoders. Tracks A/VW and B/RW have a common switch, track N/- of a channel has its own switch, which can be used to set the appropriate encoder type:

- Switch open (OFF): 15 V encoder: Switching threshold = 7 V
- Switch closed (ON): 5 V encoder: Switching threshold = 0 V

Switch S1 and S3



		15 V encoders		5 V encoders	
Encoder		Switch		Switch	
Channel	Track	Numbr	Position	Numbr	Position
Encoder 1	A / VW B / RW	S1, 1	OFF	S1, 1	ON
	N / -	S3, 1	OFF	S3, 1	ON
Encoder 2	A / VW B / RW	S1, 2	OFF	S1, 2	ON
	N / -	S3, 2	OFF	S3, 2	ON
Encoder 3	A / VW B / RW	S1, 3	OFF	S1, 3	ON
	N / -	S3, 3	OFF	S3, 3	ON
Encoder 4	A / VW B / RW	S1, 4	OFF	S1, 4	ON
	N / -	S3, 4	OFF	S3, 4	ON
Encoder 5	A / VW B / RW	S1, 5	OFF	S1, 5	ON
	N / -	S3, 5	OFF	S3, 5	ON
Encoder 6	A / VW B / RW	S1, 6	OFF	S1, 6	ON
	N / -	S3, 6	OFF	S3, 6	ON
Encoder 7	A / VW B / RW	S1, 7	OFF	S1, 7	ON
	N / -	S3, 7	OFF	S3, 7	ON
Encoder 8	A / VW B / RW	S1, 8	OFF	S1, 8	ON
	N / -	S3, 8	OFF	S3, 8	ON

Table 2-19 Switch settings for 5 V- and 15 V encoders

2.3.6 Technical data

Order No.

/O expansion module EXM 438-1	6DD1607 0CA1

Analog outputs

Number	4
Version	
Electrical isolation	No
Output voltage range	- 10 V to + 10 V
Output current	± 10 mA
Resolution	12 bit
Conversion time per channel, typ.	4 µs
Accuracy • Integral linearity error, max. • Gain error, max. • Offset error, max.	 ± 1 LSB ± 0,3 % ± 24 mV
Slew rate	approx. 3,5 V/µs
Voltage output • Short-circuit protection • Short-circuit current	 Yes (with respect to ground) approx. 100 mA

Number	4
Version	
Electrical isolation	No
Output voltage range	- 10 V to + 10 V
Output current	± 10 mA
Resolution	16 bit
Conversion time per channel, typ.	2 µs
Accuracy • Integral linearity error, max. • Gain error, max. • Offset error, max.	 ± 1 LSB ± 0,1 % ± 1 mV
Slew rate	approx. 0,7 V/µs
Voltage output • Short-circuit protection • Short-circuit current	 Yes (with respect to ground) approx. 27 mA for a chanel

Voltage, currents

Rated voltages at 25° C	Typical current drain
+5 V	1,5 A

Power loss/ fan

Power loss, typ.	7,5 W
Fan required	Fanless operation up to 40° C (ambient temperature) possible.

NOTE All other technical data are identical with those of the input/output expansion module EXM 438 (refer to Section 2.2.6).

2.4 Communications expansion module EXM 448

Designation	Order No.
Communications expansion module EXM 448	6DD1607-0EA0

2.4.1 Application and design

Application

The EXM 448 expansion module is used as communications module for PROFIBUS-DP in the master- or slave function.

Design

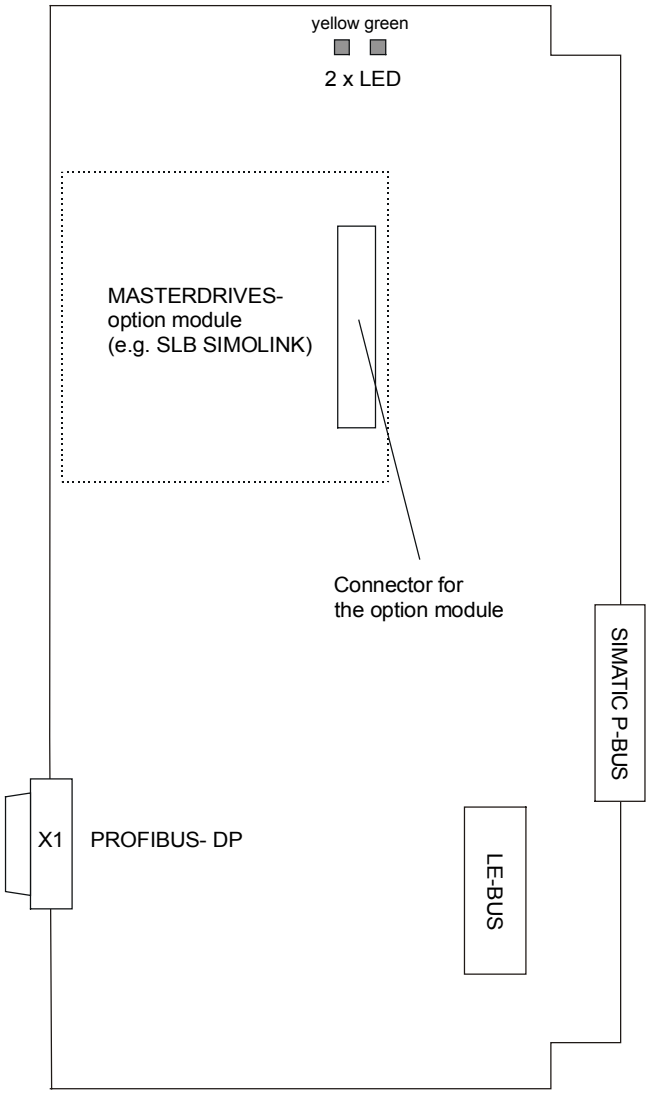


Fig. 2-7 Mechanical design of the communications expansion module EXM 448

2.4.2 Performance features

- Master- or slave interface for PROFIBUS-DP
  incl. the functions "Shared Input“, SYNC, FREEZE
- Data transfer rates from 9.6 kbit/s to 12 Mbit/s
- Max. 127 slaves can be connected (dependent on the configuration)
- Telegram length of max.. 244 bytes per slave
- RS 485 interface for PROFIBUS-DP, floating
- RS 232 interface to parameterize the bus node
- Two displays (LED) to indicate the operating status of the communications interface and the bus activity
- Optionally, additional functions can be implemented using plug-on modules, e.g. SLB for SIMOLINK:
  - SIMOLINK with master function to control up to 200 MASTERDRIVES
  - SIMOLINK with slave function for establishing a fast coupling to SIMADYN D or several FM 458
- DP master with COM PROFIBUS
- LE bus

  The LE bus ensures fast data transfer between the FM 458 application module and its expansion modules EXM 438/EXM 438-1/EXM 448.
- P bus

  The peripheral bus (P bus) is the parallel SIMATIC backplane bus, which only provides the power supply for the EXM 448.

2.4.3 Supplementary components

- Plug-in option module

Designation	Order No.
SLB SIMOLINK	6SE7090-0XX84-0FJ0
Additional modules are being prepared!	

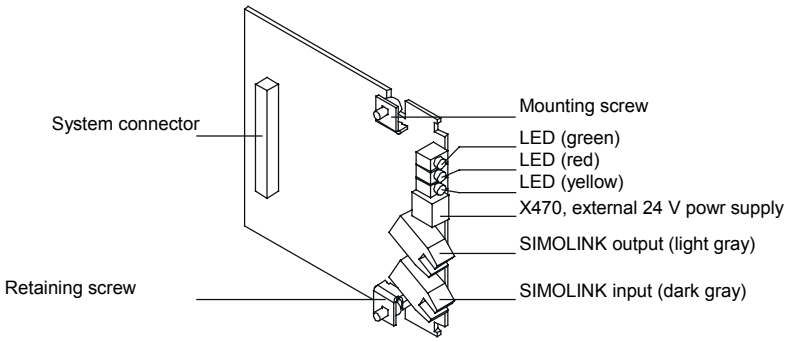


Fig. 2-8 View of the SLB SIMOLINK option module

2.4.4 Installing the option module

Mounting the option module

1. Remove the righthand housing cover on the side of the EXM 448, by releasing the retaining screws.

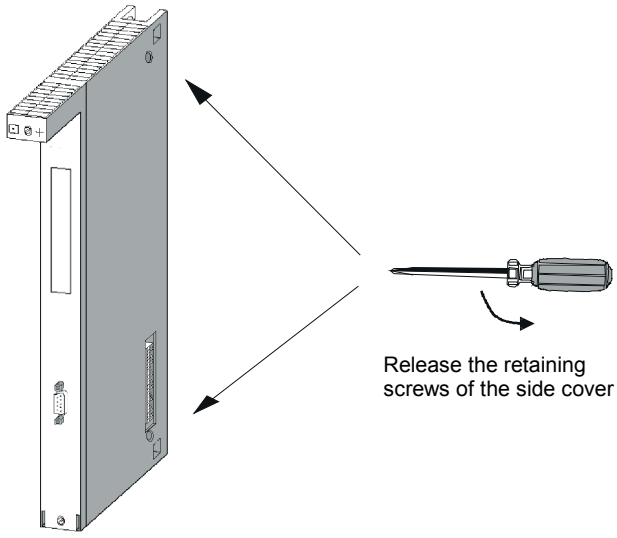


Fig. 2-9 Removing the housing cover on the side

2. Insert the option module from the rear into the slot cover (①), until the position of the 64-pin connector on the main board lines-up with the socket.

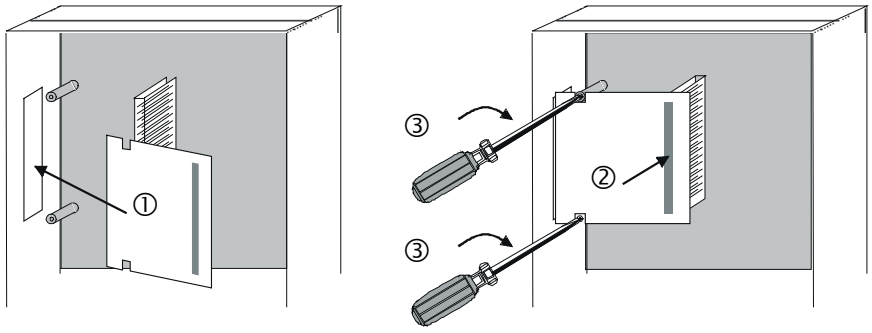


Fig. 2-10 Mounting the option module

3. Insert the option module from the right into the 64-pin system connector on the main board (②). This shows it when it is installed.
4. Using the two screws, screw the option module at the mounting points in the front section of the option module (③).
5. Screw on the side housing cover.

2.4.5 Connection possibilities

Connecting diagram

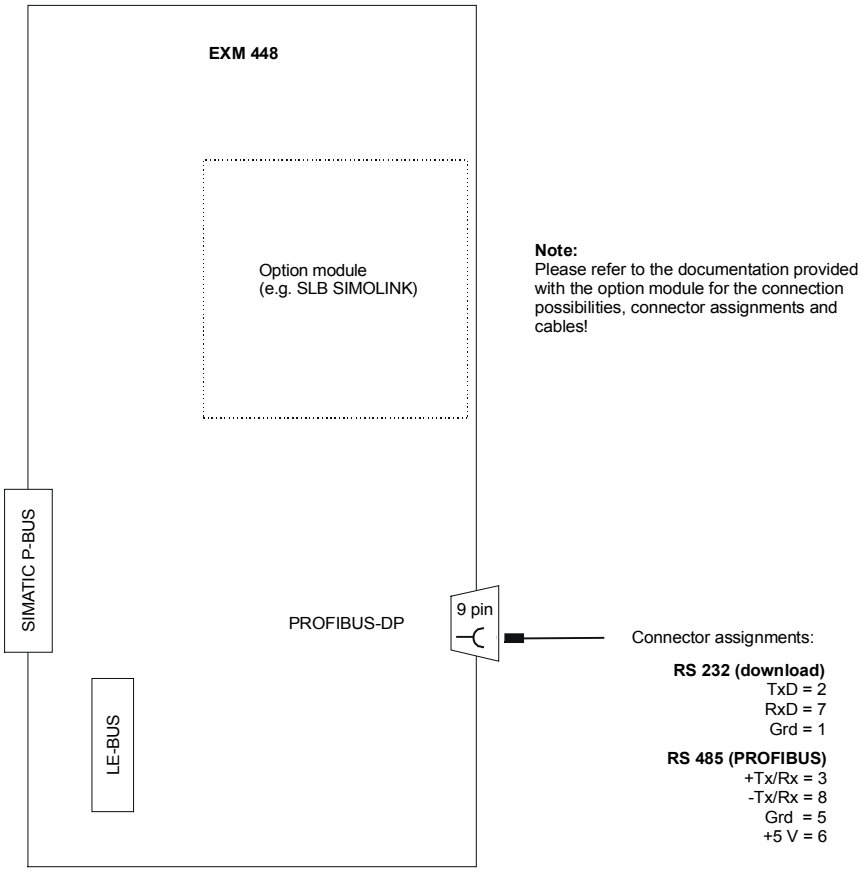


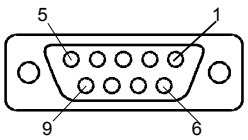
Fig. 2-11 Connection possibilities for the communications expansion module EXM 448

LE-bus connection An additional expansion module (EXM 438/EXM 438-1 or EXM 448) can be inserted at this 5 x 24 pin socket connector.

P-bus connection The 5 x 17 pin socket connectors is used to connect to the SIMATIC S7 backplane (only power supply).

PROFIBUS-DP (X1) The following connections are provided at the 9-pin sub-D socket:

- PROFIBUS interface with RS 485 format with electrical isolation (floating)
- Parameterizing- and diagnostics interface with RS 232 format to download the bus configuration
- 5V power supply for the Optical Link Module (OLM) with electrical isolation



Pin	Designation	Explanation
1	RS 232: ground	for "SS52load“
2	RS 232: TxD	for "SS52load“: Receive signal
3	RS 485: +TxRx	PROFIBUS: Receive- and send signal + (corresponds to data B)
4	RTS	Request to send (for OLM control; "1“ when sending; as for pin 9)
5	M5EXT	External ground; to supply OLMs
6	P5EXT	P5 external; to supply OLMs
7	RS 232: RxD	for "SS52load“: Send signal
8	RS 485: -Tx/Rx	PROFIBUS: receive- and send signal - (corresponds to data A)
9	RTS	Request to send (for OLM control; "1“ when sending; as for pin 4)

Table 2-20 Connection assignment of X1 (RS232 and RS485)

Parameterizing

The "COM PROFIBUS" program is required to use the FM 458 application module with the communications expansion module EXM 448 as master. It runs on a PC under Windows and generates a COM database.

The generated database can also be loaded via

- PROFIBUS (with PC PROFIBUS card CP5411, CP5511 card)

  or

- COM1/2 interface of the PC and RS-232 parameterizing/diagnostics interface with the "SS52load" driver program in the EXM 448.

COM PROFIBUS must be additionally ordered, if EXM 448 is to be configured as master.

Designation	Order No.
COM PROFIBUS	6ES5 895-6SE12 (German)

The "SS52 load“ driver program is included in COM PROFIBUS from V3.1, or it can be requested at no charge via the Siemens Intranet under the following address:

ftp://www.erlf80.asi.siemens.de/ SIMADYN_D/html/treiber.htm

2.4.6 Status displays

There are two LED displays provided under the upper housing cover of the FM 448 communications expansion module. These provide information about the actual operating status.

LED	Status	Diagnostics information
green	dark	PROFIBUS not initialized
	flashing 5 Hz	fatal error: The error code can be read at function block @CSPRO and then contact the SIMADYN D Hotline
	flashing 1 Hz	The connection to the associated CPU module is being initialized (@CSPRO): Check the configuring
	bright	Initialization O.K.
yellow	dark	No bus operation (initialization phase)
	flashing 5 Hz	Bus error/fault, e.g. short-circuit: Check the bus cable and other nodes
	flashing 1 Hz	COM database not available or inactive when downloading (only for PROFIBUS)
	flashing 0.5 Hz	CFC- and COM configuring do not match: Restricted bus operation possible (only for PROFIBUS)
	bright	Bus operation O.K.

Table 2-21 Status displays of the communications expansion module FM 448

NOTE The green and yellow LEDs are only visible from the top through the cooling slots of the housing.

2.4.7 Technical data

Order No.

Communications expansion module EXM 448	6DD1607-0EA0

Voltage, currents

Rated voltage	+5 V
Typical, current drain	0,3 A

Dimensions

Assignment, slots	1
Dimensions W x H x D [mm]	25 x 290 x 210
Weight	0,85 kg

3 Mounting

3.1 Mounting the expansion modules

Introduction

The Order No. and the product release are printed on every SIMATIC S7-400 module. The following diagram indicates where these can be found on a module.

For the product release, instead of the valid number, there is an X. A module with product release 1 is shown in the following diagram.

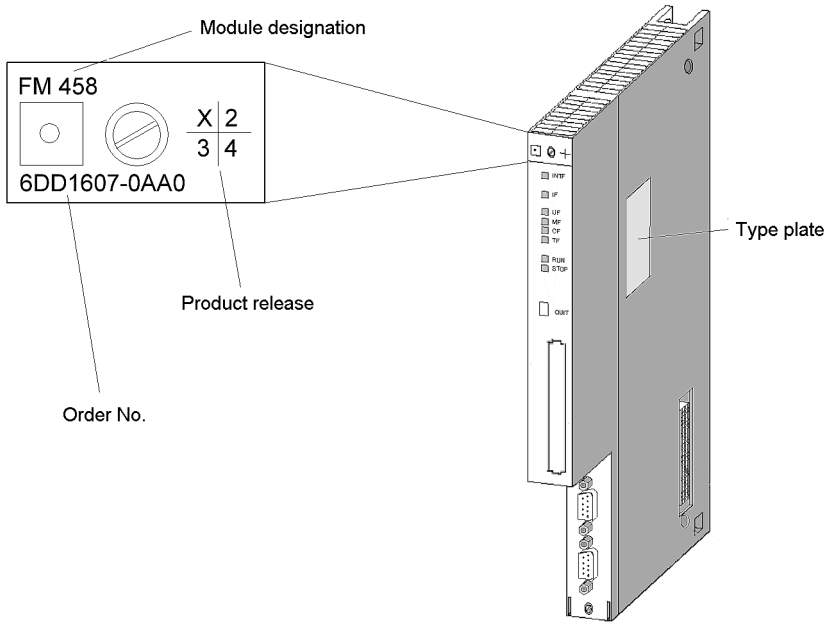


Fig. 3-1 Position of the Order No., product release and type plate

NOTE

A cover plate for the LE bus expansion socket is provided with the FM 458. If an expansion module is not to be installed, this must be screwed in place over the housing opening of the LE bus!

Before installation in the SIMATIC subrack, you must pre-mount the FM458 application module with all of the required options.

A max. of two expansion modules can be used together with the FM 458 application module. The following combinations are possible:

Application module	1st expansion module	2nd expansion module
FM 458	None	None
	EXM 438	None
	EXM 448	None
	EXM 438	EXM 438
	EXM 448	EXM 448
	EXM 448	EXM 438
	EXM 438	EXM 448

Table 3-1 Possibilities of combining expansion modules

Installation sequence

When installing the FM458, proceed in the following sequence:

1. Remove the connector- and socket cover from the modules.
2. Remove the connecting clips provided at the top and bottom of the module.
3. Remove the covers from the modules.
4. Place the modules on a flat surface and plug together.
5. Lock the modules together using the connecting clips at the top and bottom.

The individual steps when installing options are now described.

Removing the connector- and socket cover

There is a 5 x 24-pin socket to connect expansion modules to the LE bus. They are provided on the righthand side of the FM458 application module. This socket is protected using a removable cover.

The following are provided on the EXM 438 and EXM 448 expansion modules

- on the lefthand side, the matching connector
- and on the righthand side, a socket into which one additional expansion module can be inserted.

Remove the transport protection from the expansion connectors and the foil from the expansion socket on the module, at which an expansion module is to be inserted.

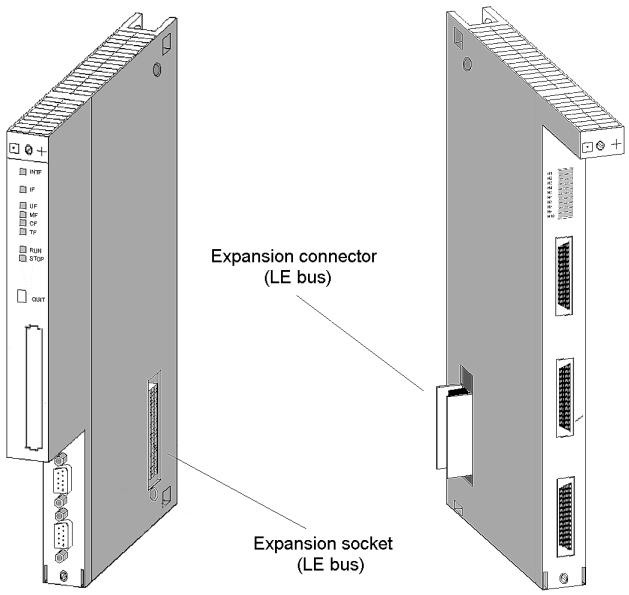


Fig. 3-2 Position of the expansion socket and connector (schematic diagram)

Removing the connecting clips

The expansion modules have connecting clips at the top and bottom. Remove these upwards or downwards.

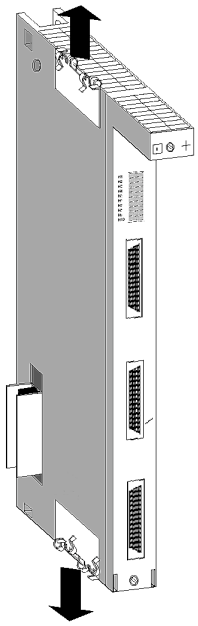


Fig. 3-3 EXM 438 with connecting clips (schematic diagram)

Removing the cover

Remove the cover before plugging the modules together. Proceed as follows:

1. Press the latch downwards (1).
2. Swivel the cover forwards (2).

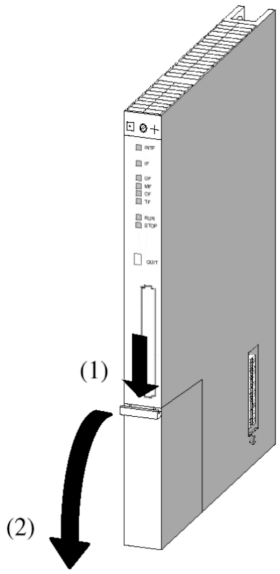


Fig. 3-4 Removing the cover

Plugging the modules together

Place the FM 458 application module and the first expansion module on a flat surface and carefully connect the modules, so that the connector of the expansion module is inserted, with all of its pins, exactly into the socket of the FM458 module.
When required, insert the second expansion module.

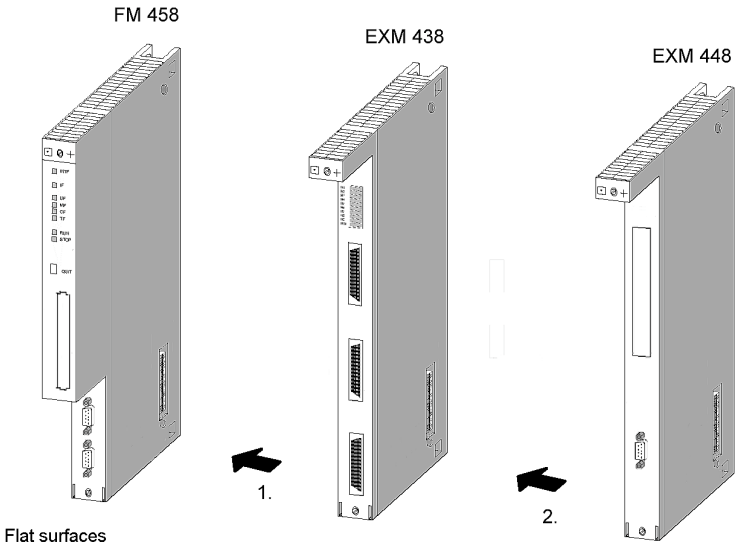


Fig. 3-5 Plugging the modules together (schematic diagram)

WARNING

The connector pins can be damaged if the modules are not correctly lined-up when connecting. The modules must be carefully lined-up with one another before plugging together.

Lock the modules together using the connecting clips

After the modules have been plugged together secure them in place using the two connecting clips provided so that the modules cannot be twisted or moved apart. Proceed as follows:

1. Insert a connecting clip from top between the two modules to be clipped together until the bent clip ends come into contact with the housing cover of the modules.
2. Align the connecting clip, so that the angled section of the clip is located above a grid hole of the module housing cover. The first bent clip end should be located above the 5th grid hole from the rear of the module.

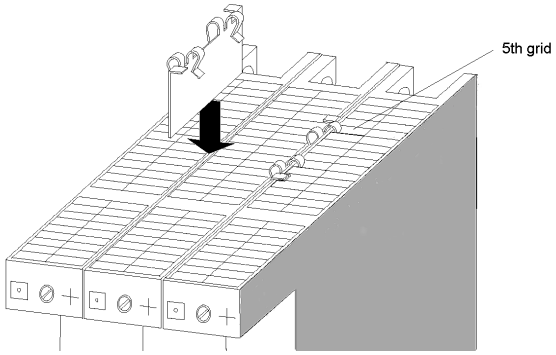


Fig. 3-6 Locking the modules together using a connecting clip (schematic diagram)

3. Then press downwards on the connecting clip at the two ends which are bent at right angles until they latch into place.
4. Repeat steps 1 to 3 at the lower side of the modules to be latched together.

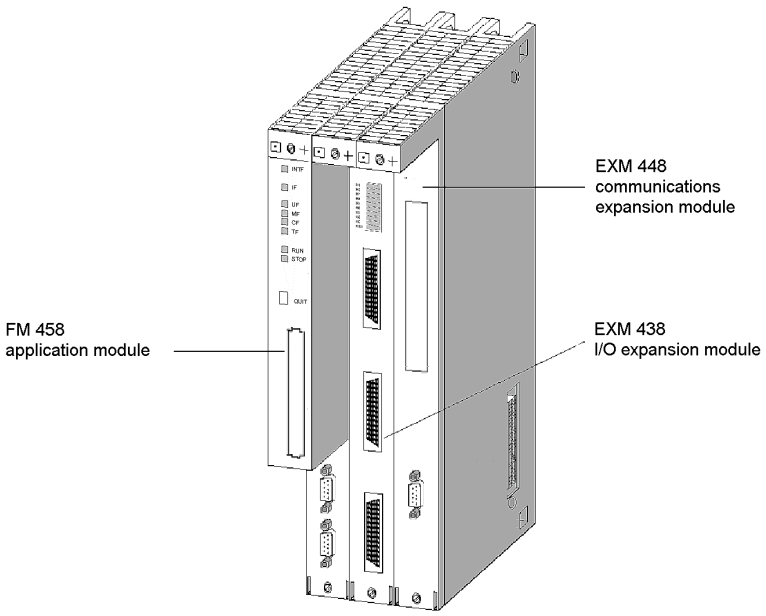


Fig. 3-7 Pre-mounted module assembly with two expansion modules (schematic diagram)

3.2 Installing the assembly into the SIMATIC subrack

NOTE

The subsequently described installation and assembly operations only refer to the FM 458, EXM 438 and EXM 448 modules, which can be installed in the S7-400 automation system.

