### Product data sheet Characteristics

# ATV32H075N4

variable speed drive ATV32 - 0.75 kw - 400 V - 3 phase - with heat sink



#### Main

Altivar 32   Variable speed drive   Synchronous motors   Asynchronous motors   Complex machines
Synchronous motors Asynchronous motors
Asynchronous motors
Complex machines
-
With heat sink
ATV32
Class C2 EMC filter integrated
3 phases
380500 V - 1510 %
323550 V
5060 Hz - 55 %
47.563 Hz
0.75 kW at 380480 V
1 hp at 380480 V

### Complementary

2.7 A for 500 V 3 phases 0.75 kW / 1 hp	
3.6 A for 380 V 3 phases 0.75 kW / 1 hp	
2.3 kVA at 500 V 3 phases 0.75 kW / 1 hp	
5 kA for 3 phases	
2.3 A at 4 kHz 500 V 0.75 kW / 1 hp	
3.5 A for 60 s 0.75 kW / 1 hp	
0.0005…0.599 kHz	
4 kHz	
216 kHz adjustable	
1100 for asynchronous motor in open-loop mode	
+/- 10 % of nominal slip 0.2 Tn to Tn	
+/- 15 %	
170200 %	
<= 170 % with braking resistor	
	2.3 kVA at 500 V 3 phases 0.75 kW / 1 hp   5 kA for 3 phases   2.3 A at 4 kHz 500 V 0.75 kW / 1 hp   3.5 A for 60 s 0.75 kW / 1 hp   0.00050.599 kHz   4 kHz   216 kHz adjustable   1100 for asynchronous motor in open-loop mode   +/- 10 % of nominal slip 0.2 Tn to Tn   +/- 15 %   170200 %



Asynchronous motor control profile	Voltage/frequency ratio, 2 points Flux vector control without sensor - Energy Saving, NoLoad law Voltage/frequency ratio, 5 points	
	Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, guadratic U/f	
Synchronous motor control profile	Vector control without sensor	
Regulation loop	Adjustable PID regulator	
Motor slip compensation	Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load Adjustable 0300 %	
Local signalling	1 LED red for drive voltage 1 LED green for CANopen run 1 LED red for CANopen error 1 LED red for drive fault	
Output voltage	<= power supply voltage	
Noise level	43 dB conforming to 86/188/EEC	
Insulation	Electrical between power and control	
Electrical connection	Screw terminal, clamping capacity: 0.51.5 mm², AWG 18AWG 14 (control) Removable screw terminals, clamping capacity: 1.52.5 mm², AWG 14AWG 12 (motor/braking resistor) Screw terminal, clamping capacity: 1.54 mm², AWG 14AWG 10 (power supply)	
Tightening torque	0.5 N.m, 4.4 lb/ft (control) 0.7 N.m, 7.1 lb/ft (motor/braking resistor) 0.6 N.m, 5.3 lb/ft (power supply)	
Supply	Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection	
Analogue input number	3	
Analogue input type	Al1 voltage: 010 V DC, impedance: 30000 Ohm, resolution 10 bits Al2 bipolar differential voltage: +/- 10 V DC, impedance: 30000 Ohm, resolution 10 bits Al3 current: 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance 250 Ohm, resolution 10 bits	
Sampling duration	2 ms (AI1, AI2, AI3) - analog input(s) 2 ms (AO1) - analog input(s)	
Response time	LI1LI6 8 ms, tolerance +/- 0.7 ms for logic output(s) R1A, R1B, R1C 2 ms for relay output(s) R2A, R2C 2 ms for relay output(s)	
Accuracy	+/- 0.2 % (Al1, Al2, Al3) for a temperature of -1060 °C +/- 0.5 % (Al1, Al2, Al3) for a temperature of 25 °C +/- 1 % (AO1) for a temperature of 25 °C +/- 2 % (AO1) for a temperature of -1060 °C	
Linearity error	+/- 0.20.5 % of maximum value (Al1, Al2, Al3) +/- 0.3 % (AO1)	
Analogue output number	1	
Analogue output type	AO1 software-configurable current 020 mA, impedance: 800 Ohm, resolution 10 bits AO1 software-configurable voltage 010 V, impedance: 470 Ohm, resolution 10 bits	
Discrete output number	3	
Discrete output type	Configurable relay logic: (R1A, R1B, R1C) NO/NC - 100000 cycles Configurable relay logic: (R2A, R2B) NO - 100000 cycles Logic: (LO)	
Minimum switching current	5 mA at 24 V DC for configurable relay logic	
Maximum switching current	R1: 3 A at 250 V AC resistive load, cos phi = 1 R1: 4 A at 30 V DC resistive load, cos phi = 1 R1, R2: 2 A at 250 V AC inductive load, cos phi = 0.4 R1, R2: 2 A at 30 V DC inductive load, cos phi = 0.4 R2: 5 A at 250 V AC resistive load, cos phi = 1 R2: 5 A at 30 V DC resistive load, cos phi = 1	
Discrete input number	7	
Discrete input type	Programmable (sink/source) (LI1LI4)2430 V DC, with level 1 PLC Programmable as pulse input 20 kpps (LI5)2430 V DC, with level 1 PLC Switch-configurable PTC probe (LI6)2430 V DC Safe torque off (STO)2430 V DC - 1500 Ohm	
Discrete input logic	Negative logic (sink) (LI1LI6), > 19 V (state 0), < 13 V (state 1) Positive logic (source) (LI1LI6), < 5 V (state 0), > 11 V (state 1)	
Acceleration and deceleration ramps	S	

