SIEMENS

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This manual is part of the documentation package with the order number **6ES7198-8FA10-8BA0**

Edition 02/2003 EWA 4NEB 780601602-06

This manual contains notices intended to ensure personal safety, as well as to protect the products and connected equipment against damage. These notices are highlighted by the symbols shown below and graded according to severity by the following texts:



Danger

indicates that death, severe personal injury or substantial property damage will result if proper precautions are not taken.



Warning

indicates that death, severe personal injury or substantial property damage can result if proper precautions are not taken.



Caution

indicates that minor personal injury can result if proper precautions are not taken.

Caution

indicates that property damage can result if proper precautions are not taken.

Notice

draws your attention to particularly important information on the product, handling the product, or to a particular part of the documentation.

Qualified Personnel

Only **qualified personnel** should be allowed to install and work on this equipment. Qualified persons are defined as persons who are authorized to commission, to ground and to tag circuits, equipment, and systems in accordance with established safety practices and standards.

Correct Usage

Note the following:



Warning

This device and its components may only be used for the applications described in the catalog or the technical description, and only in connection with devices or components from other manufacturers which have been approved or recommended by Siemens.

This product can only function correctly and safely if it is transported, stored, set up, and installed correctly, and operated and maintained as recommended.

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Siemens AG Bereich Automation and Drives Geschaeftsgebiet Industrial Automation Systems Postfach 4848, D- 90327 Nuernberg We have checked the contents of this manual for agreement with the hardware and software described. Since deviations cannot be precluded entirely, we cannot guarantee full agreement. However, the data in this manual are reviewed regularly and any necessary corrections included in subsequent editions. Suggestions for improvement are welcomed.

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Preface

Purpose of the manual

The information contained in this manual will enable you to operate the ET 200X distributed I/O device as a DP slave on PROFIBUS-DP.

Required basic knowledge

General knowledge of automation engineering is required to understand the manual.

Scope of validity of the manual

This manual is valid for the ET 200X distributed I/O system components specified in Appendix A.

This manual contains a description of the components that were valid at the time the manual was published. We reserve the right to enclose a Product Information bulletin containing up-to-date information about new components and new versions of components.

Changes since the previous version

Compared to the previous version, the manual contains the following changes and additions:

DPV1 support of DPV1 of all basic modules with DDB file SI0380**.GS*

Note: You can recognize the previous version of this ET 200X manual by the number EWA-4NEB 78060160x-04 in the footer.

The current number is EWA-4NEB 78060160x-05.

Certification

See Section 6.1 Standards, certificates, and approvals.

CE certification

See Section 6.1 Standards, certificates, and approvals.

Identification code for Australia (C-tick mark)

See Section 6.1 Standards, certificates, and approvals.

Standards

See Section 6.1 Standards, certificates, and approvals.

Position in the information landscape

This delivery package (order number 6ES7 198-8FA01-8AA0) consists of 4 manuals with the following contents:

BM 147/CPU basic module



- Addressing
- ET 200X with BM 147/CPU with PROFIBUS-DP
- Commissioning and diagnostics
- Technical data
- Order numbers
- STEP 7 list of operations



FT 200X

Distributed I/O Device

- Installation and wiring
- Commissioning and diagnostics
- Technical specifications of digital and analog modules
- Order numbers for digital and analog modules



EM300 Motor Starter

Wiring

- Commissioning and diagnostics
- Technical data
 - Order numbers



EM 148-FC

Frequency converter

Wiring

- Commissioning and diagnostics
- Functions and technical data
- Order numbers

Guide

You can quickly access specific information in the manual by using the following aids:

- At the beginning of the manual you will find a comprehensive table of contents and lists of the figures and tables in the entire manual.
- In the left margin on each page in every chapter you will find information that provides you with an overview of the contents of each section .
- Following the appendices, you will find a glossary in which important technical terms used in the manual are defined.
- At the end of the manual you will find a comprehensive index enabling rapid access to the information you are looking for.

Points to note

In addition to this manual, you will also need the manual for the DP master (see Appendix A).

Note

You will find a detailed list of the contents of the ET 200X manuals in Section 1.8 of this manual. We recommend that you begin by reading this section so as to find out which parts of which manuals are most relevant to you in helping you to do what you want to do.

Recycling and disposal

The ET 200X is suitable for recycling on account of its low-emission components. To ensure that your old devices are recycled and disposed of in an environmentally sound way, contact an authorized company for electronic waste.

Additional support

If you have any questions that are not answered here on the use on any of the products described in this manual, please contact your Siemens office or agency.

http://www.ad.siemens.com/automation/partner

Training center

We offer the relevant courses to get you started more easily with xxx and the SIMATIC S7 programmable controller. Please contact either your regional training center or the central training center in D-90327 Nuremberg. Telephone: +49 (911) 895-3200.

Internet: http://www.sitrain.com

A&D Technical Support

Available at any time of the day:



Service & Support on the Internet

In addition to our documentation, you can also find comprehensive information on the Internet.

http://www.siemens.com/automation/service&support

There you can find:

- Our newsletter with the latest product information.
- Any documents you may require via our search in Service & Support.
- A forum in which users and specialists worldwide exchange their experiences.
- Your contact person in Automation & Drives via the contact database.
- Information on local service, repairs, spare parts. You will also find lots more under "Services".

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Product Overview

In this Chapter

The product overview tells you

- how to incorporate the ET 200X distributed I/O device into the Siemens programmable controller landscape.
- The components which make up the ET 200X distributed I/O device
- Which manuals in the ET 200X manual package contain what information

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1.1 What are distributed I/O devices?

Distributed I/O devices – usage

When a system is set up, the inputs and outputs to and from the process are often located centrally in the programmable controller.

If there are inputs and outputs at considerable distances from the programmable logic controller, there may be long runs of cabling which are not immediately comprehensible, and electromagnetic interference may impair reliability.

The use of distributed I/O devices is suitable for such systems:

- The controller CPU is located centrally.
- The I/O devices (inputs and outputs) are operating locally on a distributed basis.
- The high-performance PROFIBUS-DP ensures with its high baud rates that the controller CPU and I/O devices communicate smoothly.

What is **PROFIBUS-DP**?

PROFIBUS-DP is an open bus system complying with IEC 61784-1:2002 Ed1 CP 3/1 with the "DP" transmission log (DP stands for Distributed Peripheral).

Physically, PROFIBUS-DP is either an electrical network based on a shielded two-wire line or an optical network based on a fiber-optic cable.