Detailed information about the mechanical design of a SIMATIC S7-400 station, as well as the installation which must be observed when locating modules in the PLC, are provided in the "S7-400 Installation Manual“ (C79000-G7000-C417).

Installation sequence

Proceed as follows to install the FM 458 module (also as module assembly with options) into the subrack of an S7-400:

1. Remove the line connector at the power supply module.
2. Remove the dummy covers from the slots in which you wish to insert the modules. Hold the dummy cover at the positions marked and withdraw towards the front.
3. Insert the module (1) and carefully swing it downwards (2). If you detect some resistance when swinging the module downwards, slightly lift the module and try again.

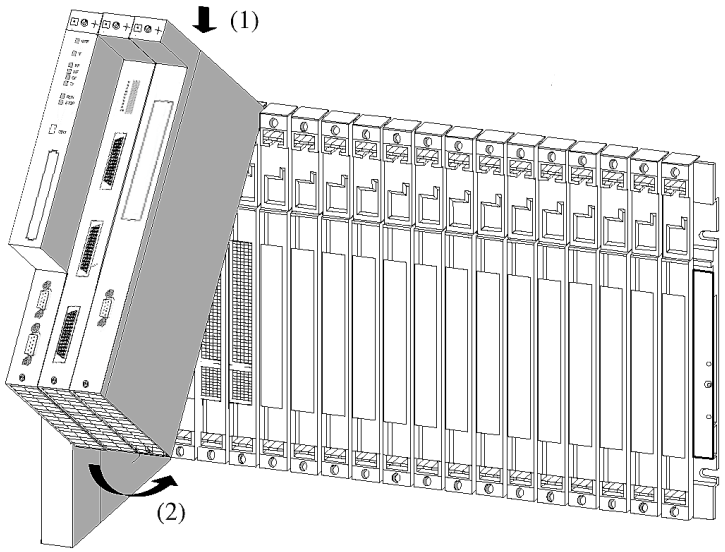


Fig. 3-8 Inserting the FM 458 module (schematic diagram)

4. Screw the module at the top and bottom, tightening the screws to 0.8 ... 1.1 Nm.
5. Re-insert the line connector at the power supply module.

3.3 Application information and noise immunity

CAUTION The following is valid for the FM 458 application module and for the EXM 438 and EXM 448 expansion modules:

- Noise-immune operation is only possible if the modules are tightly screwed into the subrack.
- It is not permissible to insert or withdraw modules undervoltage.

Operation without fan is not possible, a fan assembly is always required

NOTE A fan monitoring signal is not provided by the system and must be configured by the user.

4 Configuring

4.1 Freely configuring the FM 458 application module

Software components

The following software components are required to configure the FM 458 application module:

Components	Function (for FM 458)
STEP 7	General project management and hardware configuration
CFC	Graphic Editor
D7-SYS (from V5.0.1)	Operating system, compiler, function block library
COM-PROFIBUS	Supplementary software, if EXM 448 is to be configured as master.

Detail informations: refer to www.siemens.com/fm458

Graphic configuring

Control related functions can be extremely easily configured using the graphic configuring interface CFC (**C**ontinuos **F**unction **C**hart). A programming language does not have to be learned.

Function blocks are taken from a library comprising approximately 250 function blocks, and placed on a page using simple drag and drop.

The block I/Os are connected with one another by clicking on an output and an input.

For inputs, which are assigned a fixed value and which are not connected, the value is specified in a parameterizing dialog box.

The configured software thus generated is compiled by the graphic configuring interface CFC and downloaded into the FM458 application module.

NOTE

Please refer to the appropriate SIMATIC S7 Documentation and the online help of the programs for information on installation and mode of operation of STEP 7 and CFC.

Using the D7-SYS supplementary software, detailed procedures and instructions are provided in the appropriate SIMADYN D User Documentation "D7-SYS“.

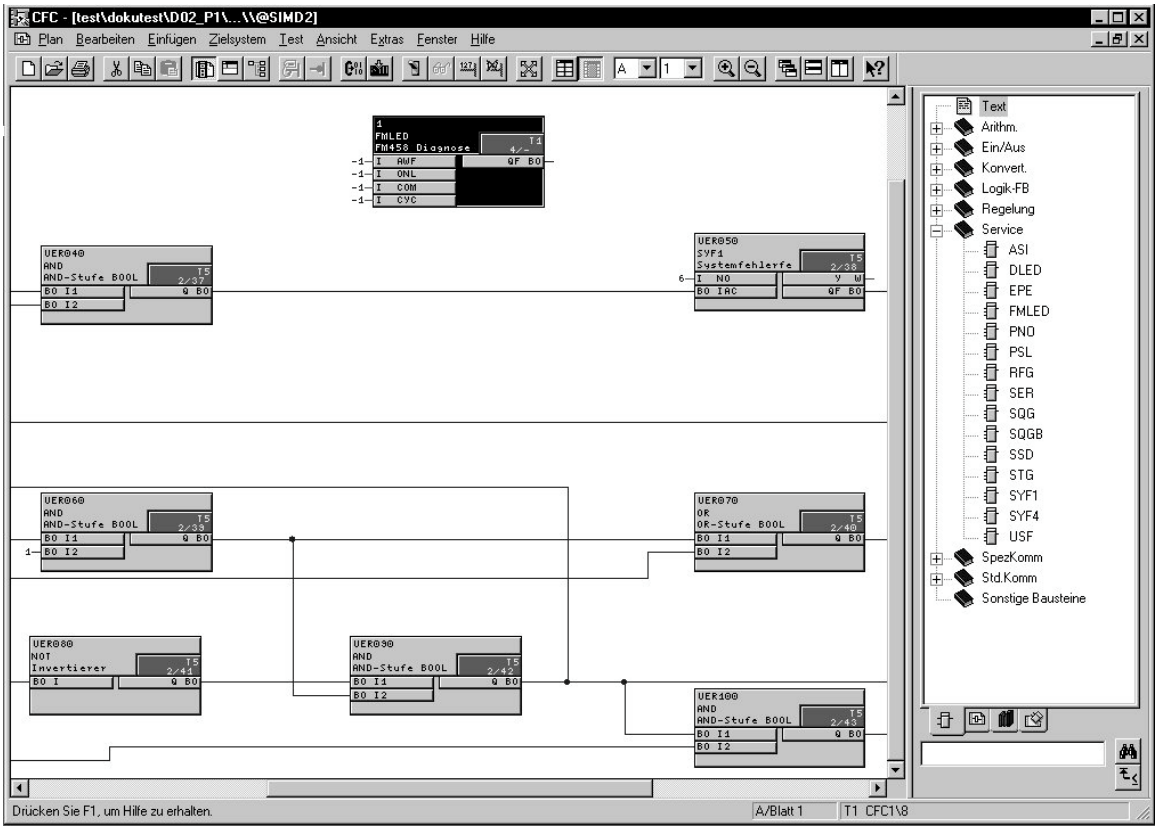


Fig. 4-1 View of the graphic configuring interface

If the program is run on the FM458, the following can be directly implemented on the editor interface (CFC):

- actual values displayed and changed from the FM 458,
- connections displayed, modified, deleted and added,
- and function blocks added or deleted.

4.2 Configuring and parameterizing the components

HWConfig The hardware configuration is defined in the program section of STEP 7, in which the user indicates which components (modules) he wishes to use for his system.

Configuring Arranging subracks, modules and sub-modules in a station window is known as configuring. Subracks are represented using a configuring table, which permits, just like the "real" subracks, a defined number of modules which can be inserted.

Parameterization

Properties of modules which can be parameterized, can be set using the appropriate dialog fields. The module type defines which of the parameters can be set. Before a module can be parameterized, it must be arranged in the subrack.

A dialog field, with one or several tabs appears by double-clicking on the line of the subrack with the module. This includes information and the parameters which can be set for the selected module.

These dialog fields can also be displayed by marking the module and the menu command „Edit > Object properties“ or can be displayed using the righthand mouse key "Object properties".

Procedure

In order to configure and parameterize the layout, you must make the following steps in HWConfig:

1. Select the subrack (S7-400 Rack) ; it must have at least one S7 power supply unit and one S7-CPU.
2. Select the modules and submodules (FM 458 and components)
3. Parameterize the modules (define the properties)
4. Check configuration consistency
5. Save the configuration

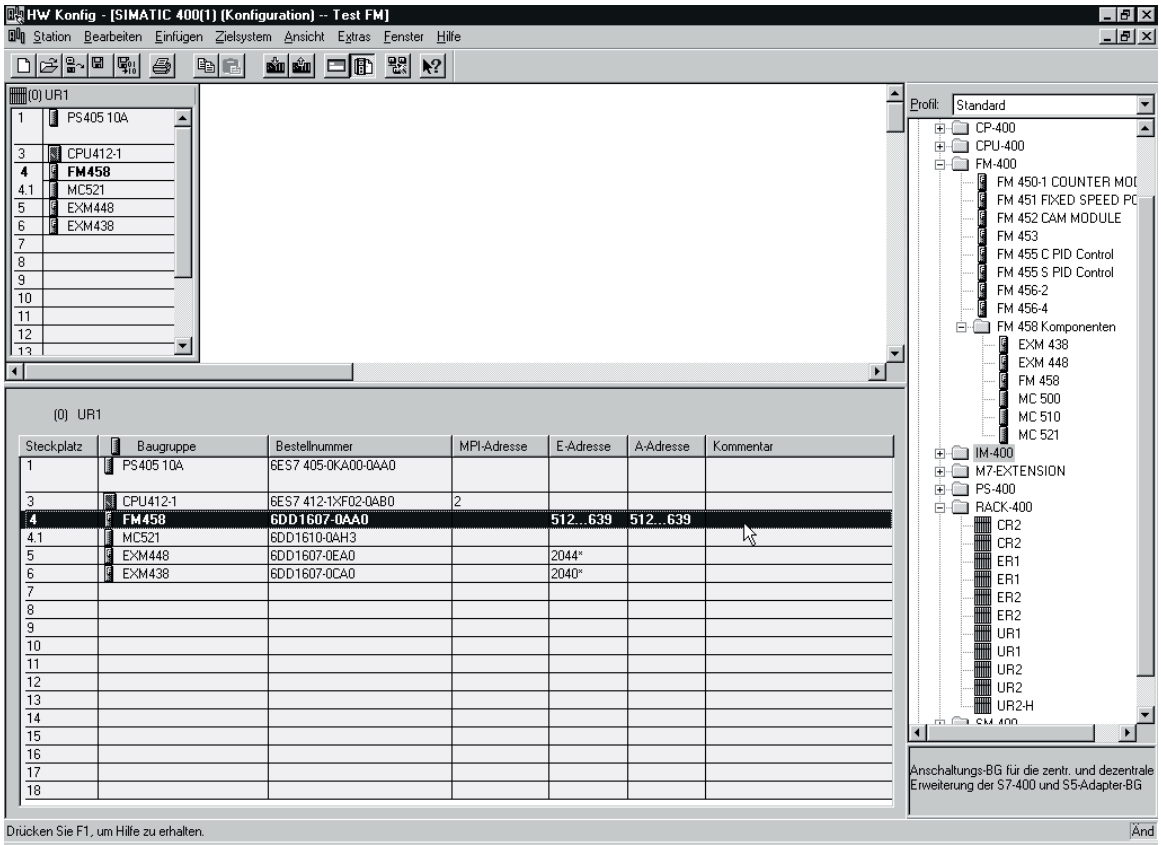


Fig. 4-2 View of hardware configuration man-machine interface (screen)

Basic operator actions

Independent of the packaging technology of a station, the configuration is always made as follows:

1. To open the sub-directories, click on the “+“ symbol in the directory structure of the hardware catalog.
2. A hardware component is marked in the "hardware catalog" window.
3. The selected hardware component is dragged into the station window per drag and drop.

Example

An S7-400 station is to be configured with the following components:

Designation	Type
Rack for S7-400 station	e.g. UR1
Power supply for S7-400 station	e.g. PS 405 10A
CPU for S7-400 station	e.g. CPU 412-1
FM 458 application module	FM 458
Program memory module	e.g. MC 521
Communications expansion module	EXM 448
I/O expansion module	EXM 438

Corresponding to the actual machine (hardware), FM 458 modules are placed in the subrack of the S7-400 station in HWConfig; this subrack must be equipped, as a minimum with a power supply and an S7-CPU.

The 400 subrack, is represented using a "configuration table", which has as many lines, as modules, which can be inserted in the actual subrack.

4.3 Coupling to the SIMATIC S7-CPU

P-bus memory

The **FM 458** has a RAM memory (128 Kbytes) which can be used to connect it to a P bus. Data can be exchanged with **one** SIMATIC S7-CPU via this P-bus memory.
The FM 458 is **passive on the P bus**, i.e. the FM 458 cannot directly access other modules of the SIMATIC station.
There are 3 ways to transfer data to the SIMATIC CPU:

- 4 bytes can be received from the SIMATIC-CPU using a **process interrupt**
- 128 bytes can be sent and received via SIMATIC **I/O accesses**
- extremely large data quantities can be sent and received using **data blocks/sets**

Accessing EXM 438, EXM 448

The **EXM 438**, **EXM 448** expansion modules can only be accessed from the FM 458 (via the FM-internal LE bus); they have no direct connection to the P bus.

Addresses

The start addresses of the I/O, under which a SIMATIC CPU can address the I/O range of the FM 458, are configured in HW Config. The addresses for inputs and outputs can differ.

HW Config menu: *"Edit/Properties/Addresses"*
Default: **512** (decimal; for inputs and outputs)

Diagnostic interrupts

The FM 458 also sends diagnostic interrupts to the SIMATIC-CPU, independent of what has been configured, in the following situations.

- Transition into the statuses
  - "initialization error "
  - "system error "
  - "user stop "
  - "RUN"
- If the memory module is inserted or withdrawn, or is not available

4.3.1 Overview of the 3 data transfer types, FM 458 ←→ SIMATIC-CPU

Designation	Number of data	Configuring	Speed	Computation time (on the FM 458)
1. **Process interrupt**	**4 bytes** to SIMATIC-CPU	*FM 458:* Block PAS7 *SIMATIC-CPU:* OB40, etc.	When PAS7 is called, an interrupt is initiated on the SIMATIC CPU, e.g. OB40 (if a higher priority interrupt isn't being processed at precisely that time).	Extremely low: only for PAS7
2. Data transfer with **I/O (peripheral) accesses**	**128 bytes** in the send and 128 bytes in the receive direction	*FM 458:* blocks S7RD, S7WR *SIMATIC-CPU:* transfer commands for the I/O (periphery)	When a block is called, data is immediately read-out of the memory or written into the memory.	Computation times of all configured S7RD/S7WR blocks: each approx. 5µs.
3. Transferring **data sets/blocks**	For extremely high quantities of data: max. approx. 125 data sets with each max. 240 bytes (refer below.)	*FM 458:* "virtual connections" with blocks @CPB, CRV/CTV *SIMATIC-CPU:* system functions SFC58/59 **Consistency:** All of the data associated with a telegram are consistent with one another, i.e. they are transferred in a "data package".	The data associated with a telegram are read or sent when the block is called.	Computation time is required for each data set via telegram processing (approx. 30µs each CRV/CTV) and to copy the net data into/out of the P-bus memory. If extremely large data quantities are involved and there is a P-bus utilization, then a somewhat higher degree of computation time can be assumed. The data are transferred into the memory in blocks up to max. 16 bytes. The P bus must be re-assigned between the blocks, which means that the required computation time may increase.

Table 4-1 Data transfer, SIMATIC-CPU ↔ FM 458

All of the 3 data transfer types can be used in parallel.

4.3.2 Initiating a process interrupt on SIMATIC-CPU

PAS7

Function block PAS7 initiates, when triggered, a process interrupt to the assigned S7-CPU. Supplementary interrupt info of 4 bytes is configured at the IFO input, which contains net data information.

When an interrupt is initiated, the interrupt OB, which should be configured in HW Config, is called in the SIMATIC S7-CPU. The supplementary interrupt info, taking up 4 bytes, is written into the local data of the interrupt OBs.

The start address of the input/outputs of the sending FM 458 (to be configured in HW Config; in the example 512dec = 200hex) is also saved in the local data of the OB 40.

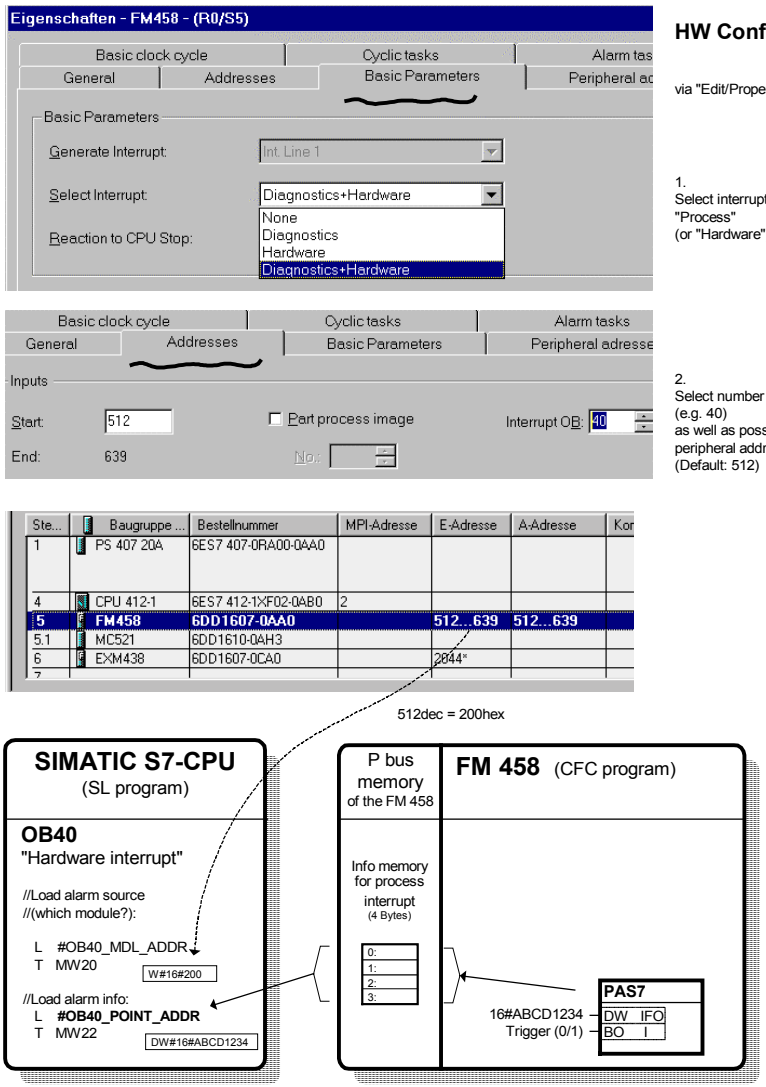


Fig. 4-3 Data transfer to the S7-CPU with process interrupt

4.3.3 Data transfer via I/O accesses

Application

To transfer low data quantities: up to max. 128 bytes

Blocks and transfer commands

Appropriate function blocks are available for each data transfer direction and for each data type to be transferred.

SIMATIC-CPU			FM 458	
Data type	**Transfer command (SL program)**	**Write direction**	**CFC function block**	**Data type**
BYTE	T PAB abs.addr.	→	**S7RD_B**	BOOL
INT	T PAW abs.addr.		**S7RD_I**	INT
DINT	T PAD abs.addr.		**S7RD_D**	DINT
REAL	T PAD abs.addr.		**S7RD**	REAL
BYTE	L PEB abs.addr.	←	**S7WR_B**	BOOL
INT	L PEW abs.addr.		**S7WR_I**	INT
DINT	L PED abs.addr.		**S7WR_D**	DINT
REAL	L PED abs.addr.		**S7WR**	REAL

Table 4-2 Data types and the associated commands/blocks for peripheral accesses

CFC data type "BOOL"

The 8-bit CFC data type "BOOL" is represented in the SIMATIC S7-CPU as "**BYTE**" data type. This means that the SIMATIC S7 user must appropriately set or evaluate the decisive MSB (**M**ost **S**ignificant **B**it):

- S7-CPU: bit variable
- FM 458: 1XXX XXXX = TRUE
  0XXX XXXX = FALSE

Data save

In order to achieve high processing speeds with 32-bit accesses, the following must be ensured by appropriately configuring the FM 458/CFC (offset, refer below) as well as programming the SIMATIC-CPU, so that

- 16-bit values (INT/WORD data types)
  are saved at even addresses (word limits) and
- 32-bit values (REAL, DINT data types)
  at addresses which are divisible by 4 (double word limits)

are saved in the two P-bus memories which are 128 bytes large.

Entering the offset for FM 458

The FM 458 side is accessed using the S7RD/S7WR blocks, at which the offset of the data to be transferred is configured, i.e. the position within the 128 bytes.

When assigning the offset, the number of all of the values located before the block involved (blocks) and their data type (assigned memory range in bytes) are taken into account. It is especially important that possible overlaps are avoided. Gaps between individual values are not permitted (e.g. for reserve ranges).

However, the offset is not specified in the number of bytes, but as a multiple of the data type of the associated function block!

In this case, the offset, starting from an entry in bytes must be divided by 2 (for INT types) or by 4 (for REAL/DINT types) and this result must be configured at the offset input.

Using this technique, it is automatically guaranteed, that the data to be transferred is available at optimum addresses, i.e. addresses which can be quickly accessed. However, if the data is unfavorably structured, this can result in memory cells which cannot be used (refer to the example diagram below). In order to avoid this, for example, BYTE- and INT types should be individually distributed over the memory area, but should be arranged one after the other (consecutively).

Absolute address for SIMATIC-CPU

Absolute addresses are used in the SIMATIC S7 program which are obtained from the FM 458 address and the offset of the associated S7RD/S7WR block in bytes (!):

Absolute address = (offset x F) + FM 458 I/O address

FM 458 I/O address: The start address, configured in HW Config for the I/O range of the associated FM 458

Offset = Value at the associated S7RD/S7WR function block
F = Data type length in number of bytes:

F = 1 for S7WR_B, S7RD_B
F = 2 for S7WR_I, S7RD_I
F = 4 for S7WR, S7RD, S7WR_D, S7RD_D

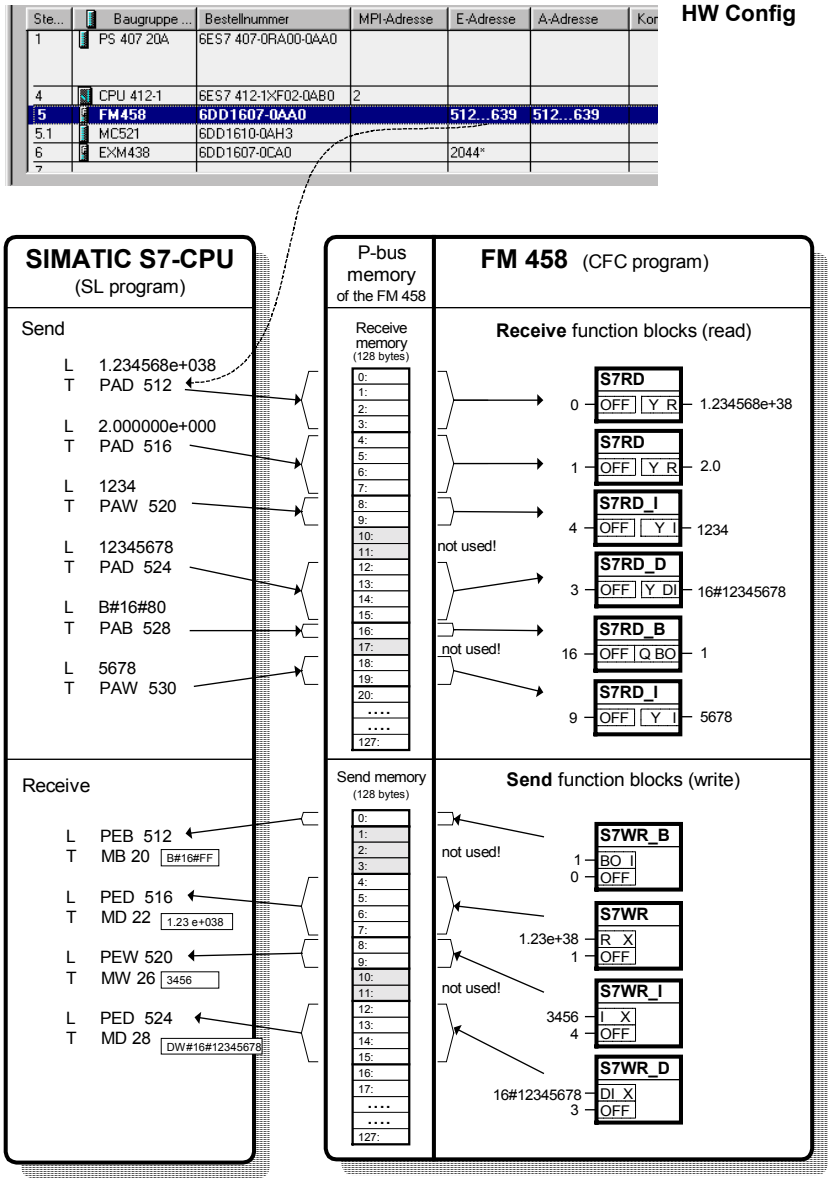


Fig. 4-4 Data transfer with peripheral accesses (I/O accesses)

4.3.4 Transferring data sets

Application

If extremely large quantities of data are to be transferred, e.g. for visualization applications (WinCC), or if data have to be transferred between SIMATIC and FM 458 for an extremely high number of drives.

Features, limit values

- Memory available on the P bus: 114688 bytes (0x1C000 hex), for various "data sets" (or "telegrams").
- max. 125 read and 125 write data sets
- max. length per data set (telegram): 240 bytes
- max. data quantity which can be transferred:
  For internal data management and buffer mechanisms, the following are required
  - for received data sets, 2x data set length
  - for sent data sets 3x data set length
  The sum of the required bytes for all of the write and read data sets may not exceed the above mentioned memory size of 114688 bytes!

Example:
Max. number of write and read data sets, each 240 bytes:

114688 bytes / (5 * 240 bytes) = 95.5733

A maximum of 95 write- and 95 read data sets, each with 240 bytes can be configured.

SIMATIC S7 access with SFC

"**S**ystem **F**unction **C**alls" SFC are used in the SIMATIC-CPU for data set transfer:

- write **SFC 58** data set (to the FM 458)
- read **SFC 59** to the data set (from FM 458)

FM 458 with "virtual connections"

This coupling type is configured on the FM 458 in 3 steps:

1. Establish the coupling:
   Configure a central communications block **@CPB** (from the "SpezKomm" block family) to initialize and monitor the data set coupling.
2. Define the send and receive data sets:
   A function block must be configured for each data set (telegram):

   CRV to receive,
   CTV to send

   Data/entries at the CRV/CTV connections:
   – ***CTS = FM458.*P_B**
   Connection is connected to the P bus coupling:

CFC entry:
Mark the CTS/righthand mouse key/connection to the operand. The configured module name (default “FM458”) appears in the selection list for the module to be connected.