	Deceleration ramp adaptation Linear CUS Deceleration ramp automatic stop DC injection Ramp switching U	
Braking to standstill	By DC injection	
Protection type	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive	
Communication port protocol	Modbus CANopen	
Connector type	1 RJ45 (on front face) for Modbus/CANopen	
Physical interface	2-wire RS 485 for Modbus	
Transmission frame	RTU for Modbus	
Type of polarization	No impedance for Modbus	
Number of addresses	1127 for CANopen 1247 for Modbus	
Method of access	Slave CANopen	
Electromagnetic compatibility	1.2/50 μs - 8/20 μs surge immunity test, level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test, level 3 conforming to IEC 61000-4-6 Electrical fast transient/burst immunity test, level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test, level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test, level 3 conforming to IEC 61000-4-3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11	
Width	45 mm	
Height	325 mm	
Depth	245 mm	
Net weight	2.5 kg	
Option card	Communication card for CANopen daisy chain Communication card for CANopen open style Communication card for DeviceNet Communication card for Ethernet/IP Communication card for Profibus DP V1	
Functionality	Mid	
Specific application	Other applications	
Environment		
Standards	EN/IEC 61800-3 EN/IEC 61800-5-1 EN 61800-3 environments 1 category C2 EN 55011 class A group 1 EN 61800-3 environments 2 category C2	
Product certifications	C-Tick CSA NOM 117 UL GOST	
Marking	CE	
Pollution degree	2 conforming to EN/IEC 61800-5-1	
IP degree of protection	IP20 conforming to EN/IEC 61800-5-1	
Vibration resistance	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) conforming to EN/IEC 60068-2-6	
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27	
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3	
Ambient air temperature for operation	-1050 °C without derating 5060 °C with derating factor	
Ambient air temperature for storage	-2570 °C	
Operating altitude	<= 1000 m without derating	

#### 1000...3000 m with current derating 1 % per 100 m

Operating position	Vertical +/- 10 degree

18 months

### Packing Units

2.357 kg	
0.850 dm	
2.750 dm	
3.250 dm	
	0.850 dm 2.750 dm

### Contractual warranty

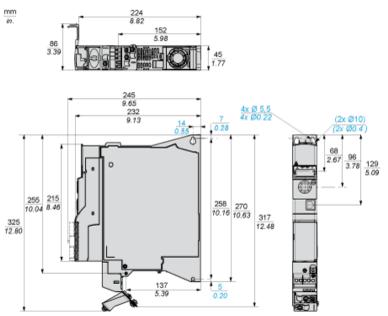
Warranty

Product data sheet **Dimensions Drawings** 

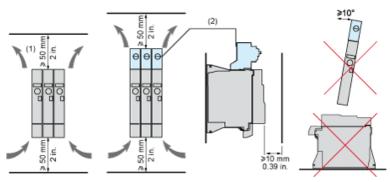
# ATV32H075N4

### Size A

### Dimensions



### Mounting and Clearance



(1) (2) Minimum value corresponding to thermal constraints. A 150 mm clearance may help to connect the ground.

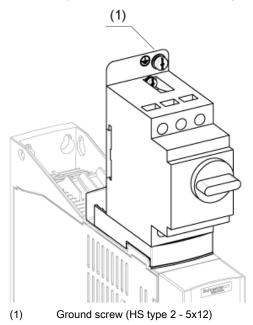
Optional GV2 circuit-breaker

#### Option: Protection Device, GV2 circuit-breaker

The drive is prepared to be equipped with an optional GV2 circuit-breaker.

The GV2 circuit-breaker is directly mounted on the drive. Mechanical and electrical link are made using the optional adapter. The options are supplied with detailed mounting instruction sheet.