The "DP" transmission log allows a rapid, cyclic exchange of data between the controller CPU and the distributed I/O devices.

What are DP masters and DP slaves?

The link between the controller CPU and distributed I/O devices is the DP master. The DP master exchanges data by means of PROFIBUS-DP with the distributed I/O devices and monitors PROFIBUS-DP.

The distributed I/O devices (= DP slaves) prepare the data of the sensors and actuators so that it can be transferred via PROFIBUS-DP to the controller CPU.

What devices can be connected to PROFIBUS-DP?

Different devices can be connected on PROFIBUS-DP as DP masters or DP slaves provided they behave in accordance with the IEC 61784-1:2002 Ed1 CP 3/1 standard. You can use devices from the following product families amongst others:

- SIMATIC S5
- SIMATIC S7/M7/C7
- SIMATIC programmer/PC
- SIMATIC HMI (operator interface OP, OS, TD)
- Devices from other manufacturers

Configuring a PROFIBUS-DP network

In the figure below you can see a typical installation of a PROFIBUS-DP network. The DP masters are integrated in the relevant device – for example, the S7-400 has a PROFIBUS-DP interface, and the IM 308-C master interface module is inserted in the S5-115U. The DP slaves are the distributed I/O devices connected to the DP masters via PROFIBUS-DP.



Figure 1-1 Typical PROFIBUS-DP network installation

1.2 What is the ET 200X distributed I/O device?

Definition

The ET 200X distributed I/O device is a modular DP slave in the IP 65 to IP 67 degrees of protection.

Usage

Owing to its robust design and the IP 65 to IP 67 degrees of protection, the ET 200X distributed I/O device is particularly suitable for usage in harsh industrial environments.

Rapid and optimum adaptation of the ET 200X to the technological functional units of your machine is ensured thanks to the option of integrating motor starters (switching and protecting any three-phase loads up to 5.5 kW), frequency converters (actuating asynchronous motors up to 0.75 kW rated power) and I/O modules.

Basic and expansion modules

An ET 200X distributed I/O device consists of a basic module in which some digital inputs and outputs have already been integrated. Up to 7 expansion modules can be added to the basic module.

An ET 200X distributed I/O device is connected to PROFIBUS-DP by means of cable connectors for PROFIBUS-DP on the basic module. Every ET 200X distributed I/O device is a DP slave on PROFIBUS-DP.

ET 200X with BM 147/CPU can also be configured for standalone operation (i.e. not connected to a bus).



Configuration of ET 200X (example)

Figure 1-2 Configuration of the ET 200X distributed I/O device (example)

Components

The components of the ET 200X include the following basic modules:

- + BM 141 DI 8 \times DC 24V basic module
- + BM 141 DI 8 \times DC 24V ECOFAST basic module
- BM 141 DI 8 imes DC 24V ECOFAST DIAG basic module
- + BM 142 DO 4 \times DC 24V/2A basic module
- BM 143-DESINA FO basic module
- BM 143-DESINA RS485 basic module
- BM 147/CPU basic module

The following expansion modules can be added to each of the basic modules:

- EM 141 DI 4 \times DC 24V expansion module
- EM 141 DI 8 × DC 24V expansion module
- + EM 141 DI 8 imes DC 24V expansion module (short and long types)
- EM 142 DO 4 \times DC 24V/0.5A expansion module
- EM 142 DO 8 \times DC 24V/1.2A expansion module
- + EM 142 DO 4 \times DC 24V/2A expansion module
- EM 143-DESINA expansion module (only with BM 143-DESINA)
- + EM 144 AI 2 \times U (±10 V) expansion module
- + EM 144 Al 2 $\,\times\,$ I ($\pm\,$ 20 mA or 4 to 20 mA) expansion module
- EM 144 AI 2 × I (4 to 20 mA) expansion module
- EM 144 AI 2 × RTD (Pt 100) expansion module
- EM 145 AO 2 \times U (±10 V) expansion module
- EM 145 AO 2 \times I (\pm 20 mA or 4 to 20 mA) expansion module
- EM 300... expansion module (motor starter)
- EM 148-FC frequency converter
- EM 148-P DI 4 × DC 24V/DO 2 × P expansion module (pneumatic module)
- EM 148-P DO 16 × P/CPV10 expansion module (pneumatic interface module for FESTO valve island CPV10)
- EM 148-P DO 16 × P/CPV14 expansion module (pneumatic interface module for FESTO valve island CPV14)
- PM 148 DO 4 \times DC 24V/2A power module
- SITOP power 24V/10A power supply unit
- CP 142-2 communication processor as AS-i master

Features of the ET 200X

- The supply voltage for the electronic components and sensors, the load voltage and PROFIBUS-DP are connected to the basic module by means of connectors.
- The BM 141... and BM 142... basic modules contain a number of inputs and outputs. Basic modules can be expanded on a modular basis.
- Motor starters (direct-on-line and reversing starters) can be used as expansion modules for switching and protecting any three-phase loads up to 5.5 kW, at 400 VAC (refer to the manual *EM 300* Motor Starters).
- Frequency converters can be used as expansion modules for actuating asynchronous motors up to 0.75 kW rated power at 400 VAC (refer to the manual *EM 148-FC Frequency Converters*).
- Pneumatic modules having two 4/2-way valves and pneumatic interface modules for connecting two regular FESTO valve islands to the ET 200X can be used as expansion modules (refer to Section 1.4).
- When expansion modules are installed, the supply voltage for the electronic components and the sensors and the load voltage are automatically fed to these modules from the basic module.
- The voltage and the bus signals can be looped through to the next ET 200X via connectors.
- The supply voltage for the electronic components and the sensors and PROFIBUS-DP can be fed to the first ET 200X via separate cables and then looped through to the next ET 200X via a common cable.
- The PROFIBUS address of the ET 200X can be set between 1 and 125 by means of switches in the basic module.
- There are 4 LEDs on the front of the basic module that indicate faults in the hardware of an ET 200X (SF), bus faults (BF), and the supply voltage for the electronic components and sensors (ON) and load voltage (24 VDC).
- Transmission rates of 9.6 kbps to 12 Mbps are permitted for the ET 200X.
- CP 142-2 as AS-i master

DP Master for ET 200X

The ET 200X can communicate with all DP masters that behave in compliance with IEC 61784-1:2002 Ed1 CP 3/1. However, some DP masters can process only limited frame lengths.