- ***AR / AT = ‘channelname.datasetnumber”***
  Any name (max. 6 characters) and separated by a point, the data set number, which corresponds to the RECNUM info/data in the SCF58/59 calls.
  Value range: 2 to 127
  for the send and receive data set
  If several data sets are used, the channel names must be unique, i.e. they must be different.

- ***CRR / CRT = ‘Text’***
  Enter the name for the virtual connections are which are combined to form a data set (telegram).
  CFC entry:
  Mark the connection / righthand mouse key / connection to operand **“!”**
  and comprises max. 6 characters.

- ***MOD = R***
  P-bus communications always operates in the refresh mode.

3. Assigning process quantities to the data set:
   Marked block outputs are sent and the inputs are supplied from a receive data set if they are connected to the data set/telegram via the dialog box “Insert Connection to Address”. All virtual connections with this name are combined to form a data set.

A **sequence number** still has to be specified for each value (connection).
This only specifies the sequence of the associated value in the data set, but not the absolute position!
For the CFC code compilation, the data, associated with a data set, are arranged in the memory in an increasing sequence. The sequence numbers can be assigned with gaps, e.g. so that data can be easily and subsequently inserted..
Contrary to "data transfer with peripheral accesses", for virtual communications, data is always packed consecutively **without any gaps**. The configuring engineer must ensure, by sensibly assigning the sequence number, that the data are saved to word or double word limits in order to achieve a high processing speed.
The sequence number does not provide information on the address and does not specify the offset!

If an **offset of a value** in the data set (e.g. in bytes) is required for S7 program, it can be calculated from the sum of all of the previously located values, taking into account their data type (length=2 for INT, length=4 for REAL/DINT).

Different data types

SIMATIC S7 data type	FM 458 (CFC) data type	Comments
BYTE	BOOL	The MSB in the byte to be sent is decisive MSB = 1, BOOL is TRUE MSB = 0, BOOL is FALSE
REAL	SDTIME	

Table 4-3 Assignment of SIMATIC S7 and SIMADYN D data types

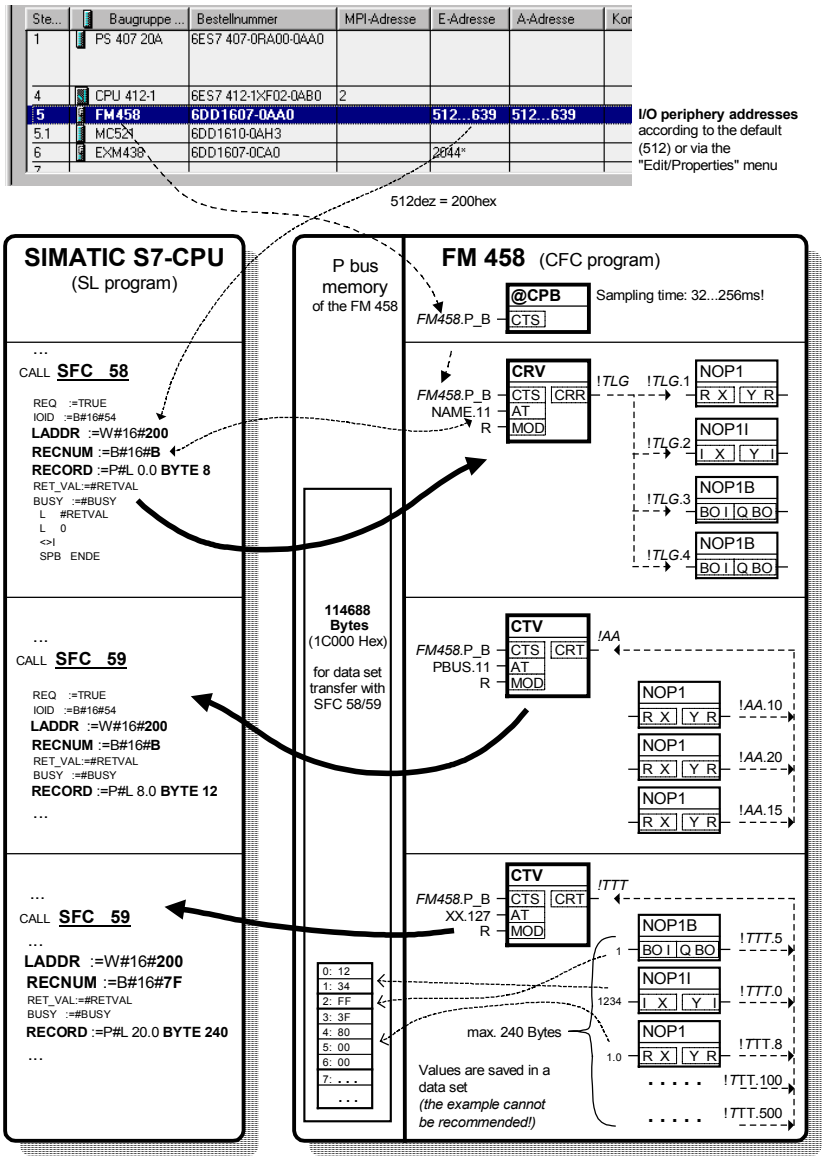


Fig. 4-5 Transferring 3 data sets

4.4 SIMOLINK drive coupling

4.4.1 Basic information

Introduction

SIMOLINK (**Si**emens **Mo**tion **Link**, SL) is a digital, serial data transfer protocol using fiber-optic cables as data transfer medium.

The SIMOLINK drive coupling has been developed for extremely fast and/or rigid cycle transfer of process data (setpoints, actual values, control and status information)

- between drives (dispatcher, transceiver)
  - SIMOVERT MASTERDRIVES MC/VC, or
  - SIMOREG DC-MASTER or
- between drives and a higher-level automation system (SL master)
  - SIMATIC S7-400 station with FM 458 and EXM448-1 or
  - SIMADYN D subrack with PM5/6 and ITSL
- between automation systems (SL master, slave/s)
- Where all of the connected nodes are synchronized (SYNC telegram) to a common system clock.

Application

By transferring a time-equidistant and jitter-free SYNC telegram, SIMOLINK allows high-dynamic response and all of the connected individual drives move in absolute position synchronism (e.g. virtual shaft).

Features

- Max. 201 active nodes (SL master, dispatcher and transceiver, passive nodes include switches and cable concentrators)
- Bus cycle:
  Time between two SYNC telegrams, i.e. the circulating time in the ringbus
- SYNC telegram:
  All of the connected nodes are synchronized after the telegrams were sent
- Telegram:
  32-bit word (double word), occupies one channel for each piece of process data.
- Nodes read **and** write their data once every bus cycle.

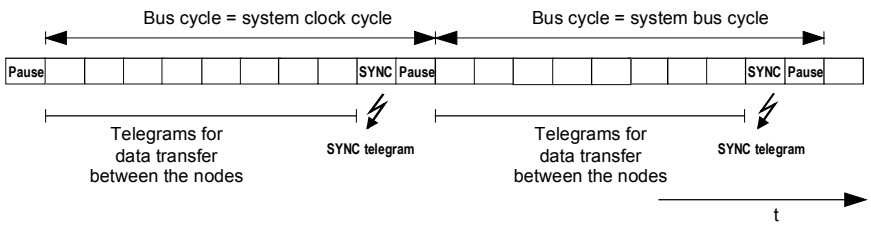


Fig. 4-1 SIMOLINK telegram data transfer

- Telegram runtime: $6.\overline{36}\ \mu s$
- All of the telegrams are sent immediately one after the other.
- For instance, for a selected bus cycle time of 0.8 ms, the SL master can transfer
  - one double word each to a max. of 124 slaves/transceiver, or
  - 4 double words each to a max. of 31 slaves/transceiver
- The remaining times are intervals where a telegram is not sent (NOP).
- Master-slave process data transfer:
  - up to 200 slaves/transceiver can be addressed with address gaps
  - up to 8 double words individually for each slave/transceiver
  - own process data for each slave/transceiver
- Dispatcher transceiver process data transfer:
  - up to 200 consecutively addressed transceivers
  - up to 8 double words
  - the same number of used channels for dispatcher and transceiver (nodes with a max. number of double words defines the number of channels for all)
- Data transfer rate: 11 Mbit/s
- Bus topology: Fiber-optic cable ring, each node as signal amplifier
- Max. distance between two nodes:
  - 40 m for plastic fiber-optic cables, or
  - 300 m for glass fiber-optic cables.

4.4.2 Application with master-slave process data transfer

The automation system with SIMOLINK interface is generally configured as the SL master. Whereby, all of the other coupling nodes are set as slaves/transceiver (refer to MASTERDRIVES option module SLB SIMOLINK).

The number of channels used for each slave/transceiver is defined by the SIMOLINK function blocks (connections CTV, CSV).

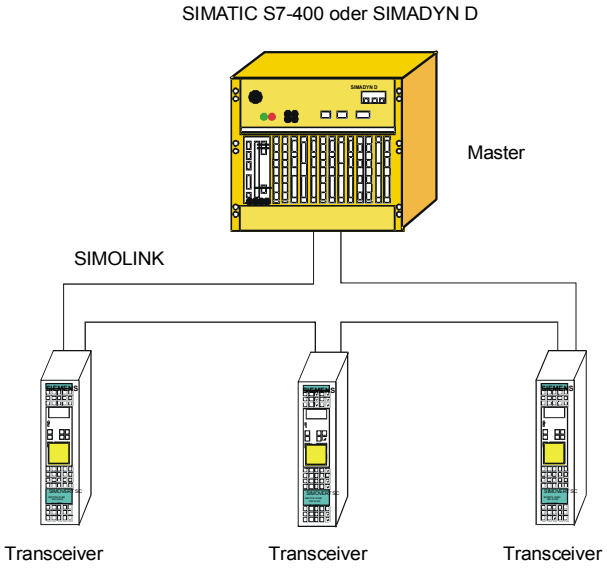


Fig. 4-2 Application example for master-slave process data transfer

Master

- The SL master can read and write into all of the channels of all of the slaves/transceiver.
  Configuring data:
  Function block @SL: MOD connection = 1...5
  For each slave: e.g. one SLSVAV

Slave

- Each slave can read all of the channels and write into a max. of 8 (**own!**) channels.
  Configuring data:
  Function block @SL: MOD connection= 0
  For each read channel: e.g. one SLAV
  For each write channel: e.g. one SLSV,
  Connection, FSL: Slave's **own** address
  Connection, NSL: 1

Slave-to-slave data transfer

- In order to transfer data from slaves/transceivers to slaves/transceivers which are physically located in front in the ring, in the same bus cycle, the slave-to-slave communications setting must be used.
  Configuring data:
  Function blocks SLAV and SLDIS: Connection QV = 1

4.4.3 Applications and modes which should be set

Various SL master, dispatcher and slave modes can be set by appropriately configuring SIMOLINK.

For **position-synchronous** actual value sensing and setpoint input (e.g. “virtual shaft” for printing or packaging machines), the **jitter-free** (equidistant in time) modes should be set

- External mode (Mode 4),
- Interrupt automatic mode (Mode 3) and
- External cyclic mode (Mode 5)
- Cyclic automatic mode (mode 10) and
-

(refer to the SIMOLINK function block description @SL).

Synchronized data send, 1 cycle deadtime

For the mode 3, 5 and 10, the telegram data of the previous bus cycle are processed in parallel to the bus cycle and equidistant SIMOLINK telegrams are sent and received. This allows the shortest SIMOLINK cycles to be configured. Ideally, this technique is suitable for applications with “**virtual shaft with values which uniformly change**”, which are required, for example, for printing machines.

The operating modes **automatic mode** (Mode 3) with processing in an interrupt task Ix should be used for jitter-free synchronization of the drives

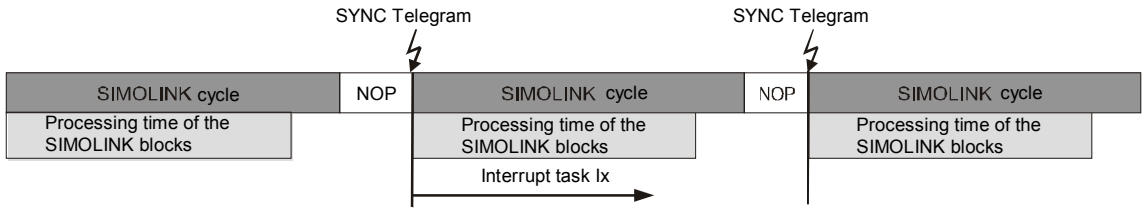


Fig. 4-3 Automatic mode (Mode 3)

and **external-cyclic mode** (Mode 5) with synchronization to the basic sampling time T0.

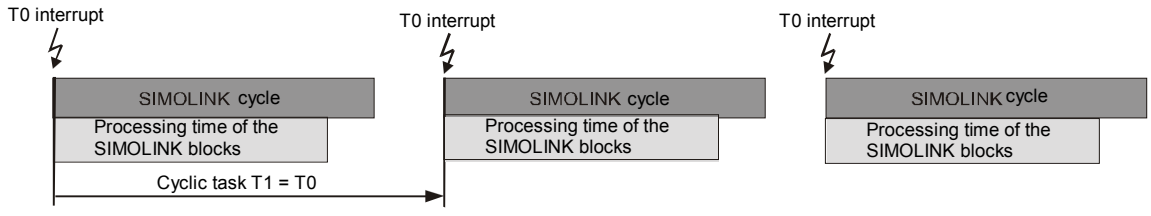


Fig. 4-4 External-cyclic mode (Mode 5)

The sampling time should be selected somewhat higher than the bus cycle time.

The external-cyclic mode offers the advantage that the processor hardware of two SIMOLINK rings can be synchronized to the (common) base sampling time T0.

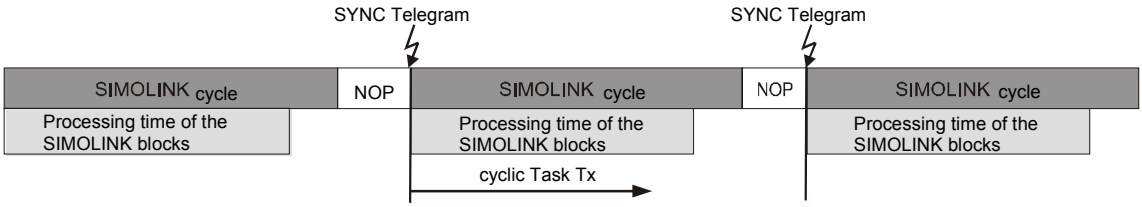


Bild 4-5 Cyclic automatik-mode (Mode 10)

The cyclic-automatic-mode 10 offers the advantage to place the function block configuration in cyklic tasks, in opposed to mode 3.

Fastest sensing, synchronous

The jitter-free SL-master mode, external-mode is best suited for synchronous actual value sensing with the fastest processing (minimum deadtime). This means, that it can be used as "**virtual shaft with dynamically changing values**", for example, for packaging machines.

In the **external mode** (Mode 4) the SIMOLINK cycle is synchronized to the base sampling time T0. The SIMOLINK blocks are immediately executed in the configured interrupt task Ix when the SYNC telegram is subsequently received.

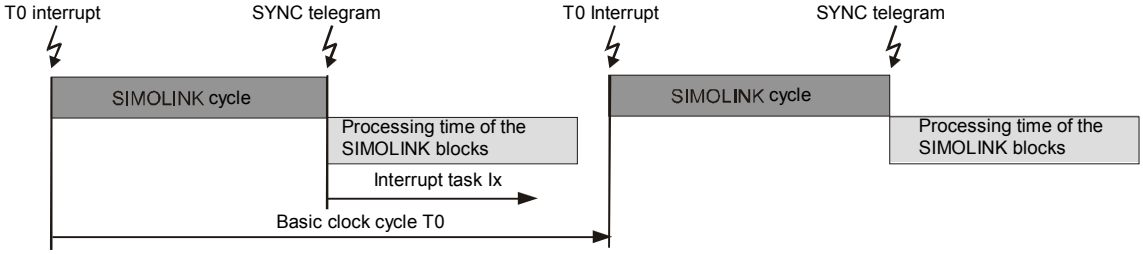


Fig. 4-6 External-mode (Mode 4)

The base sampling time T0 setting must correspond as a minimum to the bus cycle time plus the interrupt task processing time.

Fastest data send, non-synchronous

If data are to be transferred to other nodes after the calculation with minimum deadtime, then either the non-synchronous mode or the timer mode is used.

For the **non-synchronous mode** (Mode 1), data is directly output after the SIMOLINK blocks have been processed in a cyclic task Tx.

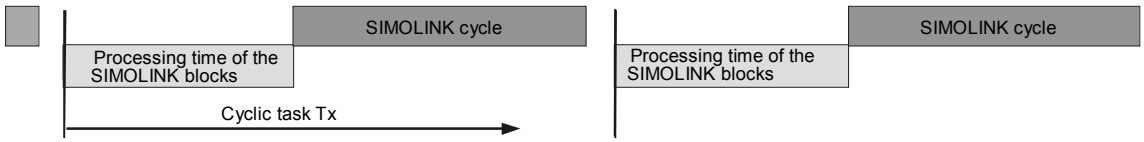


Fig. 4-7 Non-synchronous-mode (Mode 1)

In the **timer mode** (Mode 2), data is directly output after calculation in an interrupt task Ix which assigns the processing of the SIMOLINK blocks a higher priority.

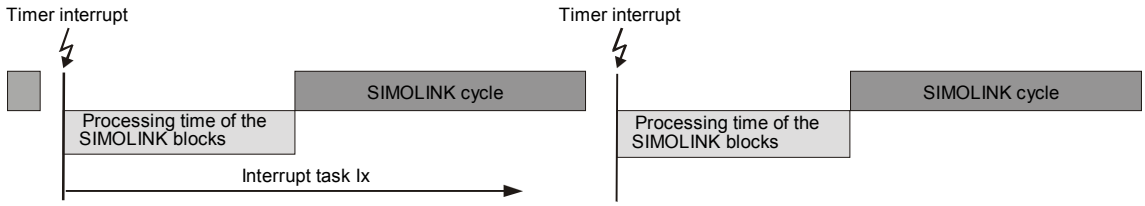


Fig. 4-8 Timer-mode (Mode 2)

In these non-synchronous SL-master modes, which exhibit jitter, the coupled drives cannot be operated with position synchronism if the SYNC telegram is sent in the time intervals which depend on the actual configuring. This allows the fastest possible data transfer between SL master (Mode 1 or 2) and the slave (Mode 0).

Reading telegrams, synchronous

The **slave mode** (Mode 0) is used to read and evaluate the bus data transfer in a drive ring, for e.g. monitoring and diagnostic purposes.

With each received SYNC telegram, the SIMOLINK module initiates that the configured interrupt task Ix is processed. If it is used as the receive section for fast data transfer between SL master and slave, all of the telegrams can be read and processed. Furthermore, it is possible to write a max. 8 telegrams, in order to, for example, transfer signals to the SL master.

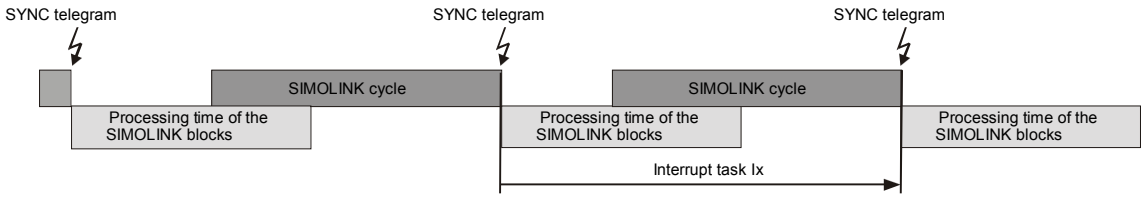


Fig. 4-9 Slave mode (Mode 0)

Coupling two automation systems

In order to send data between two automation systems via SIMOLINK, which exceeds the amount of data using 8 telegrams, two independent SIMOLINK rings are required. This means that every node can be configured once as SL master to send in one ring and as slave to receive in the other ring. This technique is used, for example, to achieve

- synchronized processing and
- extremely fast data transfer

between two SIMATIC FM 458 modules each with two EXM 448-1 expansion modules.

Cyclic or interrupt task ?

When selecting the operating mode, it should be noted, that interrupt task processing can interrupt cyclic tasks at any time. This can influence the timing. For the non-synchronous mode, the SIMOLINK cycle is delayed and for the external cyclic mode, T0 must be adapted to prevent computation time overflow or multiple sending of the same values which have not been re-calculated.

Synchronization to the base sampling time T0 can be set in 100 µs intervals while interrupt tasks are initiated by the SYNC telegram, dependent on the telegram duration.

4.4.4 Configuring - first steps

Using as an example a master-slave coupling, the necessary settings are subsequently described which must be or should be observed when configuring.

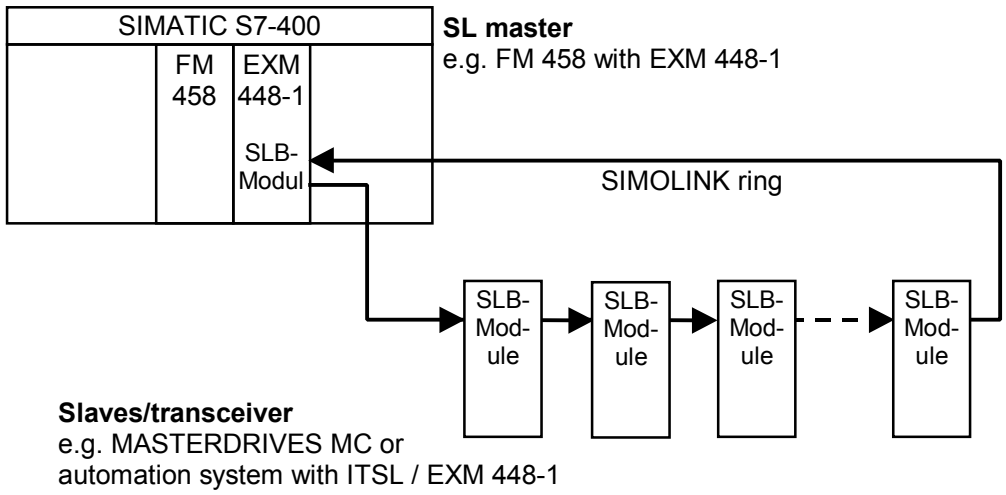


Fig. 4-10 Example for a master-slave coupling

Hardware

The SIMOLINK ring comprises the minimum of two and a maximum of 201 SLB modules, which are coupled to one another through fiber-optic cables. There is only one SL master on a ring. All of the other nodes are slaves.

An SLB module is a hardware component of an ITSL, an EXM 448-1 module or an option module SLB (**S**IMO**L**INK **B**oard, Order No. 6SX7010-0FJ00).

NOTE

Additional information on these modules and their installation is provided in the User Manual D7-SYS “Hardware“, or SIMOVERT MASTERDRIVES Instruction Manual SLB SIMOLINK board.

4.4.4.1 Configuring the SIMOLINK coupling under STEP 7

For SIMATIC FM 458 with EXM 448-1, the basic clock cycle T0, possibly the interrupt task Ix and the symbolic hardware assignment for the SIMOLINK are set in the HW Config of STEP7 in the properties dialog box.

NOTE

The EXM 448-1 expansion module should be configured as EXM 448 in HWConfig.

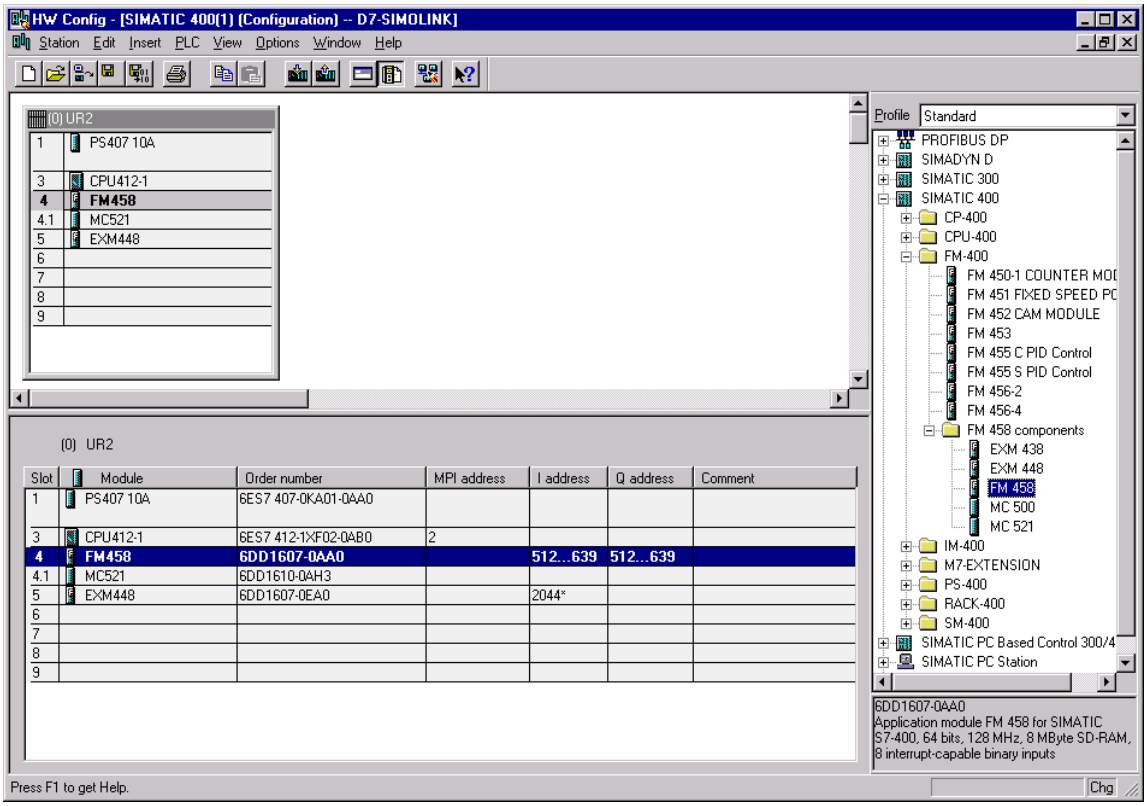


Fig. 4-11 Configuring for FM458 with EXM448-1

Basic clock cycle

The basic clock cycle time must be set in HWConfig in the properties window under the "Basic clock cycle" tab.

The basic sampling time must match the PWM frequency set in the MASTERDRIVE MC (the factory setting is: 5 kHz, parameter P340). The time sectors are derived from this frequency.

The usual values are 3.2 ms, 1.6 ms and 0.8 ms, to which the system can be synchronized. 1.6 or 3.2 ms are set depending on the control type.

The value, set as the base sampling time, must also be entered in parameter P746 of the MASTERDRIVES MC.