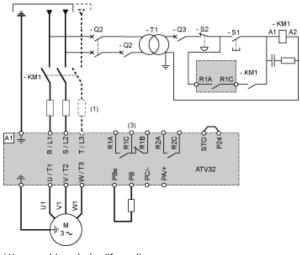
NOTE: The product overall dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.)



#### **Connection Diagrams**

#### Single or Three-phase Power Supply - Diagram with Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

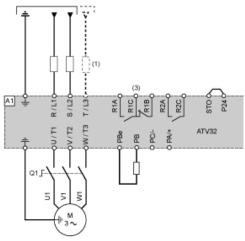


(1) (3) Line choke (if used)

Fault relay contacts, for remote signaling of drive status

#### Single or Three-phase Power Supply - Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



Line choke (if used) (1)

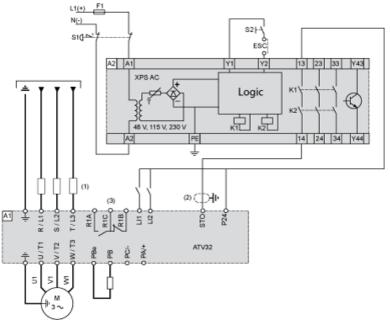
(3) Fault relay contacts, for remote signaling of drive status

#### Diagram with Preventa Safety Module (Safe Torque Off Function)

Connection diagrams conforming to standards EN 954-1 category 3 and IEC/EN 61508 capacity SIL2, stopping category 0 in accordance with standard IEC/EN 60204-1.

When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.

A contact on the Preventa XPS AC module must be inserted in the brake control circuit to engage it safely when the STO (Safe Torque Off) safety function is activated.



- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops. With an additional, approved EMERGENCY STOP module, it is also possible to implement category 1 stops.

#### STO function

The STO safety function is triggered via 2 redundant inputs. The circuits of the two inputs must be separate so that there are always two channels. The switching process must be simultaneous for both inputs (offset < 1 s).

The power stage is disabled and an error message is generated. The motor can no longer generate torque and coasts down without braking. A restart is possible after resetting the error message with a "Fault Reset".

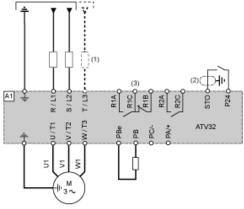
The power stage is disabled and an error message is generated if only one of the two inputs is switched off or if the time offset is too great. This error message can only be reset by switching off the product.

#### Diagram without Preventa Safety Module

Connection diagrams conforming to standards EN 954-1 category 2 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

The connection diagram below is suitable for use with machines with a short freewheel stop time (machines with low inertia or high resistive torque).

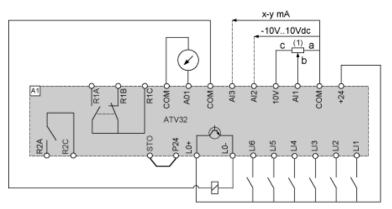
When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

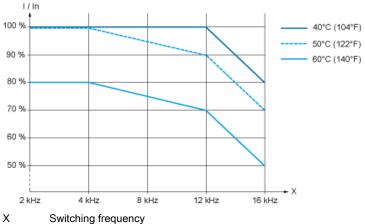
The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops.

### Control Connection Diagram in Source Mode



(1) Reference potentiometer SZ1RV1202 (2.2 k $\Omega$ ) or similar (10 k $\Omega$  maximum)

## Derating Curves

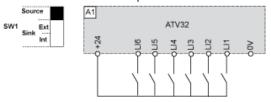


Derating curve for the nominal drive current (In) as a function of temperature and switching frequency.

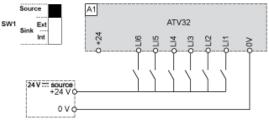
Above 4 kHz, the drive will reduce the switching frequency automatically in the event of an excessive temperature rise.

#### Sink / Source Switch Configuration (SW1)

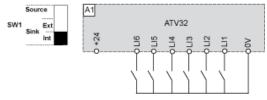
The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs. Switch SW1 set to "Source" position



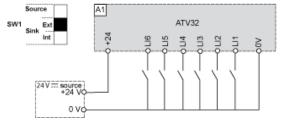
Switch SW1 set to "Source" position and use of an external power supply for the LIs



Switch SW1 set to "Sink Int" position



#### Switch SW1 set to "Sink Ext" position



### ATV32H075N4 is replaced by:



#### Variable speed drives ATV320U07N4B

variable speed drive, ATV320, 0.75 kW, 380...500 V, 3 phases, book

#### Qty 1

Reason for Substitution: End of life | Substitution date: 03 May 2016