Check whether the DP master you are using can receive frames from the ET 200X in their entirety. To ascertain this, you will find a list of maximum frame lengths in the *configuration and parameter assignment frames for ET 200X* at http://www.ad.siemens.de/simatic-cs.

1.3 ET 200X-DESINA/ET 200X-ECOFAST

ET 200X-DESINA

DESINA is the acronym for **D**istributed and **S**tandardized **IN**st**A**llation technique for machine tools.

DESINA is a uniform installation system and specifies all components in terms of function and connection system.

The followings modules fulfill the requirements of the DESINA specification:

| • | BM 143-DESINA FO | (fiber-optic PROFIBUS-DP) |
|---|------------------|------------------------------------|
| | | (FO = F ibre O ptic) |

• BM 143-DESINA RS485 RS 485) (copper wire PROFIBUS-DP based on

• EM 143-DESINA

ET 200X-ECOFAST

ECOFAST is the trade name for Energy and **CO**mmunication Field InstAllation SysTem.

The following ECOFAST module has a terminal system compliant with the DESINA specification:

- BM 141 DI 8 \times DC 24V ECOFAST

(copper wire PROFIBUS-DP based on RS 485)

Comparison of features

| Table 1-1 | Features of the ET200X-DESINA and ET200X-ECOFAST |
|-----------|--|
| | |

| ET200X-DESINA | ET200X-ECOFAST | | | |
|--|--|--|--|--|
| PROFIBUS-DP is connected via DESINA connectors | s by means of: | | | |
| Copper conductors to RS 485 | | | | |
| Fiber-optic cables for use in environments with high interference | | | | |
| Each DESINA basic module and expansion module has 8 digital channels, and each channel can be configured as an input or output. | The BM 141 DI 8 \times DC 24V ECOFAST basic module has 8 digital inputs. | | | |
| With a maximum of seven EM 143-DESINA expansion modules, an ET 200X-DESINA has a total of 64 DESINA-compliant inputs/outputs. | | | | |
| There is an additional diagnostic input for each channel. | | | | |
| The connected DESINA-compatible sensors and actuators can be directly monitored by means of the diagnostic input. Alternatively, the diagnostic input can be configured as an input with NC functionality. | _ | | | |
| The field bus (PROFIBUS-DP) and the switched and non-switched load voltages are carried to the basic module by a single cable set. The cable connects to the basic module by means of DESINA connectors. | | | | |
| When expansion modules are installed, the non-switched and switched load voltages are fed from the basic module to the expansion modules. | | | | |
| The voltages and bus signals can be looped through to the next ET 200X-DESINA by means of a second DESINA connector. | | | | |
| The PROFIBUS address is set by means of DIL switches in a removable configuration connector. This means that the basic module can be replaced without resetting the address. | | | | |
| The BM 143-DESINA and BM 141 DI 8 \times DC 24V ECOFAST basic modules can be combined with all the other expansion modules of the ET 200X. | | | | |
| Four LEDs are provided on the front of the basic modules for indicating: | | | | |
| Errors on the ET-DESINA (SF) | | | | |
| Data transfer to the BM 143-DESINA (RUN) | | | | |
| Non-switched load voltage (DC 24 V-NS)) | | | | |
| Switched load voltage (DC 24 V-S) | | | | |
| Transmission rates of 9.6 kbps to 12 Mbps are permitted. | | | | |

Note

The EM 143-DESINA expansion module can **only** be used with the BM 143-DESINA and BM 141-ECOFAST basic modules. It is not compatible with the BM 141, BM 142 and BM 147/CPU basic modules.

DP master for ET 200X-DESINA/ET 200X-ECOFAST

The ET-DESINA and ET 200X-ECOFAST can communicate with all DP masters that behave in compliance with EN 50170, Volume 2, PROFIBUS. However, some DP masters can process only limited frame lengths.

Check whether the DP master you are using can receive frames from the ET 200X-DESINA and ET 200X-ECOFAST in their entirety. To ascertain this, you will find a list of maximum frame lengths in the *configuration and parameter* assignment frames for ET 200X at http://www.ad.siemens.de/simatic-cs.



Configuration of ET 200X-DESINA/ECOFAST (examples)

Figure 1-3 Configuration of the ET 200X-DESINA/ET 200X-ECOFAST distributed I/O device (example)



Figure 1-4 Configuration of the ET 200X-DESINA/ET 200X-ECOFAST distributed I/O device with various expansion modules

1.4 ET 200X with pneumatic functionality

40 per cent of all actuators are pneumatic cylinders. Three expansion modules for the pneumatic connection to the ET 200X are available for optimum adaptation of the ET 200X to the overall process:

- EM 148-P DI 4 × DC 24V/DO 2 × P expansion module (pneumatic module)
- EM 148-P DO 16 × P/CPV10 expansion module (pneumatic interface module for FESTO valve island CPV10)
- EM 148-P DO 16 × P/CPV14 expansion module (pneumatic interface module for FESTO valve island CPV14)

Pneumatic module

The pneumatic module is an expansion module with four digital inputs and two separate 4/2-way valves. The pneumatic module is used to control:

- a maximum of two double-acting pneumatic cylinders having a piston diameter of up to 50 mm
- a single-acting pneumatic cylinder with a piston diameter up to 50 mm when a plug is used for the second connection to the valve
- other pneumatic drives such as rotary actuators or
- a nozzle.

Pneumatic cylinders having a piston diameter greater than 50 mm can similarly be controlled with constraints at the piston speed.

The digital inputs can be used to acquire the limits of travel of the pneumatic cylinders.

You can integrate up to seven pneumatic modules into an ET 200X.



Configuration of the ET 200X with pneumatic modules (example)

Figure 1-5 Configuration of the ET 200X with pneumatic modules (example)

Pneumatic interface module for the CPV10 and CPV14

The pneumatic interface modules are expansion modules for connecting two Regular CPV10 or CPV14 FESTO valve islands.

Each of the two FESTO valve islands can be equipped with as many as 16 valves (standard components of the FESTO company). The valve islands differ in respect of their rated air flows (CPV10: 400 I/min; CPV14: 800 I/min).

You can integrate up to six pneumatic interface modules into an ET 200X.

Configuration of the ET 200X with pneumatic interface module and FESTO valve island (example)



Figure 1-6 Configuration of the ET 200X with pneumatic interface module (example)

Address assignment, pneumatic interface module for CPV10 and CPV14



The figure below shows the pneumatic interface module with FESTO CPV10 valve island and addresses.