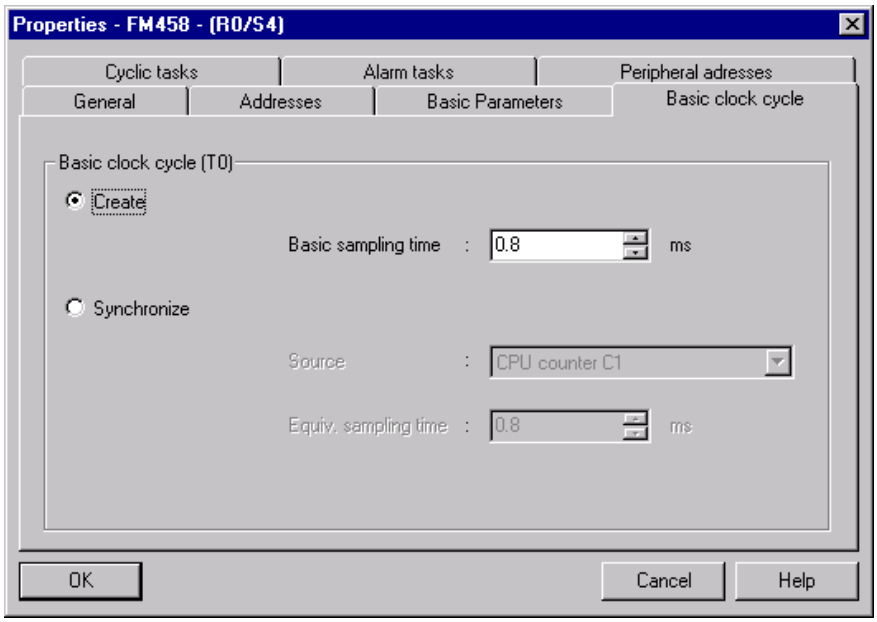


Fig. 4-12 Basic clock cycle in the HW Config

Interrupt task

For modes 0, 2, 3 and 4, sources must be assigned to initiate the configured interrupt tasks.

The settings are made in HW Config in the Properties window under the "Interrupt task" tab, dependent on the configured hardware components.

Mode	Interrupt source to be set for interrupt task Ix of the SIMOLINK blocks, if:			
	EXM 448-1/ITSL, 1st expansion	**EXM 448-1/ITSL, 2nd expansion**	**optional SLB module ITSL, 1st expansion**	**optional SLB module ITSL, 2nd expansion**
0	LE bus interrupt 1	LE bus interrupt 3	LE bus interrupt 2	LE bus interrupt 4
2	LE bus interrupt 5	LE bus interrupt 6	LE bus interrupt 7	LE bus interrupt 8
3	LE bus interrupt 1	LE bus interrupt 3	LE bus interrupt 2	LE bus interrupt 4
4	LE bus interrupt 1	LE bus interrupt 3	LE bus interrupt 2	LE bus interrupt 4

Table 4-4 Interrupt task source assignment for expansion modules with SIMOLINK

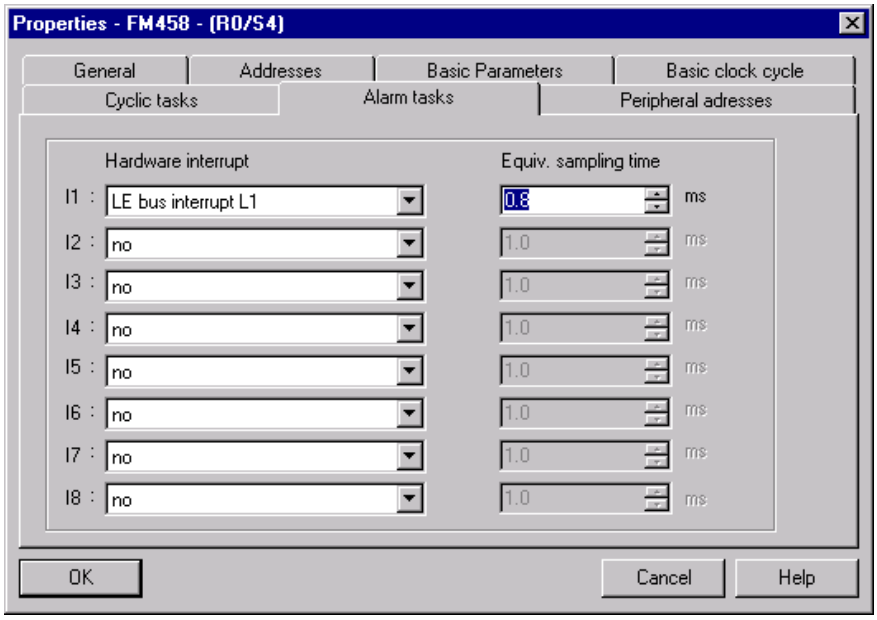


Fig. 4-13 Alarm task setting in the HW Config

Hardware addresses, SIMOLINK blocks

The SIMOLINK blocks @SL, SLAV, SLD, SLDIS, SLSV, SLSV2 and SLSVAV must be assigned to a HW address in the HW Config properties window of the EXM 448 under the "Plug-in module / I/O addresses tab.

The "process I/O" should be activated as plug-in module type. After this, symbolic names can be assigned for the I/O addresses (pre-set symbolic names are entered via the "Default" button.

The SIMOLINK blocks only use the symbolic name under “I/O address 2” (SIMOLINK does not require “I/O address 1”).

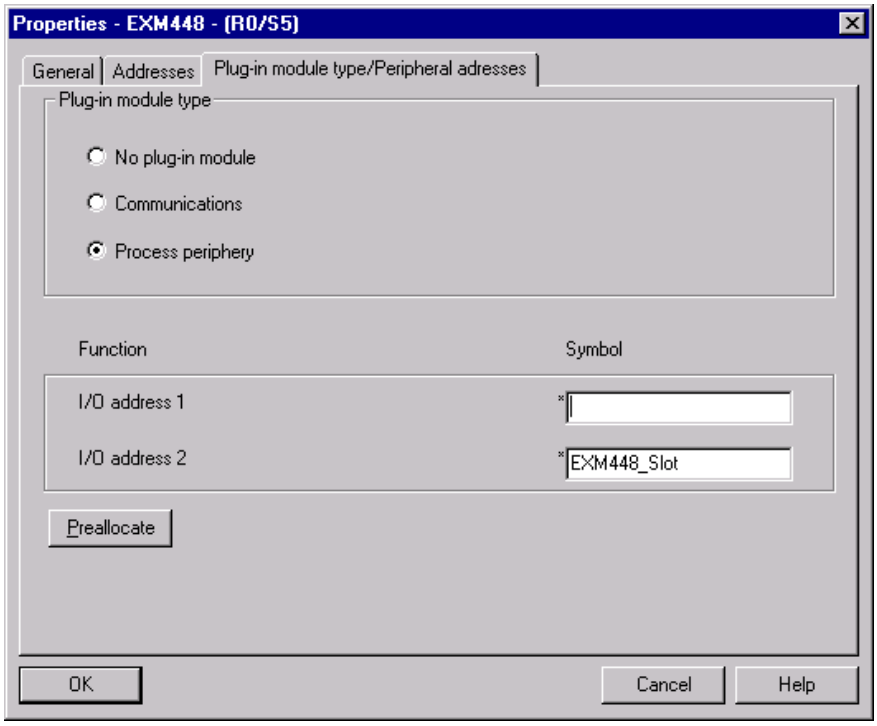


Fig. 4-14 Symbolic hardware assignment of an EXM 448-1

Different symbolic names are assigned for each SIMOLINK interface.

For example, when configuring an ITSL module, symbolic names are entered for the integrated (TAD) and the optional SIMOLINK interface (OAD) under the "Addresses" tab:

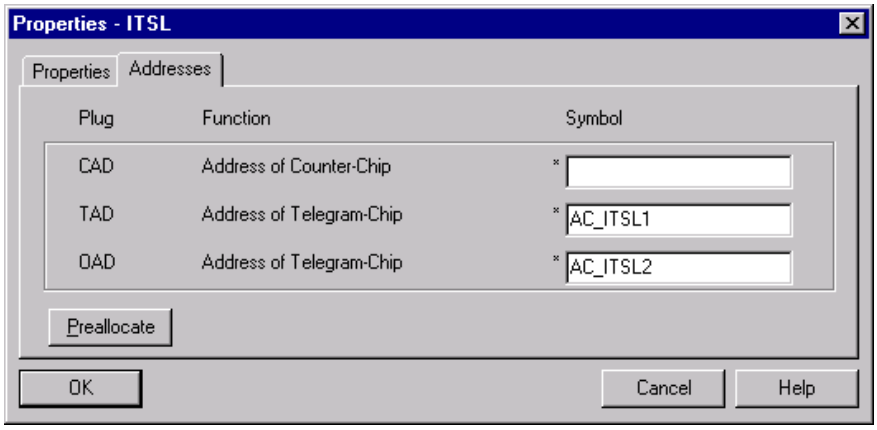


Fig. 4-15 Setting hardware addresses for an ITSL module with optional SLB module

4.4.4.2 SIMOLINK function blocks

The configuring engineer can use the following function blocks:

- @SL SIMOLINK central block
- SLAV SIMOLINK receive block, one for each actual value
- SLSV SIMOLINK send block, one for each setpoint
- SLSV2 SIMOLINK send block, for two setpoints
- SLSVAV SIMOLINK send and receive block for up to 8 setpoints and actual values of the slave
- SLD SIMOLINK delta evaluation
- SLDIS SIMOLINK dispatcher

The central block @SL permits the initialization and monitoring of communications in a SIMOLINK ring.

It may only be configured once for each SIMOLINK ring in a sampled cyclic task (T4 or T5) which is, as a minimum, 4x longer than the send and receive block.

If a transceiver no longer receives a telegram as a result of an interruption, then it automatically sends a special telegram, which evaluates the @SL function block. The address of the node is output at NDM, which first signals the fault.

NOTE Additional information regarding the mode of operation and the connections (I/O) of the specified blocks are provided in the online help of the CFC Editor and in the "Function block library" reference Manual".

4.4.4.3 Parameterizing the MASTERDRIVES MC

The following parameters must be set in the SIMOVERT MASTERDRIVES MC (refer to the User Documentation „MASTERDRIVES MC“):

Parameter	Significance/setting
P740	Own node address, transceiver/slaves: 1...200 (dispatcher=0)
P741	Telegram failure time, if the telegram fails, fault F056 is output. The usual values: > 3 x bus cycle time (refer to P746)
P742	Send power, dependent on the length of the fiber-optic cable
P743	Number of nodes in the SIMOLINK ring
P745	Number of channels (this is only relevant for the dispatcher)
P746	Bus cycle time (only relevant for the dispatcher)
P749	Read address, which is generated from the node address and the channel number, whereby the node address does not have to match its own node address (P740) Example: 2.0 = node address 2, channel number 0
P751	Send data, Index 1 = channel 1 (low word), Index 2 = channel 1 (high word), Index 3 = channel 2 (low word), etc.
P755	SIMOLINK configuration 0x100 should be entered for modes 4 and 5 so that synchronization is realized (this is valid from firmware release 1.4 for MASTERDRIVES MC)

Table 4-5 Parameters for MASTERDRIVES MC

SIMOLINK

P.-Nr.	Name		Ind	Indextext	Parameterwert	Dim
P740	SLB Teiln.Adr.	+	001	1.SLB	1	
P741	SLB Tlg.Ausz.				10	ms
P742	SLB Sendeleist.				3	
P743	SLB AnzahlTeiln.	+	001	1.SLB	5	
P744	Q.SYNC Auswahl	+	001		B0 Festbinektor 0	
P745	SLB Kanalanzahl	+	001	1.SLB	4	
P746	SLB Zykluszeit	+	001	1.SLB	3.20	ms
P747	Q.SLB Appl.Flags	+	001		B0 Festbinektor 0	
r748	SLB Diagnose	+	001	Anz. SYNC-Tlg	0	
P749	SLB Leseadresse	-	001		1.0	
			002		1.1	
			003		1.2	
			004		1.3	
			005		1.4	
			006		1.5	
			007		1.6	
			008		1.7	
r750	SLB Empf.daten	+	001		0x0	
P751	Q.SLB Sendedaten	+	001		K32 Zustandswort 1	
r752	SLB Sendedaten	+	001		0x0	
P753	Q.SyncZeitzähler				K0 Festkon. 0%	
P754	Max.sync.Zeitsch				0 Buszykluszeit	
P755	SIMOLINK Konfig.				0x100	

Fig. 4-16 Parameters for MASTERDRIVES MC (DRIVE Monitor and SIMOVIS)

Number of nodes

When configuring the system, it should be noted that the number of nodes is restricted by the following factors:

- Pulse frequency set in MASTERDRIVES MC
  The sampling time for the time sector to be synchronized is obtained from this pulse frequency (parameter number P340).
- Data quantity to be transferred
  The number of telegrams which are to be sent along the SIMOLINK ring between the SL master and the slaves.

The following formula applies:

$$N = \left(\frac{P746 + 3.18181\,\mu s}{6.36\,\mu s} - 2 \right) * \frac{1}{P745}$$

- with P746=bus cycle time (this depends on the pulse frequency and the time sector to be synchronized)
- with P745=number of channels
- with 6.36 µs=telegram run time

Node tables

When the MASTERDRIVES MC pulse frequency is set to 5 kHz, for example, the following values are determined:

No. of channels	No. of nodes		
	0.8 ms (T2)	1.6 ms (T3)	3.2 ms (T4)
1	124	201	201
2	62	124	201
3	41	83	167
4	31	62	125
5	24	49	100
6	20	41	83
7	17	35	71
8	15	31	62

Table 4-6 Node table for various bus cycle times (drive converter/inverter time sectors in brackets)

4.4.5 Coupling diagnostics

LEDs

The user can use the 3 LEDs on the front of the SLB module to analyze the operating status.

Operating display

LED	Status	Diagnostics information
green	flashing	Error-free net data transfer via SIMOLINK
red	flashing	SLB module in operation
yellow	flashing	Data transfer with the information processor FM458 or PMx is OK

Table 4-7 Operating display, SLB module

Fault display

LED	Status	Diagnostics information
green	dark/ bright	No net data transfer via SIMOLINK: Bus cable not connected or defective, poor fiber-optic cable transition, send power (launch power) too low
red	dark/ bright	SLB module power supply failed Replace the SLB module or power supply through FM458 and check PMx
yellow	dark/ bright	No data transfer with the automation processor FM458 or PMx, bus cable not connected or defective, poor fiber-optic cable transition, send power (launch power) too low, replace SLB module or automation processor FM458 and PMx

Table 4-8 Fault display, SLB module

Fault output

The fault statuses are output coded at the outputs YF of the appropriate SIMOLINK blocks.

NOTE

Only the last fault event is displayed.

Value	Diagnostics information **F:** Fault cause **R:** System response **A:** Remedy
2	F: TAD input is incorrectly connected (e.g. HW address of CS8+SLB module) R: No telegram data transfer A: Use symbolic hardware assignment of the EXM 448-1 or ITSL module
3	F: Incorrect module or SLB module not inserted or defective hardware R: No telegram data transfer A: Use or replace SLB module
4	F: SLB module is already being used by another central block @SL, configured twice R: No telegram data transfer A: Only use one FB @SL for each SIMOLINK ring

Value	Diagnostics information **F:** Fault cause **R:** System response **A:** Remedy
5	F: Memory access problem (internal error message) R: No telegram data transfer A: Reduce the size of the application software or move to another process module
6	F: Send/receive block(s) signal: Central block @SL not configured R: No telegram data transfer A: Insert @SL in the software (min. 4 x sampling time of send/receive blocks)
9	F: This software does not support this hardware combination, e.g. CS8+SLB module R: No telegram data transfer A: Use an EXM 448-1 or ITSL module for the drive coupling
10	F: Modes 0, 2 and 4: Block was not configured in an interrupt task R: No telegram data transfer A: Configure the appropriate block in the interrupt task
11	F: Modes 1 and 3: Block was not configured in a cyclic task R: No telegram data transfer A: Configure the appropriate block in a cycle task
12	F: Mode 5: Block was not configured in a cyclic task with T1=T0 R: No telegram data transfer A: In HW Config: Select T1=T0, configure the appropriate block in cyclic task T1
13	F: Mode 4: Equivalent sampling time is not equal to T0 R: No telegram data transfer A: In HW Config: Select an equivalent sampling time = T0
14	F: Modes 0, 2 and 4: Interrupt source for the interrupt task is incorrect R: No telegram data transfer A: In HW Config: Set the interrupt task source as in the assignment table
15	F: Mode 1: Not all send/receive blocks in one sampling time R: No telegram data transfer A: Configure all of the send/receive blocks in the same sampling time
16	F: Incorrect mode setting R: No telegram data transfer A: Set a valid mode (mode 0...5) at FB @SL
17	F: Mode 0, FB @SL: incorrect node address (slave) at input ASL R: No telegram data transfer A: Select a valid setting at input ASL: 1...200
18	F: FB @SL signals: No send and receive blocks available R: No telegram data transfer A: Configure send and/or receive block(s)
19	F: No. of SIMOLINK telegrams too high or SIMOLINK cycle time exceeded R: Telegram data transfer up to max. possible number A: Configure max. 1021 net telegrams or increase SIMOLINK cycle time or configure fewer SIMOLINK blocks (refer to the formula)
20	F: Send/receive block signals: Incorrect slave address R: Restricted telegram data transfer functions A: Select valid slave address: 0...200
21	F: Send/receive block signals: Channel number incorrect R: Restricted telegram data transfer functions A: Select a valid channel number: 0...7

Value	Diagnostics information **F:** Fault cause **R:** System response **A:** Remedy
22	F: Mode 0: Slave attempts to write into an incorrect address R: Restricted telegram data transfer functions A: Select own slave address
23	F: Logical configuring error: Slave-to-slave communications was configured as duplex operation, however, only one direction is possible for each slave (send or receive) R: Send and receive the same data A: Either configure send or receive for slave-to-slave communications
30	F: Physical data transfer faulted on the SIMOLINK ring R: No telegram data transfer A: Increase send power (launch power) at one of the subsections, replace medium or connector
31	F: CRC error (check sum error), data transfer along the ring faulted R: Telegram failure A: Increase send power (launch power) at one of the subsections, replace medium or connector
32	F: Timeout error in the SIMOLINK ring, bus node signals a fault R: No telegram data transfer A: FB @SL, evaluates output NDM, beforehand, check node and medium
33	F: Mode 0: Signaled SIMOLINK cycle time (in the special telegram from SL master) does not correspond to the configured equivalent sampling time R: Restricted telegram data transfer functions A: In the HW Config: Adapt the equivalent sampling time of the slave to that of the SL master

Table 4-9 Error output, SIMOLINK-FBs

4.4.6 Options and accessories

The following are available to configure a SIMOLINK coupling and as spare part:

Order No.	Components
6SE7090-0XX84-0FJ0	SLB module, spare part (without documentation, without connector)
6SX7010-0FJ00	SLB module, retrofit package (documentation, 2 fiber-optic cable connectors, 5m plastic opto-cable, 1 connector for terminal X470)
6SY7000-0AD15	Attachment for SLB (2 LWL cables, 5m plastic opto-cable)
6SX7010-0FJ50	System package for SLB (40 fiber-optic cable connectors, 100m plastic opto-cable, 20 connectors for terminal X470)

Table 4-10 SIMOLINK option modules and accessories

4.5 Table function

4.5.1 Introduction

The table function in SIMATIC TDC / SIMADYN D provides the user with the possibility of linking-in and using tabular values (values in a table) in a configured software application. In this case, the function blocks TAB and TAB_D must be configured on the SIMATIC TDC and SIMADYN D sides. Tabular values, data type REAL are managed using the TAB and data type DINT, using TAB_D. The user provides the tabular values.

The table function can be configured in three modes:

- **Manual mode**, i.e. the tabular values are directly entered at the block via an online interface (e.g. CFC in the test mode), or transferred to the block using teach-in from the program (refer to Fig. 1).
- **Automatic mode: Communications**, i.e. the tabular values are transferred via a communications interface (TCP/IP, DUST1, S7 via P bus). In order to transfer tabular values from an S7 control to a SIMATIC FM 458 application module via the P bus, in addition, the WR_TAB should be configured on the S7 control side (refer to Fig. 2).
- **Automatic mode: Memory card**, i.e. the table values are downloaded into the memory card, from where they are read.

NOTE The "Automatic mode, memory card" mode is presently still not available.

It should be noted, that it is only possible to toggle the modes between "**Manual mode"** and **"Automatic mode: Communications"** as well as "**Manual mode"** and **"Automatic mode: Memory card"**.

A validity check is made if the tabular values have been entered or transferred. The address of the table is displayed at "TAB" output.

The tabular values are managed twice, i.e. in two tables. The table, defined as "valid" (=active) is used for all arithmetic/computation operations of the configured application software. The "invalid" (=inactive) table is used to manage value changes. All of the tabular values, changed by the user, are initially transferred into the invalid table. If the inactive table is activated, the new tabular values are mirrored in the second table. The table which had been active up until then automatically becomes invalid. This means that the new tabular values are available in both tables.

Both tables can be saved in the SAVE area which is backed-up (buffered) by a battery in order to prevent data loss (connection SAV=1 when initializing).

NOTE A precise description of function blocks TAB and TAB_D is provided in their respective online help.
A detailed description of the WR_TAB function blocks is provided, further below in the Section "Function block WR_TAB".

4.5.1.1 Overview, "Manual mode"

The principle procedure in the "Manual mode" is shown in the following diagram:

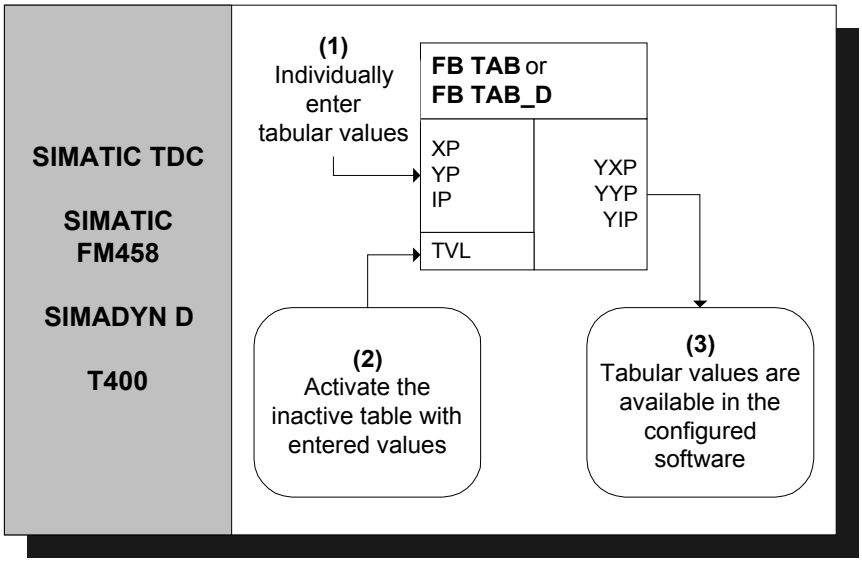


Fig. 4-17: Principle procedure in the "Manual mode"

A detailed description of the "Manual mode" is provided in Section "Manual mode" (Page 4-38)

4.5.1.2 Overview, "Automatic mode: Communications"

In the "Automatic mode: Communications", tabular values can be transferred using the following communication versions:

- S7 via the P bus for SIMATIC FM 458 (it is necessary to additionally configure the WR_TAB on the control side)
- TCP/IP (tabular values can be transferred from a SIMATIC TDC module to another one using the CTV and CRV FBs)
- DUST1 (tabular values can only be transferred via a DUST1 interface)

The tabular values are transferred using data telegrams.

The following diagram illustrates the principle procedure in the "Automatic mode: Communications" for transferring tables from an S7 control to a SIMATIC FM 458 application module via the P bus:

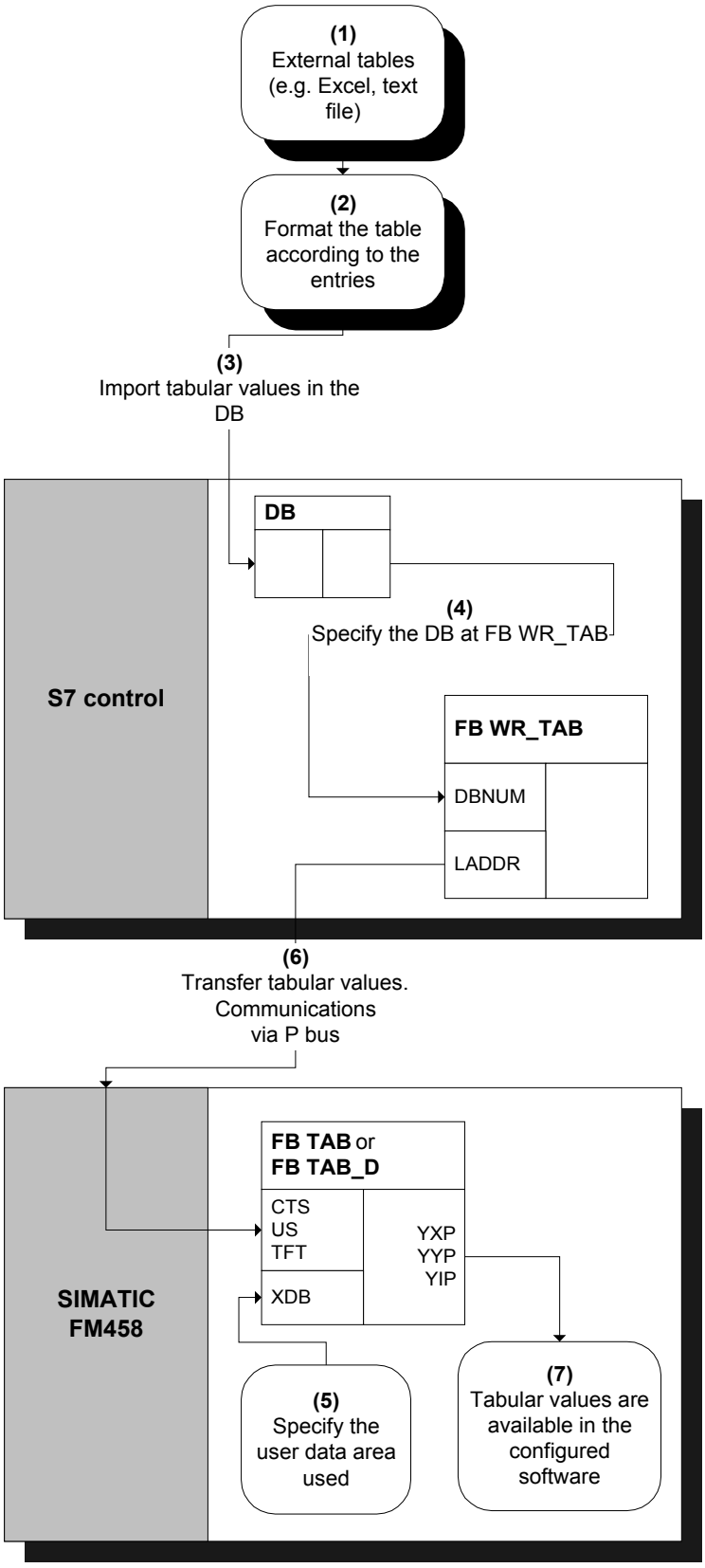


Fig. 4-18 Principle procedure for "Automatic mode: Communications"(via P bus)

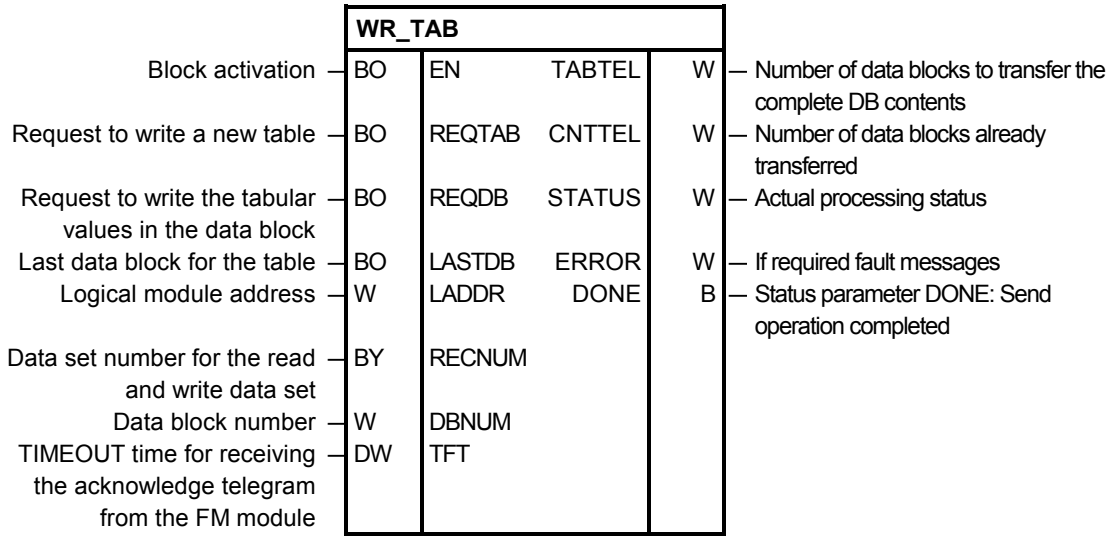
A detailed description of the "Automatic mode: Communications" mode to transfer tables from an S7 control to a SIMATIC FM 458 application module is provided in the Section "Automatic mode: Communications" (Page 4-40).

4.5.1.3 Function block WR_TAB

The function block WR_TAB is used to transfer tables from one S7 control to a SIMATIC FM 458 application module. The tabular values (permissible data types are REAL and double integer) are saved in a data block. They are transferred from WR_TAB to the function blocks TAB and TAB_D on the SIMATIC FM 458 application module, which then internally manages the tabular values.

The WR_TAB should be configured on the control side. The tabular values are transferred from one S7-400 control to a SIMATIC FM 458 application module via the P bus. All of the values are always transferred, which are in the DB specified at the DBNUM input.

Symbol



I/O

The individual connections (I/O), their data types and a connection description are listed in the following table:

Parameter	Declaration	Data type	Description
REQTAB	INPUT	BOOL	REQTAB = 1: Request to write a new table
REQDB	INPUT	BOOL	REQDB = 1: Request to write the tabular values which are saved in the data block
LASTDB	INPUT	BOOL	Last DB for the table
LADDR	INPUT	WORD	Logical address of the SIMATIC FM 458 application module
RECNUM	INPUT	BYTE	Data set number for the read and write data set
DBNUM	INPUT	WORD	Data block number of the DB in which the tabular values are located.
TFT	INPUT	DWORD	TIMEOUT time in ms for receiving acknowledge telegrams from the SIMATIC FM 458 application module.
TABTEL	OUTPUT	WORD	Number of data blocks required to transfer the complete DB contents
CNTTEL	OUTPUT	WORD	Number of data blocks already transferred to the FM module
STATUS	OUTPUT	WORD	Indicates the current status of the processing / data transfer: 0: Table transfer is inactive 1: Table transfer is active. Table values have been partially transferred from a DB (wait for the next partial transfer) 2: Table values have still not been completely transferred from a data block.
ERROR	OUTPUT	WORD	If a fault/error occurs while processing the function, then the return value is an error code
DONE	OUTPUT	BOOL	Status parameter DONE=1: Send operation has been completed

The following errors can occur and are displayed at the ERROR output:

Error code	Explanation	Remedy
0xB210	OK	-
0xB211	Logical module address invalid	Specify a valid module address at input LADDR.
0xB212	Data set number not valid	Enter the tabular values in an increasing sequence in the DB.
0xB213	Invalid table data format	Tabular values must have data type REAL for the TAB and data type DINT for the TAB_D.
0xB214	The data format of the new data set does not match that of the previously transferred data set	Ensure that all of the tabular values have the same data format.
0xB215	FM 458 does not respond	Check the communications connection and configuring.
0xB216	Table is too large	Transfer the table in sub-sets, i.e. either distribute tabular values over several DBs or after each partial transfer write new (additional) tabular values into DB and transfer.
0xB217	Table is not complete (X / Y values)	Complete the table, there must be a Y value for each X value.
0xB218	REQTAB is reset during processing	Transfer the tabular values again.
0xB219	REQDB reset during processing	Transfer the tabular values again.
0xB21A	DB number is not valid	Specify a valid DB number.
0xB21B	TIMEOUT when receiving the acknowledge telegram	Check the communications coupling and configuring. Transfer the tabular values again
0xB21C	Invalid processing status	Check the configuring of the WR_TAB.

Errors associated with the SFC58 or SFC59 are displayed at the ERROR output.

4.5.2 Manual mode

4.5.2.1 Application

The "Manual mode" mode represents the simplest way of inserting tabular values into a configured software package. However, it is comparatively time consuming as data has to be manually entered or taught-in from the program.

Entering tabular values

After the TAB or TAB_D has been correctly configured, the tabular values can be entered one after another. To start off with, the table size, i.e. the number of value pairs (=points) should be specified at input NP. If the table is to be saved in the SAVE area, then input SAV of the must be 1.

The tabular values can then be subsequently entered. In this case, to start, the index point i should be specified at input IP of the value pair to be entered. The X and Y value of the point should then be entered at inputs XP and YP. In order to accept the entered value, after entering each value pair, input WR should be set from 0 to 1. Before entering the next point, the index at input IP should be incremented. The values for this point should then be entered. This procedure is repeated until all of the values have been entered.

A specific sequence does not have to be observed when entering the individual points.

The number of entered points must match the data at input NP.

All of the entries during this procedure are transferred into the inactive table of the and are only available after being activated in the configured software. In order to activate the inactive table with the entered values, input TVL should be set to 1.

Additional changes can then be again made in the inactive table and are only available after this has been re-activated again.

Interrogating the tabular values

In order to output the entered tabular values, after entering the data at input IP, the index of the point i, to be displayed is specified, and input RD is set from 0 to 1. The tabular values of point i are then displayed at the outputs YXP (X value) and YYP (Y value). The index of point i is output at output YIP.

4.5.2.2 Configuring

For the "Manual mode", only the TAB and/or TAB_D have to be configured depending on whether tabular values, data type REAL and/or DINT have to be managed. Each table may only contain values associated with one data type. If several tables having different data types are to be managed, then an TAB or TAB_D must be configured for each table.

The function blocks TAB and TAB_D should be configured in the same sampling time of 32ms. The following connection (I/O) settings are required:

AUT =	0 (automatic mode de-activated)
NP =	[specifies the table size]
XP =	[enters the X values]
YP =	[enters the Y values]
IP =	[enters the value pair to be changed]
TVL =	1 (to activate the table after all of the values have been entered)
WR =	1 (to transfer the value pair which was entered in the table)
RD =	1 (to display the value pair, specified under IP, at outputs YXP and YYP)

NOTE

If, in the "Manual mode" the CTS connection is set to "0" when initializing (CTS=0; AUT=0), then it is no longer possible to changeover into the "Automatic mode: Memory card" (CTS=0; AUT=1).
If the CTS connection is set to "0" while initializing, and the "Automatic mode: Memory card" is activated (AUT=1), then it is possible to subsequently changeover to "Manual mode" (CTS=0; AUT=0). The table, saved on the memory card, can then be processed in the "Manual mode".
If, after this, a change is made back to "Automatic mode: Memory card" (CTS=0; AUT=1), this no longer has any effect, because it is only activated during the initialization operation.
If a communications interface is configured at the CTS connection, it is possible to toggle, as required between "Manual mode" and "Automatic mode: Communications".

4.5.3 Automatic mode: Communications

4.5.3.1 Application with an S7 control and SIMATIC FM 458 application module

Transferring tabular values

The following prerequisites must be fulfilled in order to successfully transfer tables:

- The function blocks TAB and/or TAB_D must be configured in the FM 458 application module corresponding to the configuring specifications for "Automatic mode: Communications" (A detailed explanation is provided in Section "Configuring for S7 control and SIMATIC FM 458 application module").
- The X and Y values of a table in a DB must always be present alternating. There must be a Y value for each X value, so that the number of values in a data set is always an integer number.

In order to start data transfer, inputs REQTAB and REQDB at WR_TAB must be set to 1. The tabular values of the DB, specified at input DBNUM at WR_TAB can then be transferred.

The actual number of transferred data blocks is always displayed at the CNTTEL output of the WR_TAB.

The number of data blocks is displayed at the TABTEL output of the WR_TAB, which is required until the complete contents of the DB are transferred to the SIMATIC FM 458 application module.

If the tabular values have been completely entered in the specified DB, or if it involves the last partial transfer of a table (sub-set of a table), which does not “fit” completely into a DB, then before starting the transfer, input LASTDB of the WR_TAB should be set to 1. This means that the SIMATIC FM 458 application module is signaled at the end of the data transfer. The STATUS output of the WR_TAB then changes from 2 to 0.

NOTE All of the tabular values, which are located in the DB, specified at the DBNUM input of the WR_TAB, are always transferred.

Table too large for a DB

If the table is too large for a data block, then the tabular values are split-up into individual sub-sets for transfer. The procedure is as follows:

To start, the first table section is written into the DB and is then transferred as described above. The LASTDB input of the WR_TAB remains at 0. The STATUS output of WR_TAB stays at 2 during data transfer and then changes, at the end of the table sub-set transfer (partial transfer) from 2 to 1.

The old tabular values in the DB should then be overwritten with the following tabular values. Once this has been completed, at WR_TAB the REQDB input should be again set from 0 to 1 to activate the next table sub-set transfer.

This procedure should be repeated until all of the tabular values have been transferred.

At the last sub-set transfer, input LASTDB of the WR_TAB should be set from 0 to 1. This signals the SIMATIC FM application module that data transfer has been completed. The STATUS output of the WR_TAB then changes from 2 to 0.

NOTE

If there is adequate user memory available, the table can also be saved in several different DBs. In this particular case, for each table sub-set transfer, only the matching DB number at the input DBNUM of the WR_TAB has to be specified. However, it should be ensured that the DBs are transferred in the correct sequence, so that all of the tabular values are transferred in an increasing sequence.

Data transfer duration

The time taken to transfer the tabular values depends on the following factors:

- Number of tabular values
- Size of the data blocks
- Sampling time of the TAB and TAB_D
- WR_TAB processing time

In each cycle, a telegram with 56 tabular values is transferred, from the control to the SIMATIC FM 458 application module.

The time taken for a table to be transferred can be calculated as follows:

Duration of the data transfer =	[No. of tabular values / 56] * cycle time of the slowest FB (i.e. TAB, TAB_D or WR_TAB)

The time taken for the data to be transferred via the P bus is not relevant for this estimation, as this data transfer time is generally less than 1ms and generally, the function blocks TAB and TAB_D are configured in sampling times which are greater than 32ms.

If a table is distributed over several data blocks, the time required increases. The reason for this is that in addition to the time taken to transfer the tabular values, which can be determined using the formula above, the user has to manually make the changes described above.

4.5.3.2 Configuring for S7 control and SIMATIC FM 458 application module

The following function blocks must be configured for the coupling between an S7 control and an SIMATIC FM 458 application module via P bus:

- SIMATIC FM 458 application module:
  - TAB (for REAL data type) and/or
  - TAB_D (data type DINT)
  - @CPB (P-bus coupling, central block)
- S7 control:
  - WR_TAB

Each table may only contain values associated with one particular data type. If several tables with different data types are to be managed, then an TAB or TAB_D must be configured for each table.

WR_TAB is used to transfer the tabular values from SIMATIC DB to function blocks TAB and TAB_D. The tabular values are transferred using a data telegram. When the last data telegram has been transferred, the TAB or TAB_D is automatically signaled that all of the tabular values have been transferred and that the table should be activated. WR_TAB receives a checkback signal as to whether activation was successful or not. After the table was successfully activated, its address is output at the TAB output of the TAB or TAB_D.

TAB and TAB_D

TAB and TAB_D should be configured as follows:

They should be configured in a sampling time greater than or equal to 32ms. The following connection settings are required:

CTS =	[name of the configured communications interface]
AUT =	1 (automatic mode activated)
US =	[channel name.address stage1] (address data for receive)
MOD =	[data transfer mode] (H=Handshake; R=Refresh; S=Select; M=Multiple)
TFT =	[monitoring time in milliseconds] (maximum telegram failure time while receiving tabular values)
NP =	[specifies the maximum table size]

NOTE If a communications interface is configured at the CTS connection, it is possible to toggle, as required between "Automatic mode: Communications" and "Manual mode".

WR_TAB

The following connection settings should be configured at WR_TAB:

LADDR =	[specifies the logical address of the SIMATIC FM 458 application module]
RECNUM =	[specifies the data set number for the read and write channels. This must be identical with "Address stage1" at the US connection of the TAB or TAB_D.]
DBNUM =	[specifies the data block number]

4.5.3.3 Inserting tabular values in the data block

In order to be able to transfer tabular values to a SIMATIC FM 458 application module, they must be available in a data block (DB). The DB should be programmed on the control side.

There are two ways of generating a DB with the required tabular values:

- Generating a new DB in STEP7 and manually entering the tabular values in the application "LAD/STL/CSF"
- Importing tabular values from an existing table (e.g. MS Excel) as external source in STEP7

4.5.3.3.1 Manually entering tabular values

In this case, it involves the simplest method of providing tabular values in a DB. It is realized by entering the initial (starting) and actual values of the individual table values manually in a newly generated DB in the application "LAD/STL/CSF". The steps required will now be explained.

NOTE

The initial value is any value which can be defined for every tabular value. It is only used if there is no actual value specified for the associated tabular value.
The actual value is that value which is made available as tabular value in the configured software. The required tabular values should be specified here.

(1) Generating a new DB under STEP7

To start, a new DB should be generated under STEP7. In this case, the "Blocks" folder is selected in the appropriate S7 program and in the context-sensitive menu, the entry "Insert new object → data block" is selected.

The procedure is shown in the following diagram:

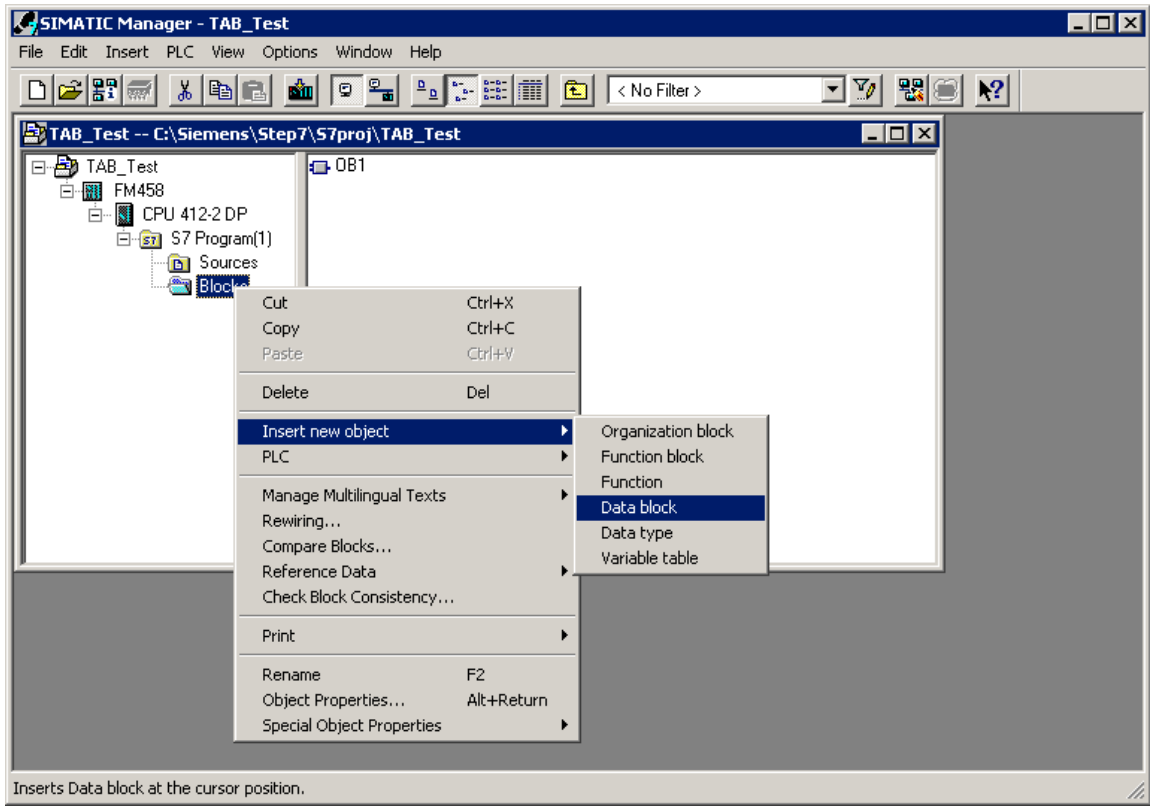


Fig. 4-19 Generating a new data block under STEP7

(2) Opening the new DB

The next step is to open the newly generated DB by double-clicking with the application "LAD/STL/CSF". "DB Editor" is the tool which is used to generate it and only one "Data block" is generated.

The following diagram illustrates the selection when opening a new DB:

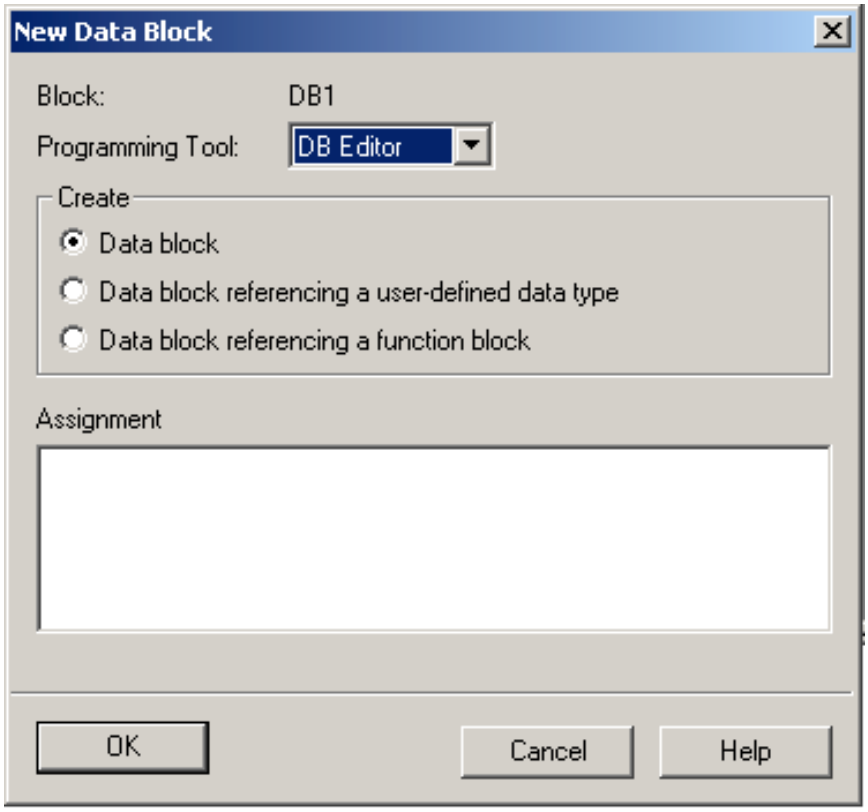


Fig. 4-20 Making a selection when generating a new DB

The opened, new DB is illustrated in the following diagram:

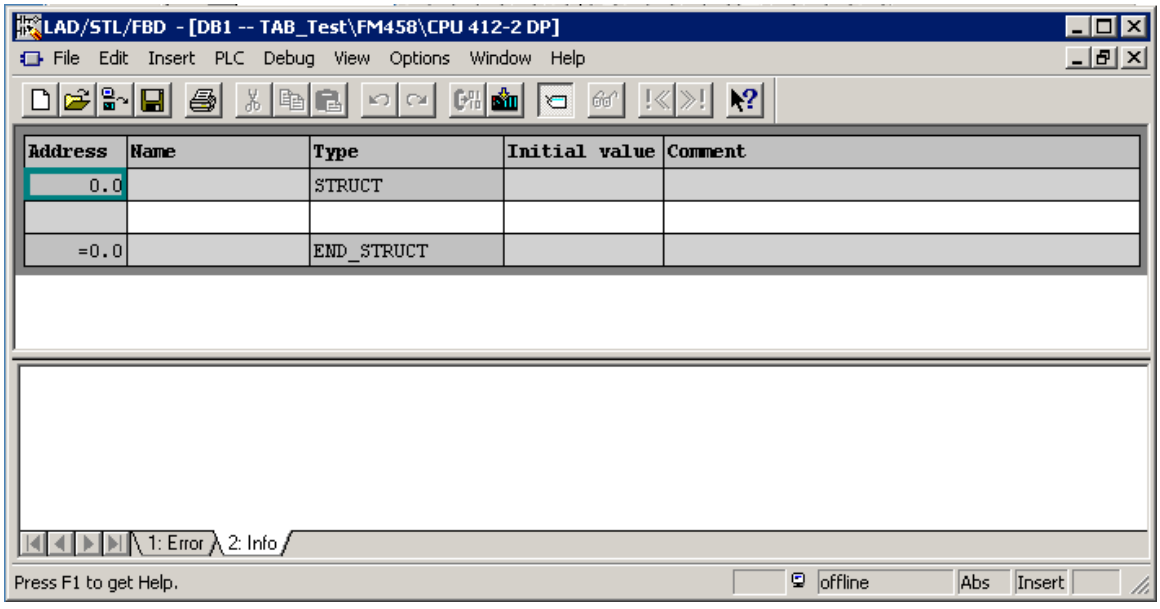


Fig. 4-21 Newly generated DB in the application "LAD/STL/CSF"

(3) Entering the tabular values

The required tabular values can now be entered. It should be ensured that the X and Y values are entered, alternating.

To start, the data type, used in the table, should be entered (REAL or DINT). In this case, the name is always "Data type", "WORD" type and initial value for data type REAL "W#16#1", for data type DINT "W#16#2".

Then, for each individual tabular value, the name, data type ("Type" column) and value ("Initial value" column) should be entered.

The procedure when entering tabular values, data type REAL, is shown in the following diagram:

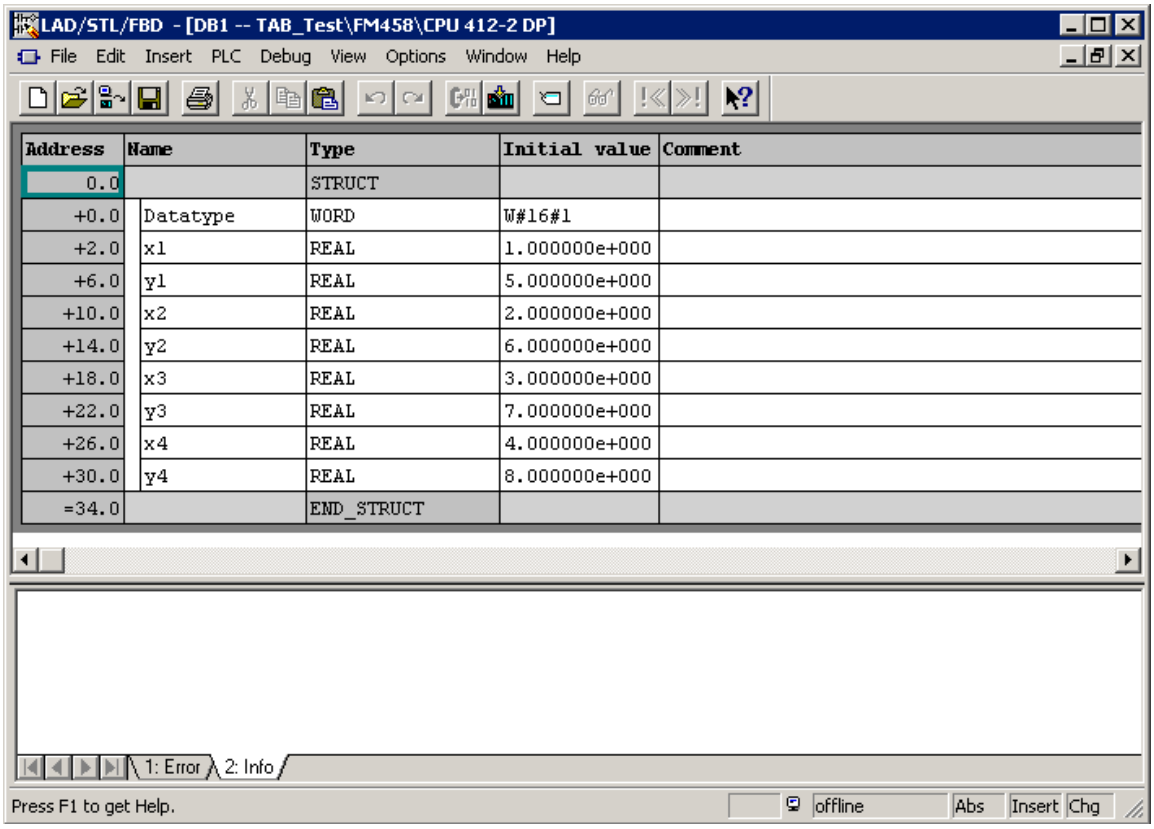


Fig. 4-22 Manually entered tabular values in the "LAD/STL/CSF" application

HINWEIS Only values associated with the same data type may be included in a table. For this reason, specifying an ARRAY is an effective way of entering data. This means that the data type doesn't have to be specified each time.
Refer to the online help of the application "LAD/STL/CSF" - especially "Help for STL" for the procedure to make entries for an ARRAY type.

(4) Saving the DBs

After the tabular values have been completely entered, the DB can be saved under "File → Save".
The tabular values are then located in the DB for transfer.

4.5.3.3.2 Importing tabular values

The tabular values, provided in the DB, can also be imported from an external source, e.g. an MS Excel table. However, the following points should be observed for error-free import:

- The source file of the table must have a specific format
- The source file must be linked-in as external source file under STEP7
- A new DB is generated from the external source file
- The necessary points and steps, required for the import operation, will now be explained.

Table format

In order to import an existing table (e.g. generated using Excel) into the DB, it must be compliant with a specific format syntax:

- The table must contain a header, which contains information about the name of the DB and the version.
- Information about the structure and the data type of the tabular values should then be specified.
- The tabular values are then specified (as initial values).
- It should be observed that X and Y values must always be specified, alternating.
- The table should be saved with the *.AWL extension.
- The table can then be used as external source file.