Figure 1-7 Assigning addresses to the pneumatic interface module

1.5 ET 200X with PM 148 DO 4 \times DC 24V/2A power module

Function

The power module is an expansion module for ET-voltage feed. You can use power modules to loop through or feed load voltage separately from multiple supply points to the digital-output modules of the ET 200X.

You can integrate a maximum of 7 power modules into an ET 200X.

Switching load voltage ON/Off selectively

A separate load-voltage supply means that you can switch load voltage on and off selectively for individual modules. The "DC 24V" LED on the power module indicates whether or not load voltage is applied.



Configuration of ET 200X with power module (example)

Figure 1-8 Configuration of ET 200X with power module (example)

1.6 ET 200X with SITOP power

Function

SITOP-mode power supply unit for ET 200X.

It integrates into the ET 200X without additional wiring and supply the power for electronics/sensors and/or the load voltage. Response to faults is parameterizable (restart or shutdown following a short circuit on the output side).

Note

- SITOP power 24V/10A must always be installed in the rightmost slot of the ET 200X.
- If a SITOP power module is installed on a BM 143-DESINA or BM 141-ECOFAST, do not use the DESINA hybrid cable to supply power (power is supplied by the SITOP power). In this case the DESINA hybrid cable is used only for connection to PROFIBUS-DP. Do not loop through the power supply from a BM 143-DESINA or BM 141-ECOFAST with SITOP power.

Configuration of ET 200X with SITOP power 24V/10A (example)



Figure 1-9 Configuration of ET 200X with SITOP power (Example)

1.7 ET 200X with CP 142-2 communication processor

Function

You can connect an AS interface to the ET 200X with the aid of the CP 142-2 (as AS-i master). A configuration of this nature can include a maximum of 31 AS-i slaves. LEDs on the front panel of the CP 142-2 indicate the operating statuses of the slaves.

The CP 142-2 is parameterized with STEP 7. Separate configuration for AS-i is not necessary.

You can connect a maximum of 6 CP 142-2 communication processors to each basic module (except the BM 147/CPU).

You can connect a maximum of 7 CP 142-2 communication processors to the BM 147/CPU basic module.



Configuration of ET 200X with CP 142-2 (example)

Figure 1-10 Configuration of ET 200X with CP 142-2 (Example)
1.8 Guide to the ET 200X manuals

Components and the manuals required for them

The components of the ET 200X are described in various manuals in the ET 200X package. The figure below shows possible ET 200X configurations and the manuals required for them.



Figure 1-11 Components and the manuals required for them

Where do you find what information?

The table below will help you get your bearings and find the information you need quickly. It tells you which manual you need to refer to and which chapter deals with the topic you are interested in.

| | Manual | | | | |
|---|--------------------------------------|--------------------------------|----------------------------|-------------------------------------|--------------------------------|
| Subject | Distributed I/O device ET 200X | BM 147/C PU basic module | EM 300 motor starter | EM 148-FC frequency converter | Chap- ter/ Appen- dix |
| ET 200X configuration options | х | | | | 2 |
| Installation of ET 200X, motor starters and frequency converters; setting the PROFIBUS address connecting the terminating resistor | x | | | | 3 |
| Installation of ET 200X-DESINA/ECOFAST; setting the PROFIBUS address | x | | | | 3 |
| BM 147/CPU addressing | | х | | | 2 |
| Electrical configuration and wiring of the ET 200X | x | | | | 4 |
| Electrical configuration and wiring of the ET 200X-DESINA/ECOFAST | x | | | | 4 |
| Wiring of motor starters | | | х | | 2 |
| Wiring of frequency converters | | | | х | 2 |
| ET 200X with BM 147/CPU with PROFIBUS-DP | | x | | | 3 |
| Commissioning and diagnostics of the ET 200X | x | | | | 5 |
| Commissioning and diagnostics of the ET 200X-DESINA/ECOFAST | x | | | | 5 |
| Commissioning and diagnostics of the ET 200X with the BM 147/CPU | | x | | | 4 |
| Commissioning and diagnostics of the ET 200X with motor starters | | | х | | 3 |
| Commissioning and diagnostics of the ET 200X with frequency converters | | | | x | 3 |
| General technical specifications of the ET 200X (standards, certificates and approvals, EMC, environmental conditions, etc.) | x | | | | 6 |
| Technical specifications of the basic and expansion modules with DI, DO, AI and AO | x | | | | 7 |
| Technical specifications of the BM 147/CPU | | x | | | 5 |
| Technical specifications of the motor starters | | | х | | 5 |
| Functions and technical specifications of the frequency converters | | | | x | 4 |
| BM 147/CPU cycle and response times | | х | | | 6 |
| Order numbers of the components | х | | | | А |

| Table 1-2 | Topics of the manuals in the ET 200X manual pack | ane |
|-----------|--|-----|
| | | aye |

| | Manual | | | | |
|--|--------------------------------------|--------------------------------|----------------------------|-------------------------------------|--------------------------------|
| Subject | Distributed I/O device ET 200X | BM 147/C PU basic module | EM 300 motor starter | EM 148-FC frequency converter | Chap- ter/ Appen- dix |
| Order numbers of the motor starters | | | х | | А |
| Order numbers of the frequency converters | | | | x | A |
| Dimensioned drawings of the basic modules and digital and analog expansion modules | x | | | | С |
| Dimensioned drawings of the motor starters | | | х | | В |
| Dimensioned drawings of the frequency converters | | | | x | В |
| Configuration and parameter assignment frames for the BM 147/CPU | | x | | | A |
| Configuration assignment frame for the motor starter | | | х | | С |
| STEP 7 list of operations | | х | | | В |
| Execution times of SFCs | | x | | | С |
| Glossary | x | х | | | Glossar y |

| Table 1-2 | Topics of the manua | als in the FT 200X | manual nackade | continued |
|-----------|----------------------|--------------------|-----------------|-----------|
| | Toples of the manual | | manual package, | continucu |

Table 1-3 Separate manuals for ET 200X components

| Subject | Manual |
|------------------|--|
| Using a CP 142-2 | CP 142-2 Manual Order No.: 6GK7 142-2AH00-8AA0 |

Configuration Options

Configuration options

There are several different ways in which ET 200X distributed I/O devices can be connected to PROFIBUS-DP. This chapter provides an overview of the various configuration options. The restrictions regarding the maximum number of modules allowed in each configuration are described in a separate section.

Contents of Chapter

| Section | Subject | Page |
|---------|--|------|
| 2.1 | Brief overview of the different basic modules | 2-2 |
| 2.2 | Feeding and looping through the supply voltage for the electronic components/sensors and PROFIBUS-DP | 2-3 |
| 2.3 | Disconnecting the ET 200X from the bus and looping through the supply voltage/PROFIBUS-DP (not ET 200X-DESINA/ ET 200X-ECOFAST) | 2-6 |
| 2.4 | Connecting the load supply voltage to the motor starters, frequency converters and looping it through | 2-8 |
| 2.5 | Connecting and looping through the load voltage | 2-10 |
| 2.6 | Use of the SITOP power power supply unit | 2-11 |
| 2.7 | Connecting and looping through load voltages and PROFIBUS-DP to ET 200X-DESINA / ET 200X-ECOFAST | 2-12 |
| 2.8 | Restrictions on the number of modules | 2-13 |
| 2.9 | Maximum configuration and configuration options with power modules | 2-16 |

Modules for the ET 200X

This chapter does not contain any further information about the types of module that can be used for the ET 200X. Please refer to Chapter 7 for the technical specifications, pinouts, basic circuit diagrams, etc.

Terminating resistor

There must be a terminating resistor on the first and last node of a PROFIBUS-DP network with copper conductors (see Section 3.4).

The ET 200X-DESINA FO has a fiber-optic waveguide to transmit bus signals. This waveguide does not require a terminating resistor.

Configuring a PROFIBUS-DP network

The principles and rules for configuring a PROFIBUS-DP network are described in the manual for the DP master.

2.1 Brief overview of the different basic modules

| Common features | Operation as a DPV0 slave Operation as a DPV1 slave Operation as a S7 slave Diagnostic interrupt Hardware interrupt Direct communication IP 67 |
|---|--|
| BM 141 DI 8 × DC 24V (6ES7 141-1BF12-0XB0) | 8 digital inputs Connectors for the supply and PROFIBUS-DP (copper conductors) DDB file for DPV1: SI03803D.GSG (as of version 1 of the basic module) |
| BM 141 DI 8 × DC 24V ECOFAST (6ES7 141-1BF01-0AB0) | 8 digital inputs ECOFAST connectors for the supply and PROFIBUS-DP (copper conductors) DDB file for DPV1: SI0380D2.GSG (as of version 1 of the basic module) |
| BM 141 DI 8 × DC 24V ECOFAST DIAG (6ES7 141-1BF40-0AB0) | 8 digital inputs ECOFAST connectors for the supply and PROFIBUS-DP (copper conductors) Diagnostic interrupt for short circuit and wire break for each channel Hardware interrupt at rising and falling edge for each channel DDB file for DPV1: SI0380D3.GSG (as of version 2 of the basic module) |
| BM 142 DO 4 × DC 24V/2A (6ES7 142-1BD22-0XB0) | 4 digital outputs (2A per output) Connectors for the supply and PROFIBUS-DP (copper conductors) DDB file for DPV1: SI03803C.GSG (as of version 3 of the basic module) |
| BM 143-DESINA FO (6ES7 143-1BF00-0XB0) | 8 digital inputs or outputs (separately parameterizable as an input or output), diagnostic input for each channel ECOFAST connectors for the supply and PROFIBUS-DP (fiber-optic cables) DDB file for DPV1: SI03809A.GSG as of version 5 of the basic module |
| BM 143-DESINA RS485 (6ES7 143-1BF00-0AB0) | 8 digital inputs or outputs (separately parameterizable as an input or output), diagnostic input for each channel ECOFAST connectors for the supply and PROFIBUS-DP (fiber-optic cables) DDB file for DPV1: SI03809A.GSG (as of version 2 of the basic module) |

2.2 Feeding and looping through the supply voltage for the electronic components/sensors and PROFIBUS-DP

Configuration options

Each ET 200X consists of a basic module (BM) and up to 7 expansion modules (EM). There are various ways of connecting ET 200X distributed I/O devices to PROFIBUS-DP:

- feeding and looping through the supply voltage for the electronics/sensors and PROFIBUS-DP via a common cable 1
- feeding and looping through the supply voltage for the electronics/sensors and PROFIBUS-DP via separate cables 2
- feeding and looping through the supply voltage for the electronics/sensors and PROFIBUS-DP via separate cables 3
- feeding the supply voltage for the electronics/sensors to every ET 200X and looping through PROFIBUS-DP via separate cables 4

Each of the above configuration options is described below using an example.

Connection

You can hook up the supply voltage and PROFIBUS-DP by means of a connector on the basic module of the ET 200X. Use a second connector for looping through.

Feeding via a common cable

The supply voltage for the electronic components and the sensors is fed to the first ET 200X and looped through to the downstream ET 200Xs via the same cable as PROFIBUS-DP.



Figure 2-1 Feeding and looping through the supply voltage and PROFIBUS-DP via a common cable

2 Looping through via a common cable

The supply voltage for the electronic components/sensors and PROFIBUS-DP are fed to the first ET 200X via two separate cables. They are looped through to the downstream ET 200Xs via a common cable.



Figure 2-2 Feeding the supply voltage and PROFIBUS-DP via separate cables and looping them through via a common cable

3 Feeding/looping through via separate cables

The supply voltage for the electronic components/sensors and PROFIBUS-DP are fed to the first ET 200X and looped through to the downstream ET 200Xs via two separate cables.



Figure 2-3 Feeding the supply voltage and PROFIBUS-DP and looping them through via separate cables

4 Feeding/looping through of PROFIBUS-DP via 1 cable

The supply voltage for the electronic components/sensors is fed to each ET 200X separately. PROFIBUS-DP is fed and looped through to the downstream ET 200Xs via a common cable.



Figure 2-4 Feeding the supply voltage separately to each ET 200X and looping PROFIBUS-DP through via a separate cable

Cables

Please refer to Section 4.4 and Appendix A for a list of suitable cable types.

Load supply voltage

If you use motor starters (EM 300...) and/or frequency converters, you must supply them with 400 VAC (see Chapter 2.4).

Load power supply

If you use basic/expansion modules that have outputs, you must connect the relevant ET 200X to a load power supply (see Section 2.5). Exception: ET 200X-DESINA (see Figure 4-4).