HINWEIS The *initial value* is any value which can be defined for each tabular value. It is only used if an actual value is not specified for the associated tabular value.
The tabular values are exclusively defined as *initial values*. *Actual values* are not used.
This significantly reduces the file size and in turn, the required memory.

An example of a table with four X and four Y values, data type REAL is shown in the following diagram:

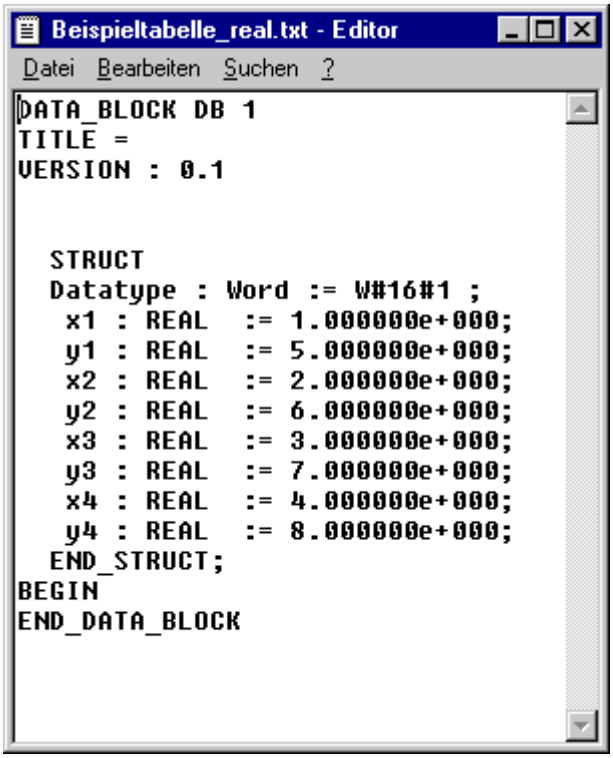


Fig. 4-23 An example of a table with values, data type REAL

An example of a table with two X and two Y values, data type DINT is shown in the following diagram:

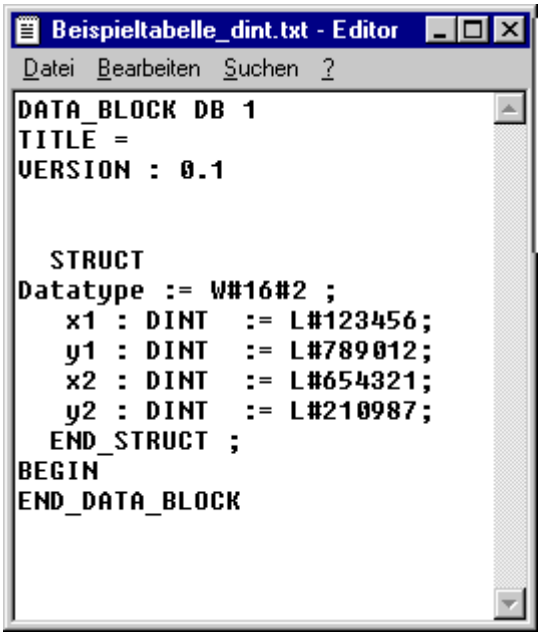


Fig. 4-24 An example of a table with values, data type DINT

From Excel to STL

The following sections explain, using examples, how to re-format an Excel table to obtain the required table format.

The file example, shown in the following diagram, is formatted step-by-step corresponding to the specifications of the required table format.

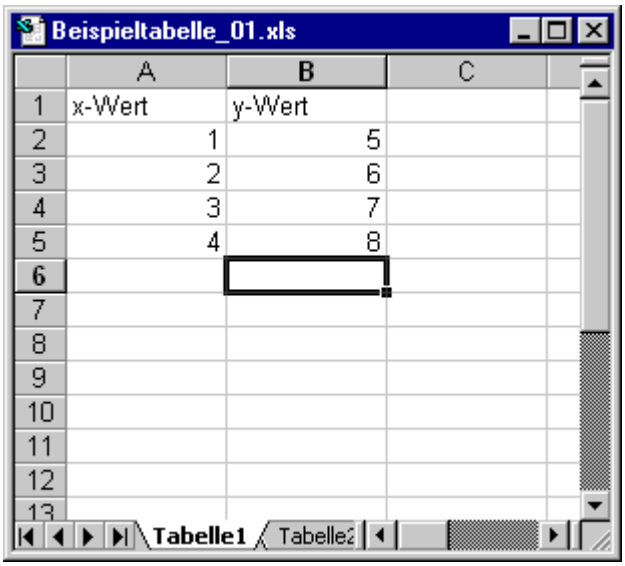


Fig. 4-25 An example of a table in MS Excel

(1) Header

Initially, the required header is inserted. To do this, 5 lines are inserted at the beginning and the following data is entered:

- DATA_BLOCK DB 1 [number of the DB]
- TITLE = [enter as required]
- VERSION : 0.1 [version data]

The Excel table with inserted header is shown in the following diagram:

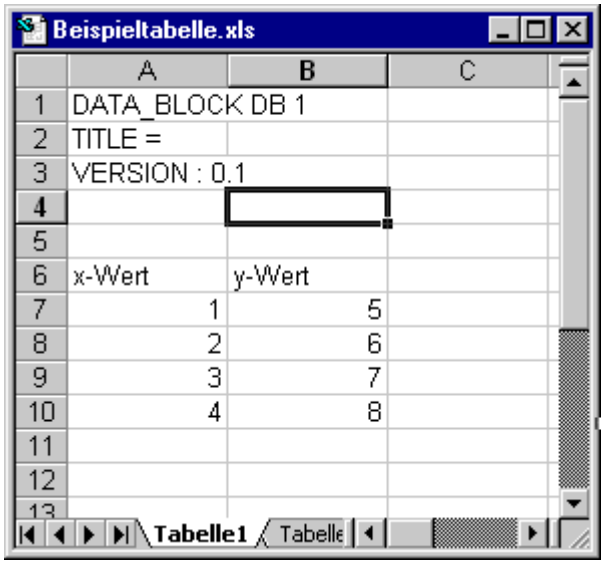


Fig. 4-26 An example of a table in MS Excel with inserted header

(2) Insert structure and tabular values

In a next step, the structure of the tabular values and the values, specifying the data type, are inserted. In this case, two lines plus an initial and end line are inserted for each value pair. Furthermore, a line is inserted at the start to specify the data type used.

The start of the structural data is displayed in the starting line with the "STRUCT" entry. The data type, used in the table, is specified in the following line ("W#16#1" for data type REAL, "W#16#2" for data type DINT).

This is followed by the structural data and tabular values for the individual value pairs, where X and Y values are always entered alternating. The tabular values are specified corresponding to the data type used (in this case REAL). The end of the structural data is displayed in the final line with the "END_STRUCT;" entry.

Finally, only the data for the data section of the actual values has still to be specified ("BEGIN" and "END_DATA_BLOCK"). As the tabular values already have the structural data in the starting (initial) values, it is not necessary to specify the individual actual values.

The Excel table with inserted structural data and tabular values is shown in the following diagram:

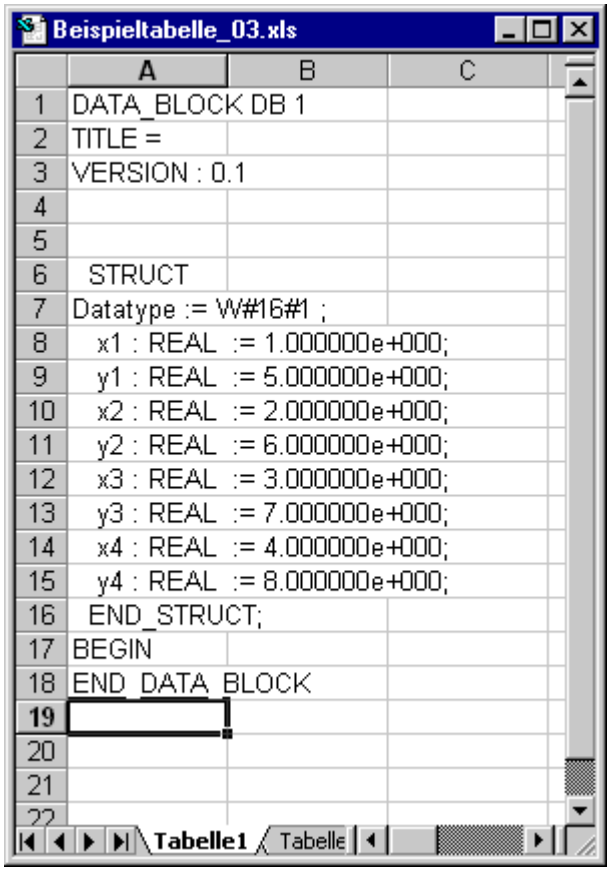


Fig. 4-27 Example of a table in MS Excel with inserted structural data and tabular values

(3) Saving as STL [AWL] file

Finally, the correctly formatted file only has to be saved as text file with the extension *.AWL. In this case, the following should be selected in MS Excel "File → Save as...". "Formatted text (separated by blanks) (*.prn)" file type should be selected and the table example should be saved under a freely selectable name and location.

"Save as" window in MS Excel with the appropriate selection is shown in the following diagram:

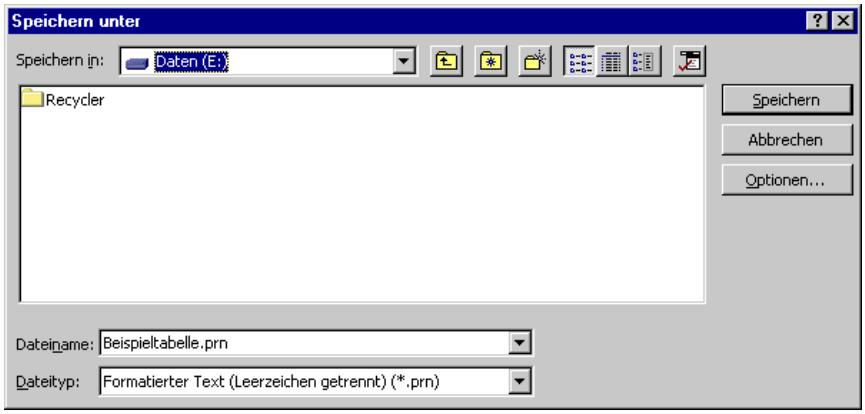


Fig. 4-28 An example of a table in MS Excel saved as text file (.prn)*

After the file has been saved, the file type should be changed from *.prn to *.awl. This file can then be opened with any text editor.

The following diagram shows the table example as STL [AWL] file, opened in the standard Windows text editor:

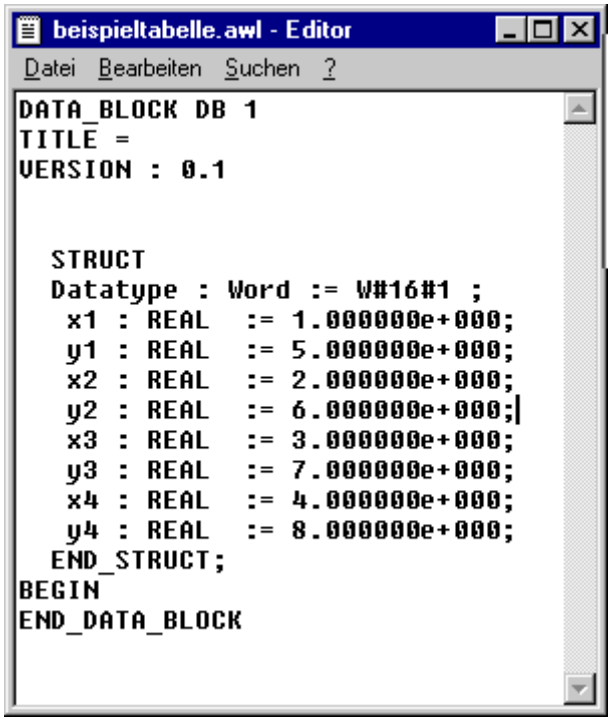


*Fig. 4-29 Table example, saved as *.awl file, opened in the text editor*

This file can only be used as external source file in STEP7 for a DB.

Incorporating the table as source file

Using the file example "BEISPIELTABELLE.AWL", generated above, the individual steps to incorporate an externally generated table in a DB will now be explained.

HINWEIS

In addition to specifying the tabular values, it is especially important to specify the name of the DB. A DB is subsequently generated using the name specified in the file.
In the above file example, "DB1" is specified as DB name in the first line. (refer to Fig. 10)

Now, an external source is inserted in the STEP7 configured software in the S7 program under "Sources". After selecting "Sources", the context-sensitive menu can be called-up by clicking in the righthand partial window with the righthand mouse key. An external source should be inserted here as new object.

The procedure is shown in the following diagram:

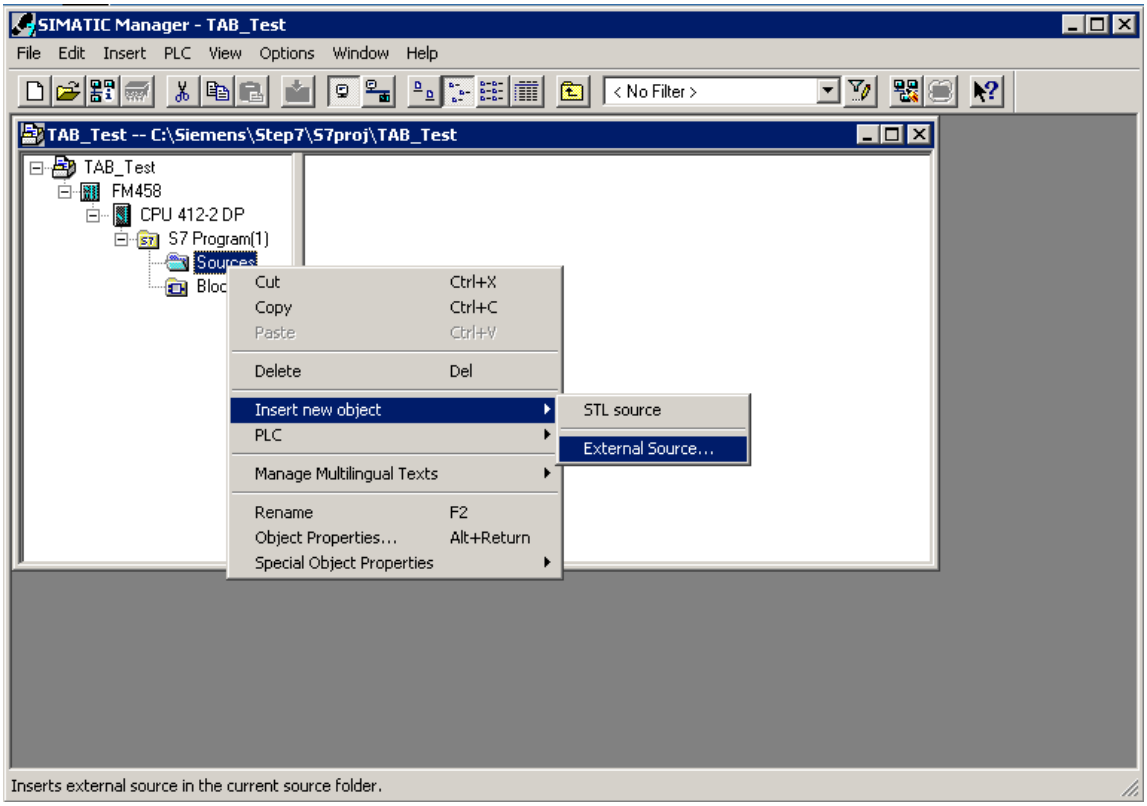


Fig. 4-30 Inserting an external source in STEP7

The STL [AWL] file, generated above, is selected as source file. The following diagram shows the file selection window:

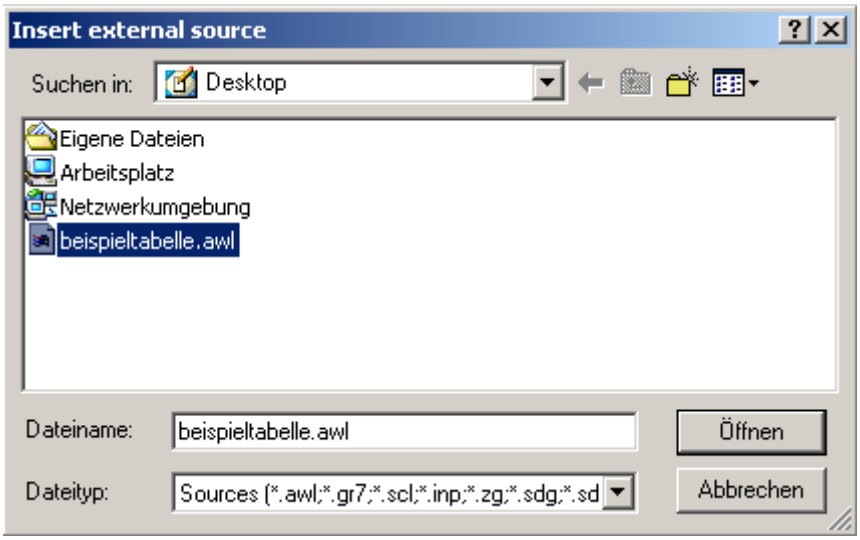


Fig. 4-31 Selecting the file to be inserted in STEP7 as external source

The selected file is opened (in this case: BEISPIELTABELLE.AWL). It now exists as source file in the configured software under "Sources". It is selected there and is opened.

The file example, available under "Sources" and its context-sensitive menu is shown in the following diagram:

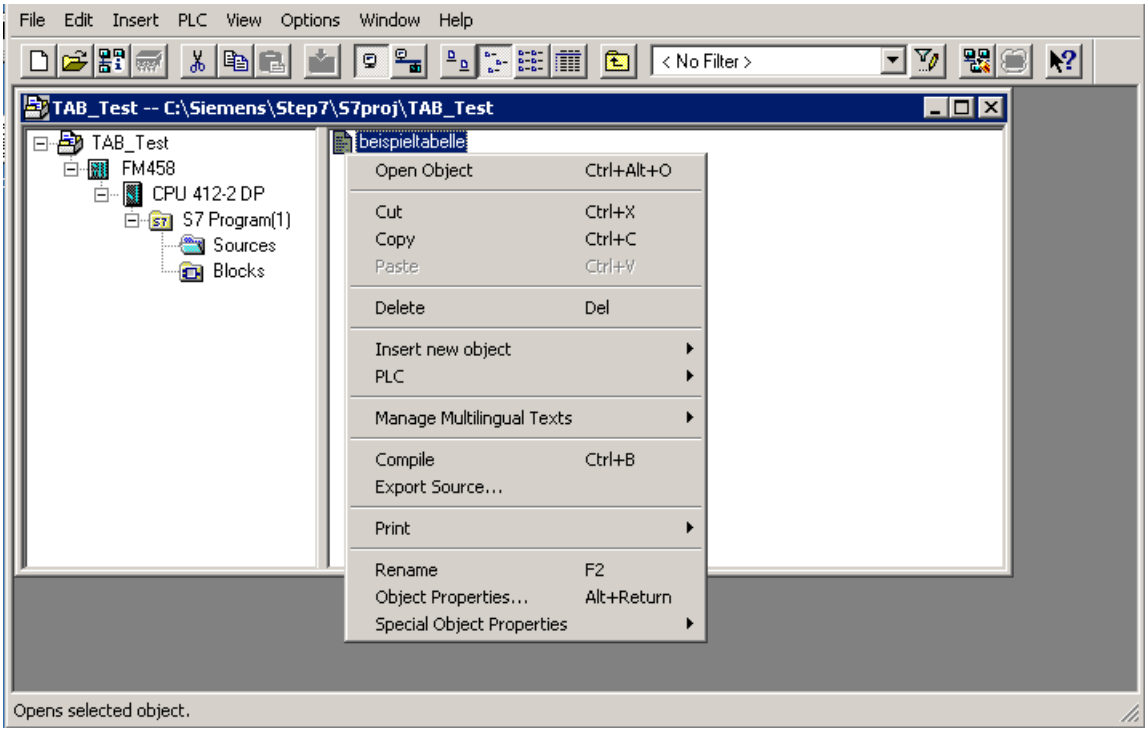


Fig. 4-32 Generated source file in STEP7

After the file has been opened, it can be edited in the "LAD/STL/CSF" program. There it can be compiled via "File / Compile".

The procedure is shown in the following diagram:

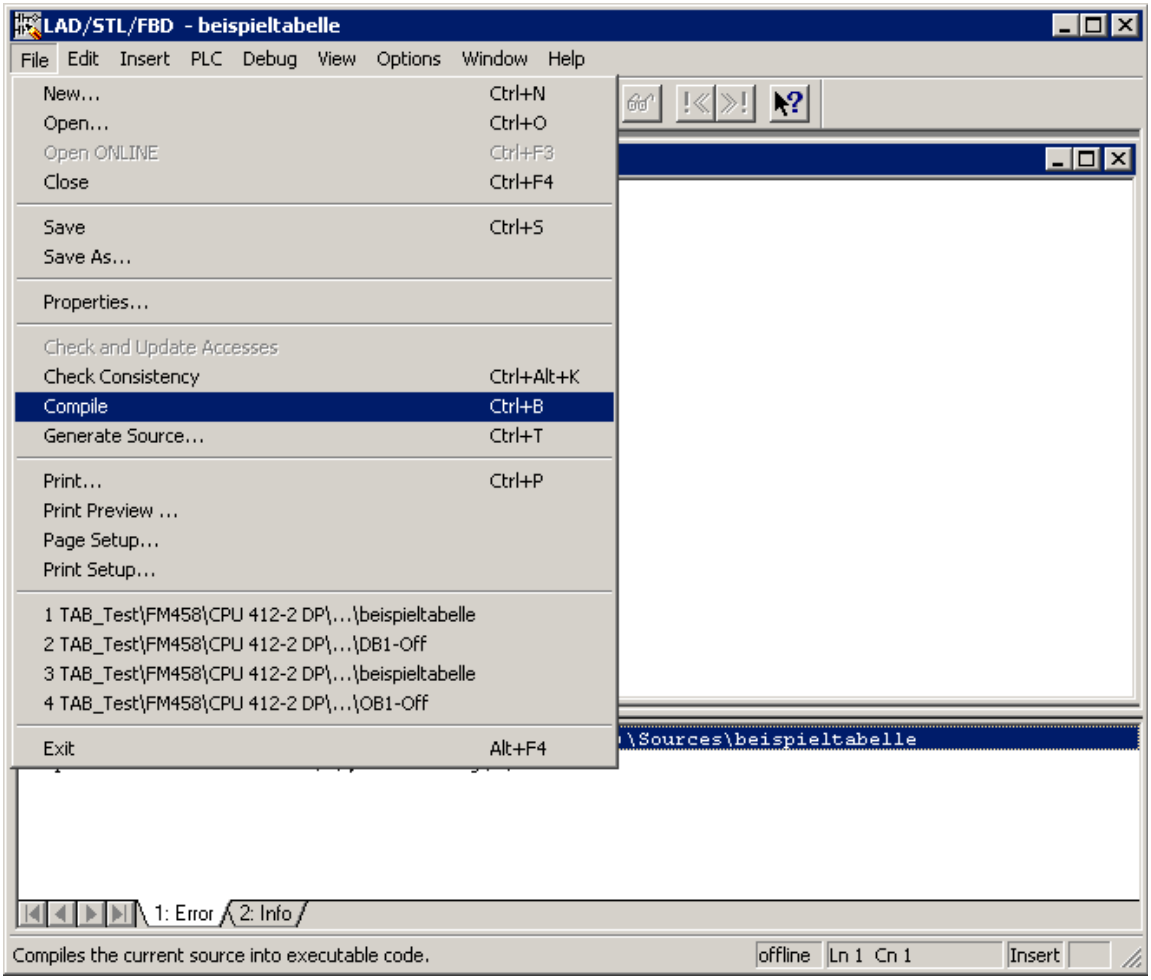


Fig. 4-33 Compiling the source file in the "LAD/STL/CSF" application

After the file has been successfully compiled, a new DB is available in the configured software. The name of the DB corresponds to the name specified in the header line of the file.

The following diagram illustrates the newly generated DB in STEP7 configured software under "Blocks":

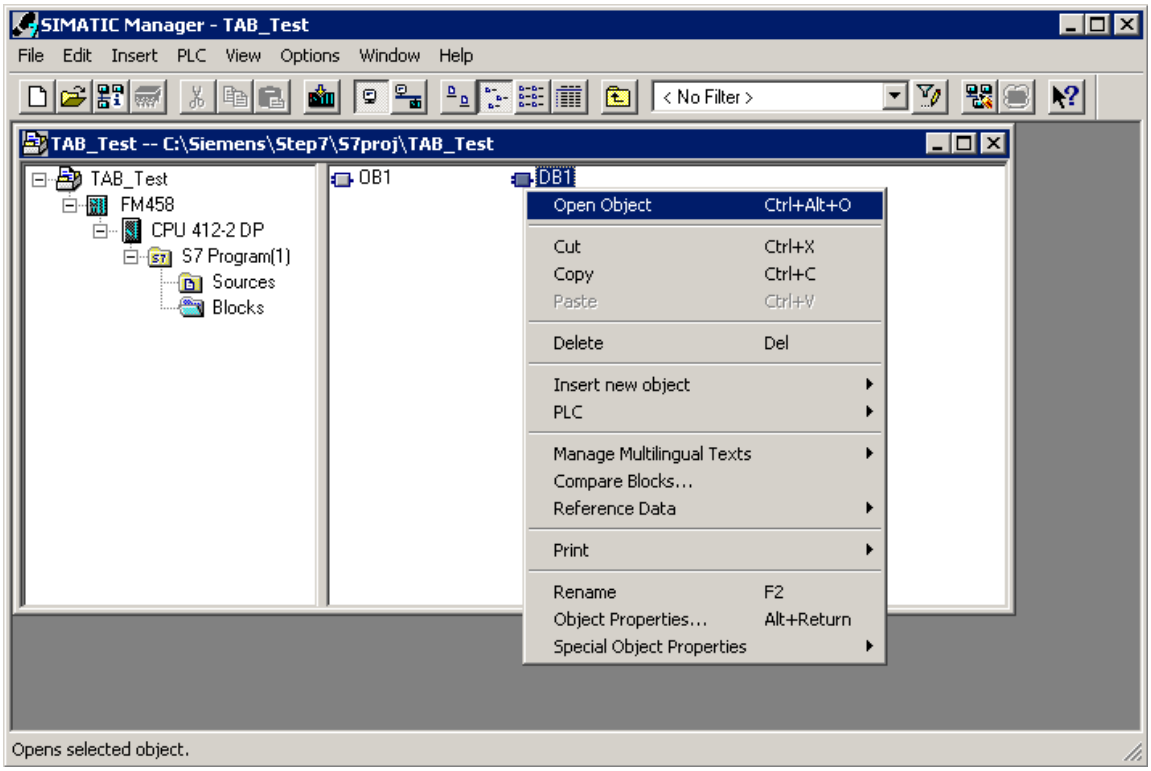


Fig. 4-34 Newly generated DB after compiling the source file

In order to check the contents of the DBs, it can be opened in the "LAD/STL/CSF" program. "Data view" should be selected in the "View" menu to display the initial (starting) values as well as the actual values.