2.3 Disconnecting ET 200X from the bus and looping through the supply voltage/PROFIBUS-DP (not ET 200X-DESINA/ET 200X-ECOFAST)

Looping through PROFIBUS-DP

The two connectors for feeding and looping through the supply voltage and PROFIBUS-DP are plugged into a connector plate in the basic module. Remove the two connectors from the BM 141/BM 142/BM 147 basic module of the ET 200X **together with the connector plate beneath them**.

Advantage

The relevant ET 200X distributed I/O device is disconnected from PROFIBUS-DP, but the supply voltage and PROFIBUS-DP are still looped through to the next ET 200X.

Example

This principle is demonstrated by the example shown in the diagram below.



Figure 2-5 Disconnecting the ET 200X from the bus and looping through the supply voltage/PROFIBUS-DP



Caution

There are freely accessible live contacts on the underside of the connector plate. Take steps to ensure that no short-circuits can occur between these contacts, or the fuse on the connector plate may be tripped and damage caused to other connected devices.

2.4 Connecting the load supply voltage to motor starters/frequency converters and looping it through

Necessity

If you use motor starters (EM 300...) and/or frequency converters (EM148-FC), you must supply them with a 400 VAC load voltage. You must also supply the basic module of the relevant ET 200X with DC 24V load voltage (exception: ET 200X-DESINA and ET 200X-ECOFAST, see Figure 4-4 and Figure 4-5).

Connection

Hook up the load supply voltage and the load to the power socket and power connector on the motor starter/frequency converter.

Looping through

The load supply voltage can be looped through from one motor starter/frequency converter to the next by connecting an additional power connector to the motor starter/frequency converter. The load supply voltage can be looped through both within the same ET 200X and from one ET 200X to the next.

Configuration example

The diagram below shows you three possible configurations with connections for the 400 VAC load supply voltage, the load and looping through. The possible configurations for motor starters and frequency converters are the same. You must take into account that the frequency converters have to be positioned to the right of the motor starters.



Figure 2-6 Connecting and looping through the load supply voltage

Cables

Please refer to Section 4.4 for a list of suitable cable types.

2.5 Connecting and looping through the load voltage

Necessity

A load voltage is only necessary if you wish to use a basic module/expansion module(s) with outputs (e. g. DO) and/or motor starters/frequency converters.

In the case of the ET 200X-DESINA and ET 200X-ECOFAST, the load voltage is carried by the DESINA hybrid cable.

Connection

You can hook up the load voltage by means of a connector on the basic module of the ET 200X. Power can also be supplied from a power module or a SITOP power.

Configuration example

The diagrams below show you a configuration with basic/expansion modules that have digital outputs (DO). Please refer to Section 7.1 for a list of the modules that can be used.



Figure 2-7 Connecting and looping through the load voltage

Looping through

The load voltage can be looped through from one ET 200X to the next by wiring the load voltage connector accordingly (see Section 4.4.2).

Cables

Please refer to Section 4.4 for a list of suitable cable types.

2.6 Use of the SITOP power power supply unit

The SITOP power 24V/10A power supply unit can provide the ET 200X with the supply voltage for electronics/sensors and/or the load voltage.

Configuration example

The diagrams below show you some configuration examples.



Figure 2-8 ET 200X with SITOP power 24V/10A

2.7 Connecting and looping through load voltages and PROFIBUS-DP to ET 200X-DESINA / ET 200X-ECOFAST

Non-switched and switched load voltage and PROFIBUS-DP are fed to the first ET 200X-DESINA/ET 200X-ECOFAST in a shared DESINA hybrid cable and looped through to the downstream ET 200X-DESINA/ ET 200X-ECOFAST.



Figure 2-9 Supply voltage and PROFIBUS-DP supplied and looped through with a DESINA hybrid cable

For the connection with controller or power supply on the DESINA hybrid cable, we recommend the MCP12P media converter manufactured by Harting. See ordering data in Appendix A.

2.8 Restrictions on the number of modules

Maximum configuration

Every ET 200X consists of a basic module and up to seven expansion modules.

Motor starter, frequency converter: A maximum of 6 motor starters or frequency converters can be connected for each basic module (EM 300..., EM 148-FC). They can be inserted anywhere in the ET 200X but frequency converters must always be to the right of the motor starters.

Pneumatic interface modules: A maximum of 6 pneumatic interface modules (EM 148-P DO $16 \times P/CPV...$) can be connected in the ET 200X configuration.

CP 142-2 communication processor: A maximum of 6 CP 142-2 communication processors can be connected to each basic module (except BM 147/CPU). Up to seven CP 142-2 processors can be connected to the BM 147/CPU.

Restrictions imposed by power input

The maximum configuration is dependent on the power input of the individual modules. The table below shows you all the possible configurations (described in the previous sections) and specifies the restrictions imposed on them. It also indicates ways of overcoming these restrictions.

Note

The PM 148 DO $4 \times$ DC 24V/2A power module interrupts the supply of load voltage to the downline expansion modules of an ET 200X. It has a separate load-voltage feed, which it uses to supply the downline expansion modules (see Section 2.9).

| Configuration options | Restrictions | Calculation/overcoming the restrictions |
|---|---|---|
| Supply voltage and PROFIBUS-DP fed and looped through via a common cable ① Supply voltage and PROFIBUS-DP fed via separate cables and looped through via a common cable ② | Power input of the whole configuration: Up to 40 °C ≤ 6 A Up to 55 °C ≤ 4 A Maximum cable length: 25 m if the power input of the whole configuration is as follows: Up to 40 °C ≤ 6 A Up to 55 °C ≤ 4 A 120 m if the power input of the whole configuration is as follows: Up to 40 °C ≤ 1 A Up to 55 °C ≤ 0.8 A | Calculate the power input of each module (see the technical specifications as of Section 7.1). Add up the power input of all the modules in the whole configuration. If the current input > 6 A (4 A), then feed the supply voltage to a few ET 200Xs from the power system again (permissible power input per ET 200X ≤ 1 A or ≤ 0.8 A as a function of temperature). |
| Supply voltage and PROFIBUS-DP fed and looped through via separate cables 3 | Power input of one ET 200X: Up to 40 °C ≤ 1 A Up to 55 °C ≤ 0.8 A | Calculate the power input of each module (see the technical specifications as of Section 7.1). Add up the power input of the modules of each ET 200X. If the power input > 1 A (0.8 A), reduce the number of expansion modules per ET 200X. |
| | The maximum cable length for the supply voltage is dependent on the cable core cross-section and on the power input of the whole configuration: Cable core cross-section 0.75 mm² and power input 1 A (0.8 A): cable length 120 m Cable core cross-section 0.75 mm² and power input 6 A (4 A): cable length 12 m Cable core cross-section 1.5 mm² and power input 1 A (0.8 A): cable length 240 m Cable core cross-section 1.5 mm² and power input 6 A (4 A): cable length 240 m Cable core cross-section 1.5 mm² and power input 6 A (4 A): cable length 240 m Table core cross-section 1.5 mm² and power input 6 A (4 A): cable length 24 m | To calculate the cable length: Add up the power input of all the modules in the whole configuration. Increase the cable length, if necessary, by feeding the supply voltage for a few ET 200Xs from the power system again. |

Table 2-2 Restrictions imposed on the maximum configuration by the power input

| Configuration options | Restrictions | Calculation/overcoming the restrictions |
|--|---|--|
| Supply voltage fed to each ET 200X from the power system and PROFIBUS–DP looped through via a separate cable | Power input of one ET 200X: • Up to 40 °C \leq 1 A • Up to 55 °C \leq 0.8 A The length of the bus cable is dependent on the transmission rate of the PROFIBUS-DP network (see the manual for the DP master) | Calculate the power input of each module (see the technical specifications as of Section 7.1). Add up the power input of the modules of each ET 200X. If the power input > 1 A (0.8 A), reduce the number of expansion modules per ET 200X. |
| Load voltage connected and looped through to the basic module (see Figure 2-7) | Power input from the load of one ET 200X: Up to 40 °C ≤ 10 A Up to 55 °C ≤ 8 A Power input from the load of the whole configuration if the load voltage is looped through: Up to 40 °C ≤ 16 A Up to 55 °C ≤ 12 A | Calculate the power input from the load of each module (see the technical specifications as of Section 7.1). Add up the power inputs of all the modules of an ET 200X or of the whole configuration. If the power input from the load of an ET 200X > 10 A (8 A), you have two options: Reduce the number of expansion module(s) with DOs and/or motor starters/frequency converters on the ET 200X Feed in the load voltage using a power module (see Figure 2-10) If the power input from the load of the whole configuration > 16 A (12 A), feed the load voltage to a few ET 200Xs from the power system again. |

Table 2-2 Restrictions imposed on the maximum configuration by the power input, continued



Caution

If you ignore the restrictions on the maximum system configuration specified in Table 2-2, the cable insulation and the contacts may be overheated and the device damaged as a result.

Currents of motor starters

You will find the power input and aggregate current of motor starters in the manual *EM 300* motor starters.

Currents of frequency converters

You will find the power input and aggregate current of frequency converters in the manual *EM 148-FC frequency converters*.

2.9 Maximum configuration and configuration options with power modules

Maximum configuration

Every ET 200X consists of a basic module and up to seven expansion modules, of which a maximum of seven expansion modules can be PM 148 DO 4 \times DC 24V/2A power modules.

Restrictions imposed by power input

The maximum system configuration is limited amongst other things by the power input of the load of the digital output modules in the configuration (see Section 2.7).

Limits for current consumption by load without use of power modules:

| Limits for one ET 200X | Limits for ET 200X overall configuration (load voltage looped through) |
|--------------------------|---|
| Up to 40 °C: \leq 10 A | Up to 40 $^{\circ}$ C: \leq 16 A |
| Up to 55 °C: \leq 8 A | Up to 55 °C: \leq 12 A |

Raising the limit

If the power input from the load exceeds the above limits, use power modules that correspond to the load power consumption of your configuration. A power module provides 10 A of load current for the downline digital-output modules.

Configuration examples

The illustration below shows a number of ET 200X configurations with power modules. The load voltage can be:

- fed separately to each basic module and each power module 1
- looped through from basic module to power module 2
- looped through from power module to power module 3



Figure 2-10 Configuration examples with power modules

Note

Load voltage cannot be supplied to power modules from the basic module via the ET 200X backplane bus. The load voltage must always be supplied via the power module's connector plug.

Installation

Structure of the ET 200X

The ET 200X distributed I/O device is a modular DP slave. An ET 200X consists of a basic module and up to 7 expansion modules.

Installation procedure

You have to install the ET 200X distributed I/O device in several stages. See Chapter 3.1 and 3.2.

Required settings

You can set the PROFIBUS address between with the 7 DIL switches in the basic module or by means of the configuration connector (BM 143-DESINA and BM 141-ECOFAST).

If the ET 200X distributed I/O device is the first or last DP slave in a PROFIBUS-DP network with copper conductors (RS 485), you must terminate the bus on the basic module with a terminating resistor (not required with BM 143-DESINA FO).

Contents of Chapter

| Section | Subject | Page |
|---------|--|------|
| 3.1 | Installing/deinstalling the ET 200X | 3-2 |
| 3.2 | Installing/disassembling pneumatic components | 3-11 |
| 3.3 | Setting/modifying the PROFIBUS address | 3-16 |
| 3.4 | Terminating PROFIBUS with a terminating resistor | 3-20 |

3.1 Installing/deinstalling the ET 200X

Installation Position

The ET 200X with no motor starters or frequency converters can be installed in any position.

An ET 200X with motor starters or frequency converters can be installed on a vertical wall in the following positions:

- ET 200X tilted up to 22.5 to the front or the rear, and/or
- ET 200X rotated up to 90 to the right or the left.

DIN rail

As a preference, the ET 200X modules must be installed on a DIN rail. Five types are available (see Table 3-1 and Figures 3-1 and 3-2).

| Table 3-1 | DIN rails for installing an ET 200X |
|-----------|-------------------------------------|
|-----------|-------------------------------------|

| Description | Order No. |
|--|---------------------|
| DIN rail, narrow, length 400 mm for ET 200X electronic module | 6ES7 194-1GA00-0XA0 |
| DIN rail, narrow, length 640 mm for ET 200X electronic module | 6ES7 194-1GA10-0XA0 |
| DIN rail, narrow, length 2000 mm for ET 200X electronic module | 6ES7 194-1GA20-0XA0 |
| DIN rail, wide, length 520 mm for ET 200X electronic module and motor starter/frequency converter/pneumatic interface module | 6ES7 194-1GB00-0XA0 |
| DIN rail, wide, length 1000 mm for ET 200X electronic module and motor starter/frequency converter/pneumatic interface module | 6ES7 194-1GB10-0XA0 |
| Screws with washer assemblies (100 screws M5 x 20, crossed recessed head with washer) for fitting ET 200X modules onto DIN rail | 6ES7 194-1KC00-0XA0 |



Figure 3-1 DIN rail for installing the ET 200X modules

Cross recessed head screws M5 x 20 8.8 Z4-1 as per DIN 7985 and a lock ring and washer should be used to fasten the module to the DIN rail. The screw length of 20 mm is absolutely essential.