The contents of the opened DB is illustrated in the following diagram:

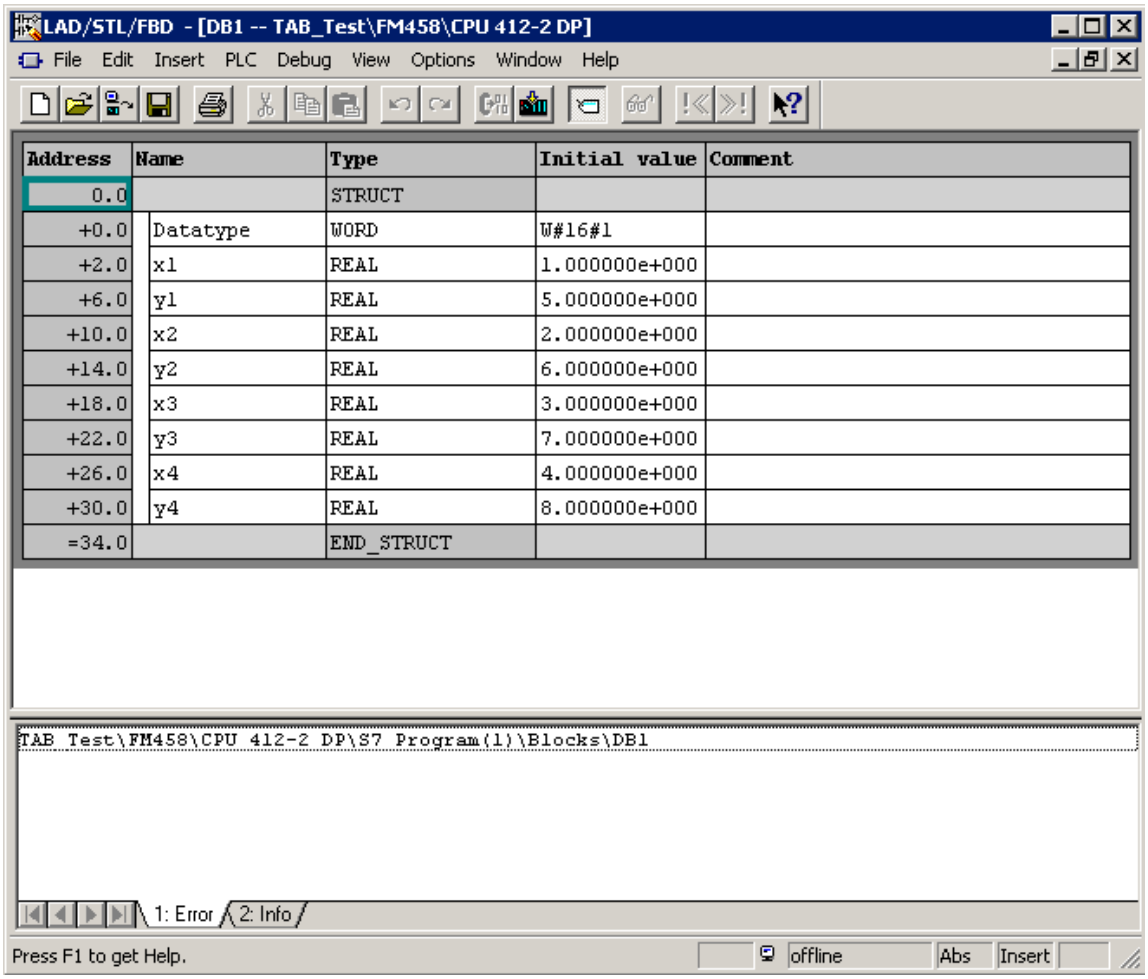


Bild 4-35 Contents of the newly generated DB in the "LAD/STL/CSF" application

4.5.3.3.3 Subsequently downloading tabular values into a DB

If tabular values are to be subsequently downloaded into the DB, because the table is too large and there is not sufficient user memory for several DBs, then the table should be transferred to the SIMATIC FM 458 application module in several sub-sets of the table. To do this, the table must be split-up into sub-sets of the table. The size of the individual sub-set tables should be selected so that the user memory of the S7-CPU is not exceeded. The individual table sub-sets are then transferred one after another.

HINWEIS It is especially important that the individual table sub-sets are transferred in the sequence of the value pairs. If they are transferred in the incorrect sequence, then the tabular values will not be correctly available in the configured software.

There are two possibilities:

- Manually enter the individual tabular parts at the DB in the "LAD/STL/CSF" application and then transfer this part of the table
- Generate individual source files with different names for each table sub-set and after being successfully linked-into the DB one after the other, then transfer

Manual entry

In order to subsequently download tabular values into a DB manually, the following steps should be carried-out:

- The appropriate DB should be opened by double-clicking in the "LAD/STL/CSF" application.
- The existing tabular values should be replaced by entering the value of the subsequent tabular section.
- The DB should be saved.
- The values of the table sub-sets can now be transferred.

Generating several source files

The following steps have to be carried-out when subsequently downloading tabular values into a DB by generating several source files:

- The same DB name should be specified in the header of the individual source files (*.AWL).
- The individual files may not exceed the memory size of the DB.
- The file names are best numbered in an increasing sequence.
- The individual files are now linked-in as source files as described above. However, they are still not compiled.
- The first source file is compiled and the tabular values, now available in the DB, transferred.
- The second source file is compiled so that its tabular values are now available in the DB. These are now transferred to the S7 control system.
- Analog to this, the other source files are compiled and transferred one after the other.
- After the last table sub-set has been transferred, the LASTDB connection should be set from 0 to 1. This signals that the table has been transferred.

4.5.3.4 Structure of the data telegram for TCP/IP or DUST1 connection

If the communications link involves a TCP/IP or DUST1 coupling, then the data telegram structure must be carefully observed. This is described in the following. The data telegrams are "generated" using the function blocks CTV and CRV.

The data telegram is defined so that all of the tabular values can be transferred in a data block as well as in several data blocks.

The structure of a data block is shown in the following table:

Data type	Description
char [4]	Telegram ID Each table telegram is identified with the "TAB0" ID
u_int16	Telegram commands (bit-coded) 1: New table (rising edge, from 0 -> 1) 2: End of table
u_int16	Data format (REAL=1, DINT=2)
u_int32	No. of the actual data block
u_int32	No. of tabular values (X and Y values) The number of values must always be an even number. This means that always the same number of X and Y values are transferred.
u_int32 [56] / float [56]	Array with tabular values. (X and Y values, always alternating)

The TAB or the TAB_D sends an acknowledgement to the sender for each data block received.

The structure of the acknowledge telegram is shown in the following table:

Data type	Description
char [4]	Telegram ID Identifies each table telegram with the "TAB0" ID
u_int32	No. of the actual data block
u_int32	Status / error numbers 0xB210 OK (data block is o.k.) .....

HINWEIS New table data is now transferred into the inactive table if the "New table" command is set.
After the "End of table" command has been received, all additional table data are rejected until the "New table" command is received.

4.5.4 Automatic mode: Memory card

Table values can be combined to form components using the D7-SYS additionalComponentBuilder (this is included in D7-SYS V5.2 plus SP1). These components can be downloaded as additional objects on the memory card. From there, they are read-out using the TAB or TAB_D function blocks.

One or several table files are imported in the D7-SYS additionalComponentBuilder, which then combines these files to form a component file (download file), which can then be downloaded onto the memory card.

The D7-SYS additionalComponentBuilder (aCB) does not check the contents of the files. The tables are an exception to this rule. The contents of these table files are checked. If the table file has an erroneous structure, then aCB immediately flags this.

The procedure from generating a table file up to configuring the function blocks is explained in the following sections using an example.

4.5.4.1 Generating a table file in the csv format

The table values are generated as required using a table calculation program (e.g. Excel).

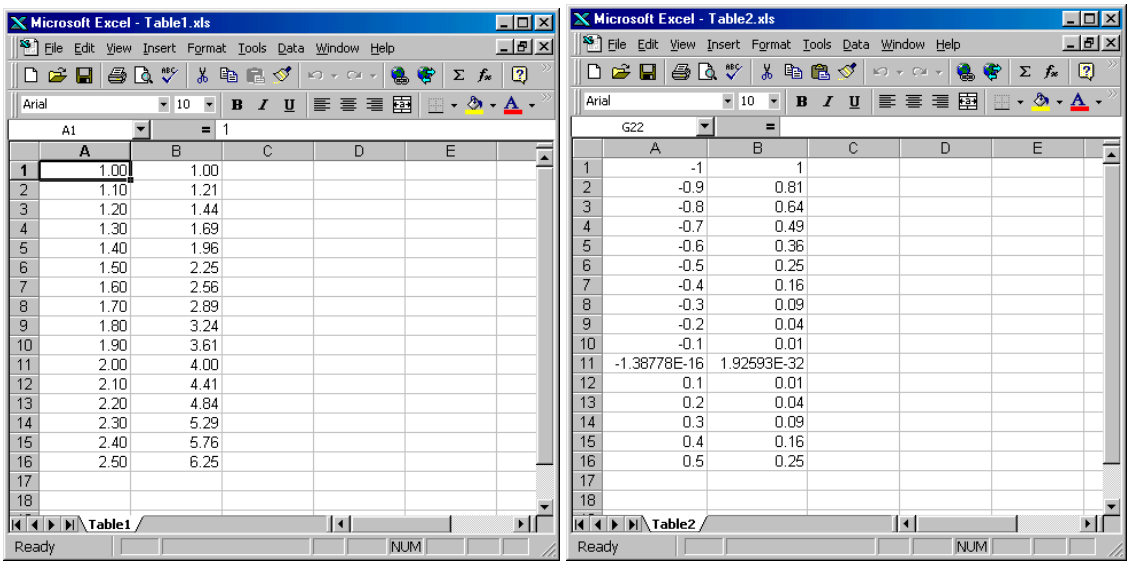


Fig. 4-36 Tables values in Excel

Conditions

The table files must fulfill the following conditions:

- A table file may only comprise two columns – if additional columns are included in the table, an error message is displayed in a dialog window.
- Both of the columns must contain the same number of values. If this is not the case, then the D7-SYS additionalComponentBuilder displays an error message in a dialog window and the table values are rejected.

The D7-SYS additionalComponentBuilder expects the following data format:

- [+/-] xxx.yyy – real value, decimal places are specified using a „.“ (e.g. 145.123)
- [+/-] xxx,yyy – real value, decimal places are specified using a „,“ (e.g. 145,122)
- [+/-] xxx.yyyE+/-mm – real values shown as an exponent, decimal places are specified using a „.“ (e.g. 145.122E+12)
- [+/-] xxx,yyyE+/-mm – real values shown as an exponent, decimal places are specified using a „,“ (e.g. 187,122E+12)

For the „Table DINT“ type description:

- [+/-]xxx – Integer or double integer (e.g. 145)

The following conditions still apply for the table files:

- ASCII files
- The table columns are separated using a semicolon or tab character
- Lines are separated using a line break or semicolon

Saving tables

Tables, which are generated using MS Excel and are saved in the *.csv format or as "Text (Tabs separate)“ fulfill these conditions.

The following diagram shows two example files with table values which were saved in the csv format:

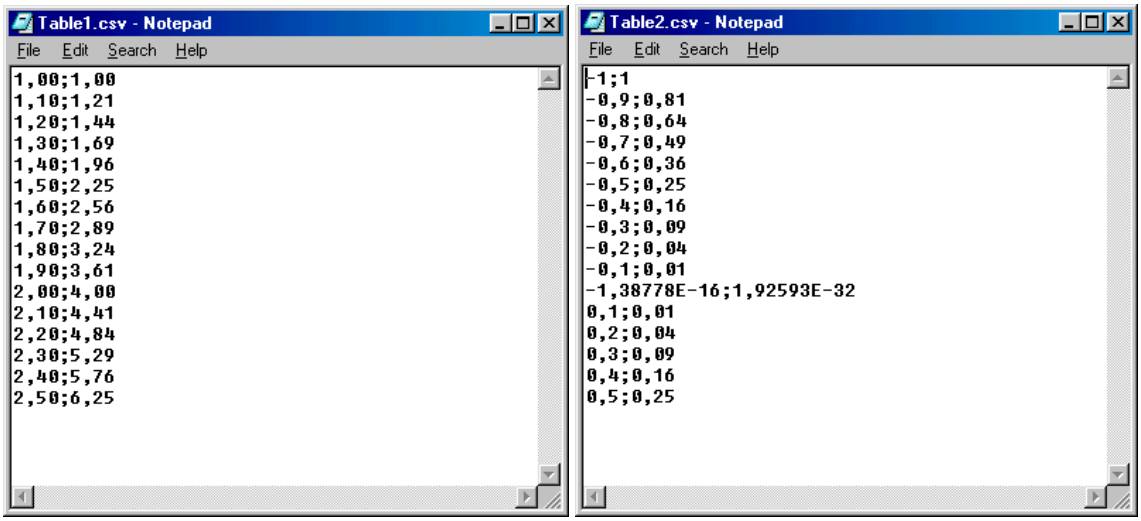


Fig. 4-37 Table values which were separated using semicolons (.csv format)*

4.5.4.2 Working with the D7-SYS additionalComponentBuilder

After the table files were saved in the csv format, they can be imported in the D7-SYS additionalComponentBuilder.

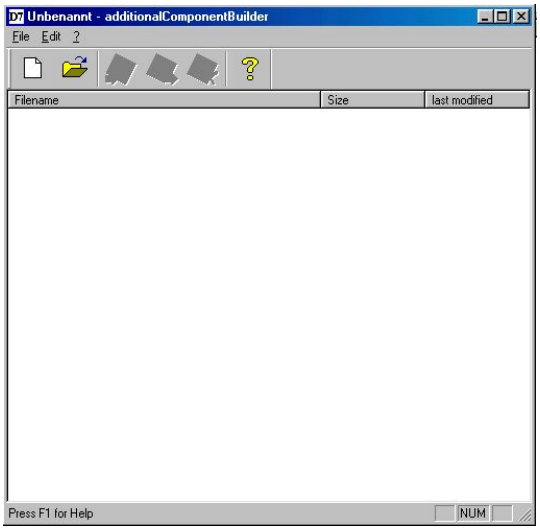


Fig. 4-38 D7-SYS additionalComponentBuilder

In the next step, a new component file is set-up with  . To start, the properties are specified in the following dialog field.

New component

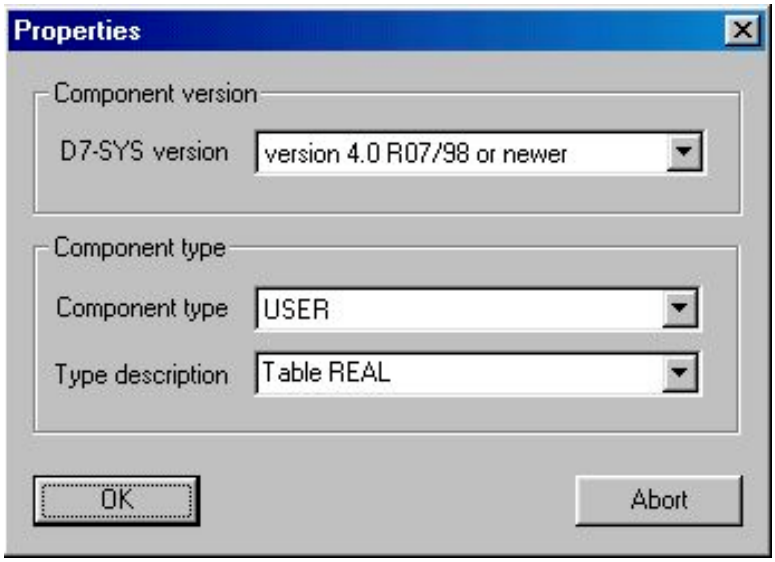


Fig. 4-39 Setting the properties

The following settings should be made:

These properties cannot be changed at a later time and have a gray background.

- **D7-SYS version**
  List box, in which the version is specified for which the components should be generated

- **Component type**
  List box with the fixed entries "USER“, "IT1“ and "IT2“. “USER” is the default value

  The entries have the following significance:

  – USER = Component file generated by the user,
    e.g. table files

  – IT1/IT2 = System component file for ITSP modules

- **Type description**
  List box with the “Table REAL” and “Table DINT” entries. "Table REAL“ is the default value for the “USER” component type. "Table DINT“ is used for tables in the DINT format.

  The entries have the following significance:

  – REAL table: Table file with REAL data type

  – DINT table: Table file with double integer data type

  A new type description can be entered in the list box and acknowledged using RETURN. This new type description is then transferred into the list box and can be selected from the list box the next time.

Saving

The new component file can be set-up after the settings have been completed.
The new component file is, as standard, set-up in C:\temp. If another memory path is specified, then when the program re-starts, this is used as standard memory path.

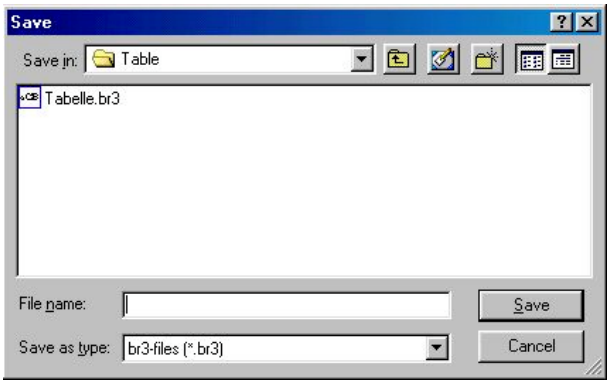


Fig. 4-40 Saving the new component file

Table files can now be added. A file selection window is opened using  with which the required table files can be selected.

NOTE

Only tables with a uniform value format can be included in a component with the "table" type description! This means that a REAL table only contains tables with REAL values.

The following diagram shows the contents of the D7-SYS additionalComponentBuilder after importing the two generated table files:

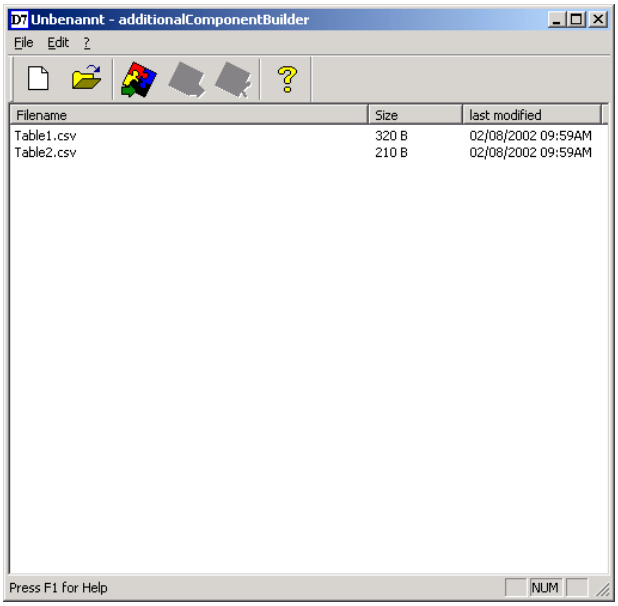


Fig. 4-41 D7-SYS additionalComponentBuilder with imported table files

Additional table files can be added or imported or deleted at any time. The D7-SYS additionalComponentBuilder automatically takes-over the management of the table files and saves the modified component files.

Opening

When opening existing components, "C:\temp“ is the standard search path of the D7-SYS additionalComponentBuilder. If another path is selected, when the program re-starts, this is used a standard search path.

4.5.4.3 Downloading

After the component file was set-up with the D7-SYS additionalComponentBuilder, it can be downloaded into the general download dialog box.

(1) Opening the download dialog box in D7-SYS with “target system→ Download”
Using this dialog box, the current configuring can download the optional components into a memory card (offline/online).

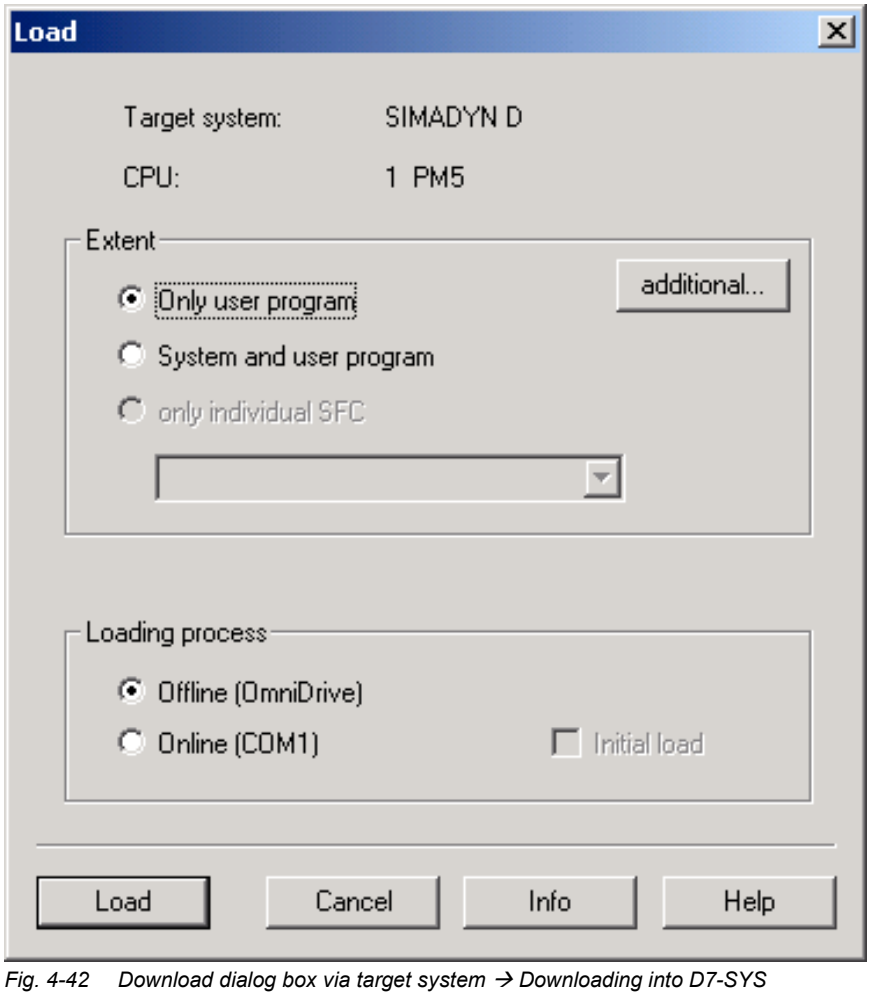


Fig. 4-42 Download dialog box via target system → Downloading into D7-SYS

(2) Opening the dialog box for optional components
A maximum of 2 components can be selected. A file can be selected for the selected components by clicking on the “NEW” button.

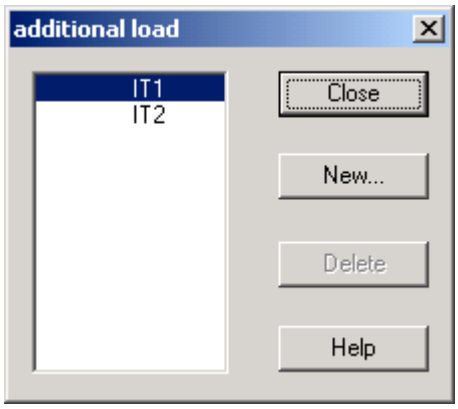


Fig. 4-43 Selection dialog box for optional components, e.g. table data

(3) A file selection dialog box opens to select additional components

The component file, previously created using the D7-SYS additionalComponentBuilder, is now assigned the component IT1 and during the next download operation, is written into the memory card.

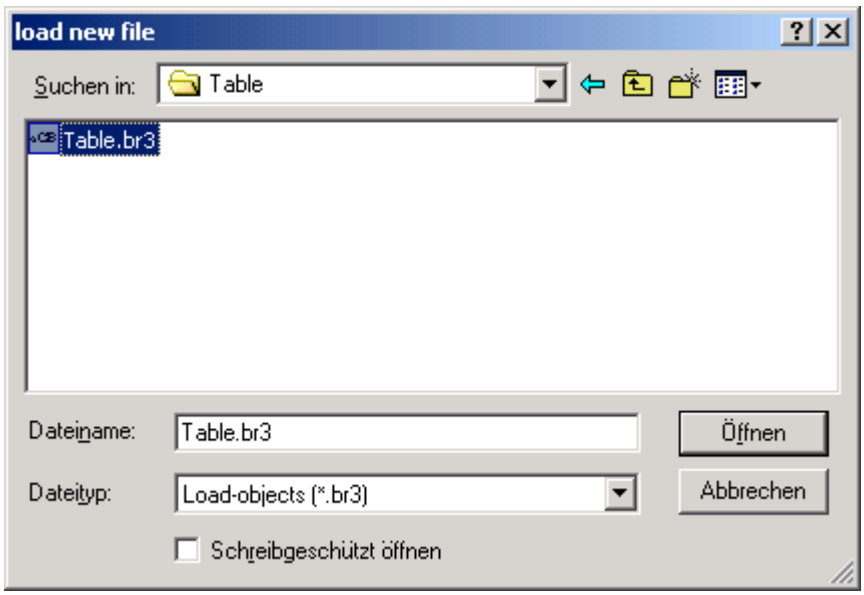


Fig. 4-44 Downloading a component file

4.5.4.4 Configuring the function blocks

For the "automatic mode, memory card" mode, only the TAB and/or TAB_D function blocks must be configured, depending as to whether table values, REAL data type and/or DINT data type have to be managed. Each table may only contain values of one data type. If several tables are to manage various data types, then a TAB or TAB_D should be configured for each table.

The TAB and TAB_D function blocks should be configured in a sampling time greater than or equal to 32ms. The following connection settings are required:

CTS=	0
US =	Not assigned
NAM =	Name of the table file (with file name extension which was defined when "saving", e.g. MS Excel)
AUT =	1 (automatic mode activated)

The configuring is shown in the following diagram:

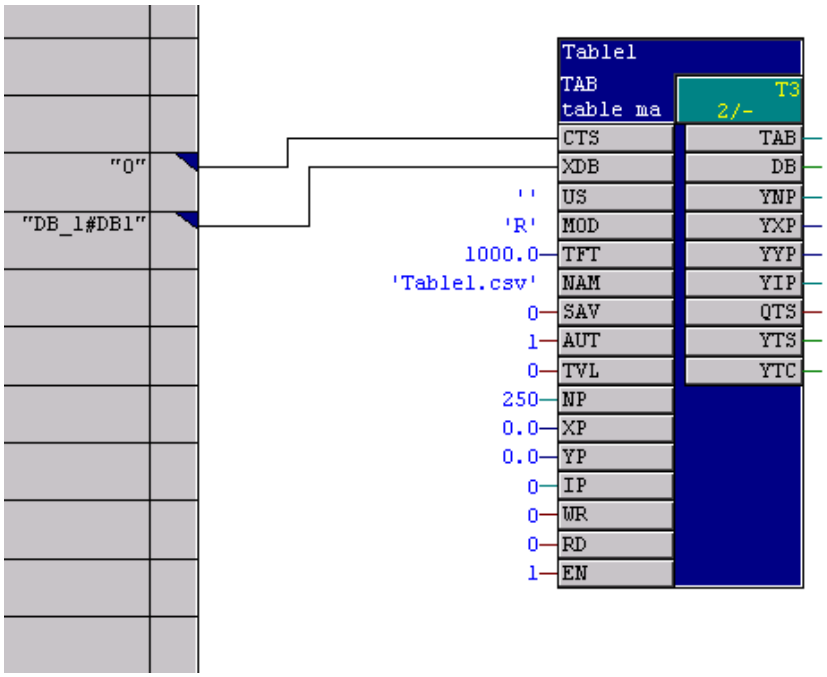


Fig. 4-45 Configuring the TAB function block

The table function blocks for 2 tables are shown in the following diagram. The table values, which are now managed by the function blocks, can now also be used by additional function blocks, e.g. FB TABCAM.

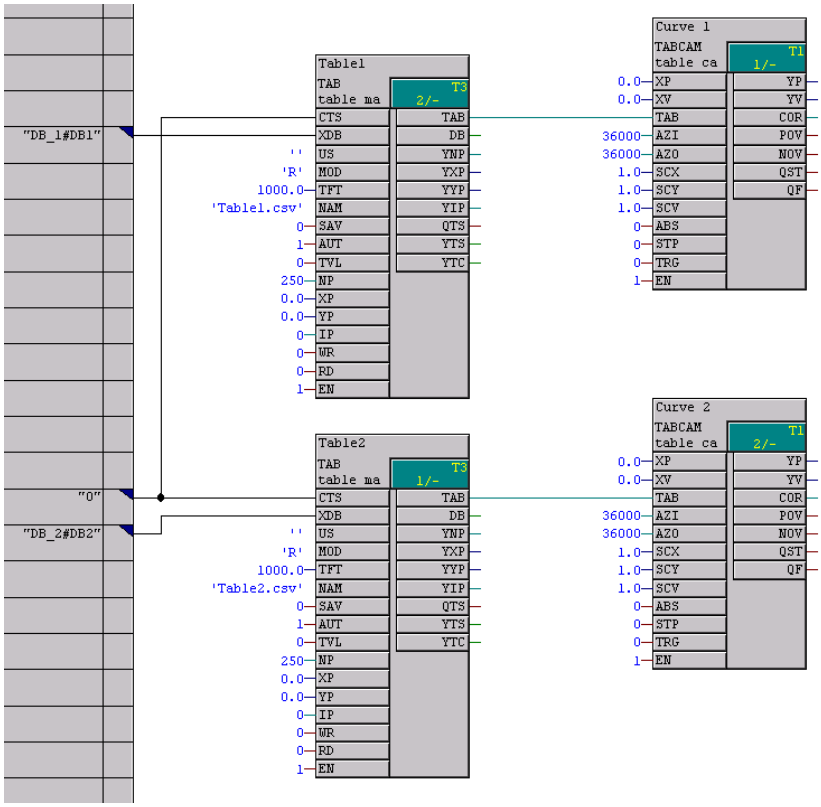


Fig. 4-46 Configuring example

4.6 Parameter access technique for D7-SYS

4.6.1 General description of the parameter functionalityinformation

By appropriately parameterizing using operator control devices for parameters at the block I/O:

- Reading values
- Changing values
- Changing values and saving in the CPU change (cache) memory
- Changing interconnections using BICO technology
- Changing interconnections and saving in the CPU change (cache) memory
- Reading parameter descriptive elements

Hardware platforms

You can be used for the Parameter access technique following hardware platforms:

- T400 technology module
- Application module FM 458
- SIMADYN D standard CPUs

NOTE

Masterdrives operator control devices, for example, OP1S or “DRIVE ES”/“DRIVE Monitor“ can be used for parameterization.

4.6.1.1 Parameters

When the parameter access technique for D7-SYS you designate block inputs or outputs as parameter.

There are two types of parameters:

- **Monitoring parameters**
  - These can be configured at the inputs and outputs of blocks
  - Values can only be read.

- **Setting parameters**
  - are configured at block inputs
  - values can be read, changed and saved in the change memory.
  - interconnections to other blocks can be changed using BICO technology

NOTE You cannot change parameter values if $ signals or virtual connections are configured at the block inputs.

Connection data types for parameters

You can configure the following D7-SYS connection data types of the blocks as parameter:

D7-SYS connection data type in CFC	Bool	Integer	Double Integer	Word	Real	SDTime
Parameter data type in the parameter description	O2	I2	I4	V2	I4	I4

Configuring parameters

A maximum of 2000 different parameters are available. Each parameter may only be assigned once. Parameters are configured in CFC as follows:

Designate the block connection using a pseudo comment @TP_bnnn, with

- b: range identification "H", "L", "c" or "d"
  - designates the number range
  - "H" or "L": I/O can only be read and changed
  - "c" or "d": Connections can only be read
- nnn: three-digit parameter number
  - 000 to 999

NOTEs

- A parameter number may only be assigned once (checked using the CFC).
- A pseudo comment may not be configured at a chart interface connection.
- A pseudo comment may not be configured at a block connection in a chart, which is to be compiled as block type.
- No more than one parameter may be configured as pseudo comment per block connection.
- A comment can include several pseudo comments, separated by blanks, followed by a "standard" comments text, e.g. "@TP_H089 @DATX ...".)

Accessing parameters

You can externally access parameters (e.g. from a higher-level control system such as SIMADYN D) as follows:

Pseudo comment	T400 Techboard	T400 baseboard / CPU modules in SIMADYN D subracks	Can be configured at connection	Connection	Significance
	Display operator control units	Display operator control units	O: Output I: Input		
@TP_dxyz	dxyz	rxyz	A / E	Any	Monitoring parameter
@TP_cxyz	cxyz	nxyz	A / E	Any	Monitoring parameter
@TP_Hxyz	Hxyz	Pxyz	E	None or OP connections	Setting parameter
@TP_Lxyz	Lxyz	Uxyz	E	None or OP connections	Setting parameter
@TP_Hxyz	Hxyz	Pxyz	A	Any	Monitoring parameter
@TP_Lxyz	Lxyz	Uxyz	A	Any	Monitoring parameter

Legend

xyz:	Parameter number
any:	Interconnected or not interconnected .
OP connection:	Interconnected using global operands.

4.6.1.2 BICO technology for SIMADYN D

With MASTERDRIVES operator control devices, with BICO technology you can change interconnections between blocks. You can change configured software without using the CFC. You can change interconnections on a T400 technology board, Application module FM 458 or CPU module in a SIMADYN D subrack.

DANGER

- **BICO technology and the CFC test mode should not be used simultaneously.**
- **If you make online changes in the CFC test mode, then you must first re-compile before you use BICO technology. Changes made in the CFC only become effective on the display of the operator control device after compilation.**
- **If changes were made using BICO technology without saving them in the CPU change memory, then data consistency between the changes on the CPU and your configured software on the PC/PG are no longer guaranteed, and can no longer be established by updating the project. If you wish to avoid this inconsistent condition, you must first RESET the module before you use CFC in the test mode**

NOTE

If you have made interconnection changes using BICO technology, and then you activate the CFC test mode, a warning is displayed in the form of the "different software release" dialog box.

Data types for technological connectors

You can configure the following D7-SYS connection data types of the blocks as technological connectors:

D7-SYS connection data type in CFC	Bool	Integer	Double Integer	Word	Real	SDTime
Data type of the technological connector in the parameter description	O2	I2	I4	V2	I4	I4

Configuring technological connectors

In order that you can change interconnections between blocks using BICO technology, you must, in addition to the parameters, still configure technological connectors at block outputs in the CFC. You can use block outputs with technological connectors to change the interconnection using BICO technology.

Technological connectors are configured as follows:

Designate the block output with a pseudo comment @TC_nnnn, with nnnn: four-digit technological connector number 0000 to 9999

NOTES

- No more than one technological connector may be configured as pseudo comment per block output.
- A technological connector number may only be assigned once (checked using CFC).
- It is not permissible to configure a technological connector at a plan interface connection.
- It is not permissible to configure a technological connector at the connection (I/O) of a block in a chart, which is to be compiled as block type.
- A comment can include several pseudo comments, separated by blanks, followed by "standard" comments text, e.g. "@TC_1389 @TP_H345 ...

Reading parameters

You can read a parameter and output the value using an operator control device.

The output value corresponds to:

- for block I/O, interconnected with technological connectors, the number of the technological connector @TC_nnnn
- for block I/O which are not interconnected, the value of the block input or output

From the parameter documentation of a standard software package, you can identify whether the output value represents the number of a technological connector or the value of the block input. It is not possible to make this differentiation at the operator control device display.

Changing interconnections using BICO technology

Using BICO technology, you can only change existing interconnections between blocks, if these interconnections are configured as follows in the CFC:

- technological connectors @TC_nnnn are configured as pseudo comments at the block output,
- parameter @TP_Hnnn or @TP_Lnnn is configured as pseudo comment at the input of a block,
- the blocks are interconnected by connecting an input with pseudo comment @TP_Hnnn or @TP_Lnnn and an output with pseudo comment TC_nnnn.

The interconnection is changed using BICO technology, by entering, at the operator control device, the number of another technological connector @TC_nnnn as parameter value.

NOTE

- The maximum number of interconnections of different inputs which are changed with BICO technology, which are saved in the change memory, are, for
  - technology module T400: approx. 1600
  - Application module FM 458: approx. 400
  - CPU module in the SIMADYN D subrack: approx. 400
- Using BICO- technology, you can only change existing interconnections between block I/O, but you cannot delete them.
- Using BICO technology, you cannot establish a new interconnection at inputs which are not connected.
- Changes made to the interconnections of block I/O using BICO technology, are only effective when updating the project in the CFC, if they were saved.
- For changes made to the interconnections of block I/O using BICO technology, when type checking the connections, the same rules apply as for CFC.

CAUTION

The pseudo comment @DATX is not supported by the CFC test mode. When changing an interconnection, where @DATX is available as pseudo comment at the block input, the value for this connection is updated again, but still maintaining the data consistency mechanisms. Thus, the pseudo comment @DATX is no longer valid.

Remedy: Re-compile and re-load the user program.

Examples

Interconnection possibilities using BICO technology and their significance:

Pseudo-comment	Con-nection-Type	Inter-connected with	Processed at the operator control device	
			Read	Write
@TP_L/H	I	Standard	Display value	Not possible
@TP_L/H	I	Flag	Display value	Change value
@TP_L/H	I	$ signal	Display value	Not possible
@TP_L/H	I	Virtual inter-connection	Display value	Not possible
@TP_L/H	I	—	Display value	Change value
@TP_L/H	I	@TC_	Display the number of the @TC_	Interconnect to a new number of @TC_, if present
@TP_c/d	I	Any	Display value	Not possible
@TP_c/d	I	@TC_	Display value	Not possible
@TP_L/H	O	Any	Display value	Not possible
@TP_c/d	O	Any	Display value	Not possible
@TC_	I	—	Error message when compiling in the CFC	
@TC_	O	—	Source for interconnection using BICO technology	

Legend

@TP_L/H: Parameter @TP_Lnnn or @TP_Hnnn

@TP_c/d: Parameter @TP_cnnn or @TP_dnnn

@TC_: Technological connector @TC_nnnn

Standard: The output is not a flag, not a $ signal and is not a virtual interconnection.

Any: Interconnected or not interconnected.

— : No interconnection.

Interconnections extending over different tasks

The number of newly generated interconnections between different tasks using BICO technology is limited. The largest of the following values applies for your application:

- Value 20
- 20 % of the already configured number of interconnections between tasks
- 0.25 × number of the @TC_... technological connectors configured in task n.

4.6.1.3 Status-dependent parameter changes

If selected parameters are only to be changed when the system is in specific statuses, then you can configure the following functions blocks:

- Function block PSTAT
  - to configure a device status
  - by entering a password with the authorization level enabled
- Function block PLIM
  - defines the statuses and access levels in which a parameter may be changed

Additional information
on function blocks, refer to the Reference Manual "SIMADYN D Control system, Function Block Library".

4.6.1.4 Identifying SIMADYN D components

Reserved parameters

To identify components, “DRIVE Monitor“ evaluates technology parmeters d998 (1998) and d999 (1999).

d998	Device	Special feature
80	SIMADYN D, general	The parameter range, especially extended for SIMADYN D up to 16 * 2000 parameters, applies. Parameters are possible in the basic device parameter range (0 .. 999). This means, an identification can result in a random product if a parameter just by chance coincides with the identification parameter and value of a drive converter/inverter.
134	T400 /	Parameter range = technology parameters (1000 .. 1999; 3000 .. 3999)
134	FM 458/ SRT400	Parameter ranges, the function can be set at the central FB • BASEBOARD: 0 ... 999; 2000 ... 2999 • TECHBOARD: 1000 ... 1999; 3000 ... 3999

Procedure when identifying

Prerequisite: The user selects SIMADYN D or SRT400 and goes online with the device type.

Dependig on the selected device type, DriveMonitor checks the identification parameter d998. If the identification was successful, it is not checked as to whether another device can be recognized.

1. User selects SIMADYN D: If d998 = 80, then the identification routine is considered to have been successful.
2. User selects SRT400: If d998 = 134, then the identification routine is considered to have been successful. This means that the user can only address the technology, also independently of the basic device!

The following is still valid: Parameter d999 is optional to identify the software version and release of standard software packages.

d999	Software	Examples
1AB	Angular synchronism, version A.Bx (x is used to number compatible versions)	120 → SPA440 V2.0x 123 → SPA440 V2.3x
2AB	Axial winder, version A.Bx	221 → SPW420 V2.1x
3AB	Cross-cutter/closed-loop shears control, version A.Bx	310 → SPS450 V1.0x

If the device identification is not successful, then an attempt is made to identify the known devices types.

If “DRIVE Monitor“ recognizes a different software (d999), the “Create database” option is listed in the “Device identification” dialog box. This means that a specific database can be set-up.

4.6.1.5 Units and unit texts

In order that you can assign *units* (physical quantities) to an input or output, you must configure a text string for the block I/O from the table below.

Physical quantity	Units	Text string to be configured
Length	Meters	m
	Millimeters	mm
	Kilometers	km
	Micrometers	um
Surface	Square meters	m²
	Square millimeters	mm2
	Square kilometers	km2
Volume	Cubic meters	m³
	Liters	l
Time	Seconds	s
	Minutes	min
	Hours	h
	Days	d
	Milliseconds	ms
	Microseconds	us
Force	Newton	N
	Kilo newtons	kN
	Mega newtons	MN
Pressure	Pascal	Pa
	Kilopascal	kPa
	Millibar	mbar
	Bar	bar
Weight	Kilograms	kg
	Grams	g
	Milligrams	mg
	Tons	t
Energy, work	Joules	J
	Kilo joules	kJ
	Mega joules	MJ
	Watt hours	Wh
	Kilowatt hours	kWh
	Megawatt hours	MWh

Physical quantity	Units	Text string to be configured
Active power	Watts	W
	Kilowatts	kW
	Megawatts	MW
	Milliwatts	mW
Apparent power	Volt-ampere	VA
	Kilovolt-ampere	kVA
	Megavolt-ampere	MVA
	Millivolt-ampere	mVA
Speed	1 / second	1/s
	1 / minute	1/min
	1 / hour	1/h
Angle	Radian	rad
	Seconds	"
	Minutes	'
	(old) degrees	grad
	New degrees (Gon)	ngrad
Velocity	Meters / second	m/s
	Millimeters / second	mm/s
	Millimeters / minute	mm/min
	Meters / minute	m/min
	Kilometers / minute	km/min
	Millimeters / hour	mm/h
	Meters / hour	m/h
	Kilometers / hour	km/h
Volume flow	Cubic meters / second	m3/s
	Cubic meters / minute	m3/min
	Cubic meters / hour	m3/h
	Liters / second	l/s
	Liters / minute	l/min
	Liters / hour	l/h
Mass flow	Kilograms / second	kg/s
	Grams / second	g/s
	Tons / second	t/s
	Grams / minute	g/min
	Kilograms / minute	kg/min
	Tons / minute	t/min
	Grams / hour	g/h
	Kilograms / hour	kg/h
	Tons / hour	t/h

Physical quantity	Units	Text string to be configured
Torque	Newton meter	Nm
	Kilonewton meter	kNm
	Meganewton meter	MNm
Temperature	Kelvin	K
	Degrees Celsius	C
	Degrees Fahrenheit	F
Enthalpy	Joule / Kilogram	J/kg
	Kilojoule / Kilogram	kJ/kg
	Megajoule / Kilogram	MJ/kg
Voltage	Volt	V
	Kilovolts	kV
	Millivolts	mV
	Microvolts	uV
Current	Ampere	A
	Milliampere	mA
	Kiloampere	kA
	Microampere	uA
Resistance (electrical)	Ohm	Ohm
	Milliohm	mOhm
	Kiloohm	kOhm
	Megaohm	MOhm
Ratio	Percentage	%
Absolute humidity	Gram / Kilogram	g/kg
Frequency	Hertz	Hz
	Kilohertz	kHz
	Megahertz	MHz
	Gigahertz	GHz
Referred torque	Newton meter / ampere	Nm/A
Acceleration	Meter / seconds	m/s2
	Meter / seconds	m/s3

4.6.2 Parameterizing on the Application module FM 458

4.6.2.1 Terminology

- EXM448
  EXM 448 communications expansion module of the FM 458 application module
- CBP2
  COMBOARD/communications module for PROFIBUS DP
- "DRIVE ES" or "DRIVE Monitor"
  Configuring software for drives and software for parameterization

4.6.2.2 Communications behavior

The FM 458 applications module can be configured in a SIMATIC S7-400 rack together with one or two communication expansion modules EXM 448. An option module, e.g. CBP2, can be inserted in the free slot X02. The CBP2 can be used to send and receive parameter tasks.

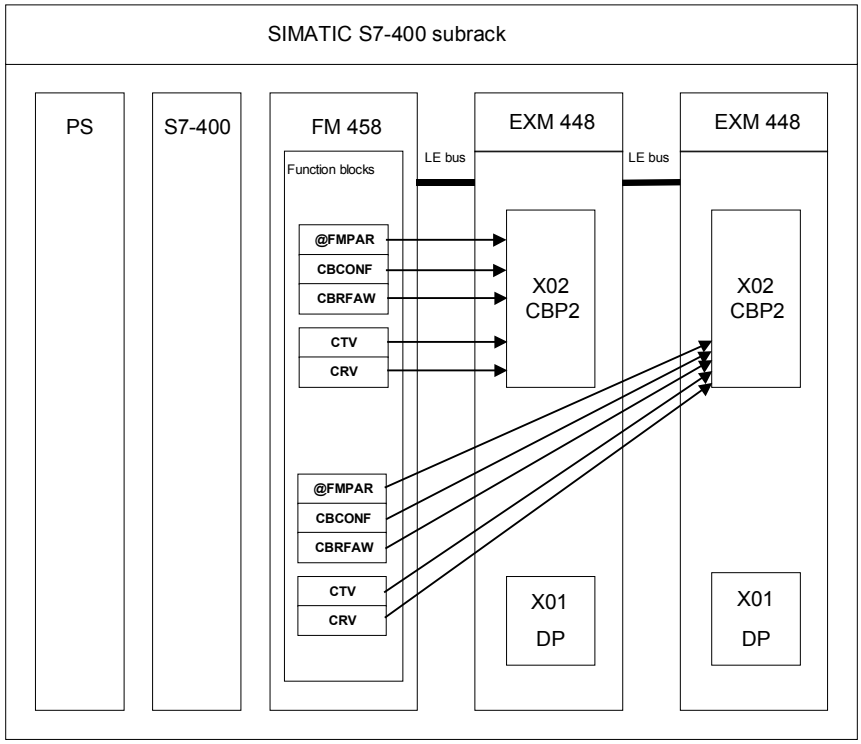


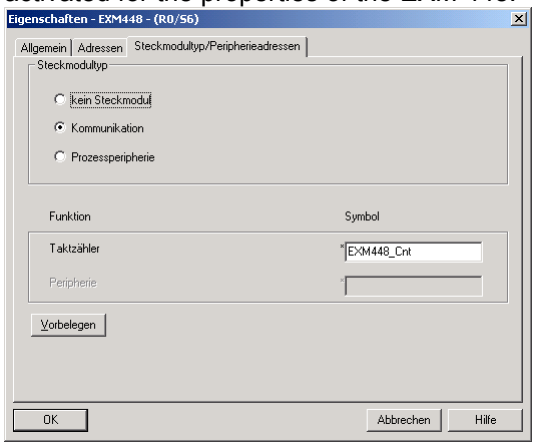
Fig. 4-47 Schematic diagram of the FM 458 application module with two EXM 448 communication-expansion modules

4.6.2.3 Generating the hardware configuration

You require the following hardware to parameterize the SIMATIC FM 458 modules:

- Subrack for S7-400
- Power supply module for the S7-400
- Central module (CPU) for S7-400
- FM 458 application module for SIMATIC S7-400
- EXM 448 communications-expansion module

  In HW Config, the "Communications" plug-in module type must be activated for the properties of the EXM 448.



- CBP2 communications module (COMBOARD)

4.6.2.4 Functional scope

You must configure the following function blocks when parameterizing with “DRIVE Monitor“:

- Central block @FMPAR
  - monitors the COMBOARD
  - processes the parameter tasks
- Function block CBCONF
  - used to configure a COMBOARD
  - used to display the diagnostic data of a COMBOARD

You can configure the following function blocks for additional functions:

- Function block CBRFAW

  To receive the alarms from a COMBOARD

- CRV

  The receive block distributes values from a data interface to the block inputs of function blocks of the same CPU.
  Only max. 16 PZD words can be received and sent using a COMBOARD (e.g. CBP2).

- CTV

  The function block only acquires and sends block output values from the CPU function blocks, on which it is configured.

4.6.2.5 Operator devices which can be connected

You can use the “DRIVE ES” or “DRIVE Monitor“ configuring software to parameterize the FM 458 application module

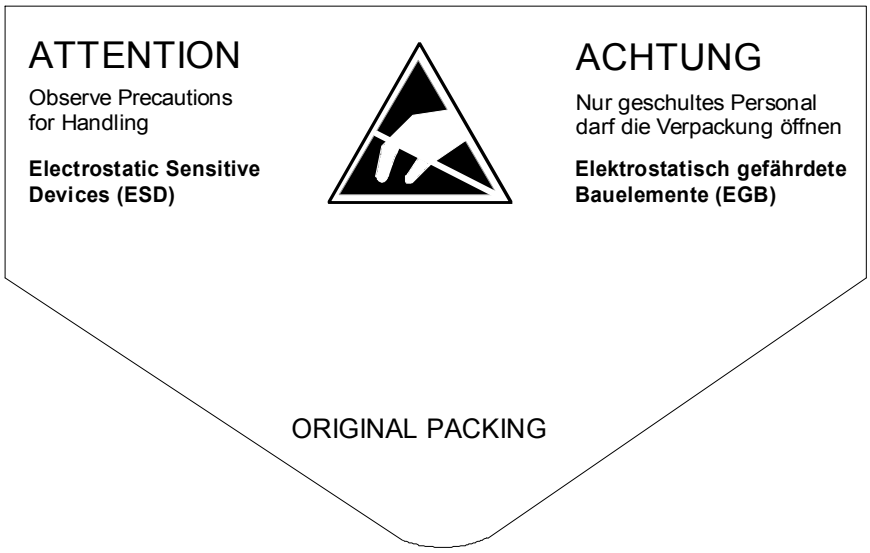
5 ESD guidelines

5.1 What does ESD mean?

Almost all of the SIMADYN D modules are equipped with highly integrated blocks. These blocks and modules are extremely sensitive to overvoltages and therefore to electrostatic discharge.

ESD The abbreviations stands for **e**lectro**s**tatic **d**ischarge

Modules which contain these components are identified with the following warning label on the component side:



Components which are sensitive to electrostatic discharge can be destroyed by voltages and energy levels which lie far below the perception level of humans. Voltages such as these even occur if a person, who has not been electrically discharged, comes into contact or touches a component or a module. Components which have been subject to overvoltages such as these, generally cannot be immediately identified as having been damaged. This only becomes obvious after a somewhat longer operating time.

5.1.1 Handling ESD boards

- Electronic boards should only be touched/handled if absolutely necessary.
- Components/devices may only be touched/handled if
  - you are continuously grounded through an ESD arm band
  - or you are wearing ESD shoes or ESD shoe grounding strips.
- The human body must be electrically discharged before touching/handling an electronics board. This can be simply done by touching a conductive, grounded object immediately beforehand (e.g. bare metal cabinet parts, water pipes etc.).
- Boards may not come into contact with highly-insulating materials which can be statically charged-up - e.g. plastic foils, insulating desktops, articles of clothing manufactured from man-made fibers.
- Boards may only be placed down on conductive surfaces (desktop with ESD surface, conductive ESD foam rubber, ESD packing bags, ESD transport containers, board- or paper surfaces).
- It is not permissible to bring boards close to monitors or TV sets.

5.1.2 Measuring and modifying ESD boards

- Measurements may only be carried-out on boards if
  - the measuring equipment is grounded (via the protective conductor) or
  - before making a measurement with an ungrounded instrument, the probe must be briefly discharged (e.g. by briefly touching a bare-metal control housing).

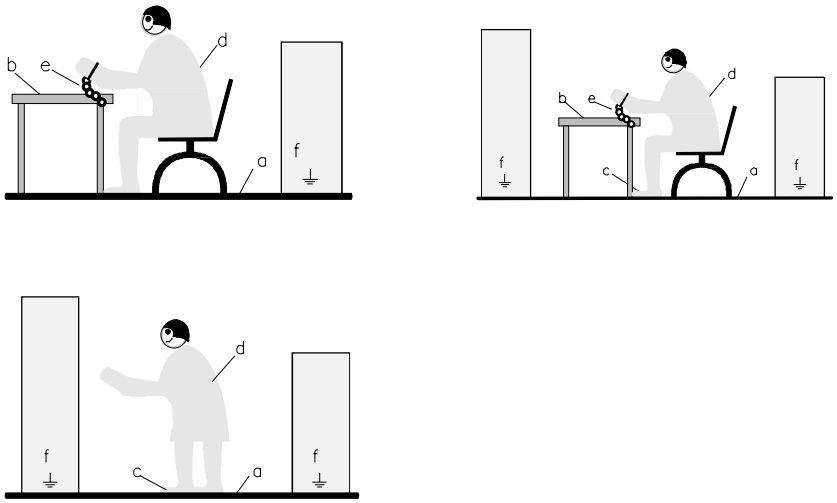
When soldering, only a grounded soldering iron may by used.

5.1.3 Shipping ESD boards

Modules and electronic components should generally be packed in electrically conducting containers (such as metallized plastic boxes or metal canisters) before being stored or shipped.

If the use of non-conducting packing containers cannot be avoided, modules must be wrapped in a conducting material before being put into such containers. Examples of such materials include electrically conducting foam rubber or household aluminum foil.

The protective measures necessary when dealing with electrostatic sensitive devices are illustrated in the following diagram.



a = Conductive floor surface

b = ESD table = ESD chain

c = ESD shoes

d = ESD overall

f = Cabinet ground connection