Figure 3-2 shows dimensioned drawings for the narrow DIN rails.

Figure 3-3 shows dimensioned drawings for the wide DIN rails.



Note

You must cut the narrow DIN rail (with a length of 2000) to suit your requirements and drill the mounting holes for M8 screws.

To ensure that all the ET 200X modules have the specified vibration resistance, the mounting holes should be spaced at even intervals of a maximum 200 mm after initial spacing of 12 mm.



Figure 3-3 Dimensioned drawings of the wide DIN rails

Installing the ET 200X

- 1. Use M8 screws to secure the DIN rail to the substrate at all the fixing points provided.
- 2. Remove the cover panel from the expansion port of the basic module.
- 3. Screw the basic module to the DIN rail at the 4 fixing points using cross-recess M5 x 20 screws
 - Tightening torque: 2 Nm (max. 3 Nm)
- 4. Plug the expansion module into the expansion interface of the basic module and fasten the modules using two M3.5 x 25 screws.

| Note | |
|------|--|
| | • If both frequency converters and motor starters are to be fitted in an ET 200X, you must always fit the frequency converters to the right of the motor starters (because the connector pin assignment of the motor starters is different from the assignment on the DESINA). |
| | SITOP power 24V/10A must always be fitted in the extreme right position in the ET 200X and the lid fitted to seal the expansion interface. |

- Use M5 x 20 cross-recess screws to screw the expansion module to the DIN rail at the two or three fixing points. Tightening torque: 2 Nm (max. 3 Nm)
- 6. Plug the next expansion module into the interface of the previous expansion module and fasten the module using two or three M3.5 x 25 screws.
- Use M5 x 20 cross-recess screws to screw the expansion module to the DIN rail at the two or three fixing points. Tightening torque: 2 Nm (max. 3 Nm)
- 8. Repeat steps 6 and 7 until the ET 200X is completely installed on the DIN rail.
- 9. Fix the cover panel for the expansion port onto the last expansion module of the ET200X.



Figure 3-4 Installing expansion modules

Deinstalling the ET 200X

Note the following before deinstalling the ET 200X:



Caution

Before you deinstall expansion modules, you must switch off all the supply voltages for the ET 200X (i.e. the ET 200X must be deenergized).

If you do not do this, when you remove the expansion modules their electronic components can get damaged.

Note

If servicing is required, it is possible to eliminate a module fault by replacing the upper section (the ET 200X must be in a deenergized state). In this case, disassemble the replacement module and use the upper section. This renders complete disassembly of the ET 200X unnecessary.

Dimensioned drawing for fixing holes

The diagrams below show you the positions of the fixing screw holes for one basic module, one expansion module and one motor starter or frequency converter. Use the specified screws.

Note

The ET 200X must be installed on the rail, and screws must be affixed at all the fixing points.



Figure 3-5 Fixing screws for basic and expansion modules



Figure 3-6 Fixing screws for motor starters and frequency converters

3.2 Installing/disassembling pneumatic components



Supply and service line connections to the pneumatic module

Figure 3-7 Supply and service lines on pneumatic module EM 148-P DI 4 x DC 24V/DO 2 x P

Diameters of tubing for pneumatic connection

| Table 3-2 | Outer diameters of pneumatic tubing |
|-----------|-------------------------------------|
|-----------|-------------------------------------|

| Tubing | Outside diameter |
|----------------------------------|------------------|
| Supply and waste air connections | 8 mm each |
| Service connections per valve | 6 mm each |

Supply, waste air and service line connection to pneumatic module

Prerequisite: You have installed the ET 200X (see Section 3.1).

- 1. Use tubing exhibiting outside tolerance from FESTO for example, type PUN ... or type PAN Push the tubing having an outer diameter complying with Table 3-2 as far as the stop over the appropriate connection on the module (refer to Figure 3-7).
- 2. Close unused service connections with plugs. (2 plugs are included with the pneumatic module.)

Note

Bundle laid tubing with hose band clips for the sake of tidiness on your system.

Directing waste air into the environment

If you want to direct the waste air from the module into the environment, you can leave the waste air connection on the module open (refer to Figure 3-7). We recommend you to place a silencer on the waste air connection to reduce noise.

You will find the order number for the silencer in Appendix A.

Containing waste air

If you place tubing on the waste air connection of the module, you can then guide the waste air away or collect it. Collection is practical, for instance, the pneumatic system is enriched with oil and you would like to dissipate the oily air.

In the case of contained air, the tubing has to be run by the shortest possible route to a large-volume waste air line or outdoors. Please note that the operating pressure must not rise with hose length. Waste air must not be impeded at the waste air connection of the module.

Note

When the waste air from several modules is funneled, the resulting back pressure in the common waste air line my be too high – for example, with a long waste air tube length or a small tube diameter. In this case we recommend you to install a non-return valve between the waste air line of the pneumatic module and the common waste air line – for example, type H-QS-8 from FESTO.

Central supply of compressed air to pneumatic modules

There is no pneumatic connection between several pneumatic modules of the ET 200X. This means that you must supply compressed air to each pneumatic module separately.

In order to feed the pneumatic modules **centrally** with air all the same, there is a simple solution. You interconnect the compressed air lines by means of T plug connections – for example, type QST-10-8 from FESTO, as basically shown in the figure below.



Figure 3-8 Central supply of compressed air to pneumatic modules

Note

The rate of air flow is lower when T plug connections are used.

Note on starting up and operating pneumatic components

Note

Please note that the permissible operating pressure is reached before the valve is switched electrically.

FESTO valve island for ET 200X

The pneumatic interface modules are expansion modules for connecting two Regular FESTO valve islands:

- EM 148-P DO 16 \times P/CPV10 for FESTO valve island CPV10
- EM 148-P DO 16 × P/CPV14 for FESTO valve island CPV14

You can obtain valve islands from FESTO. The valve islands are described in separate documents.

Installing a FESTO valve island and pneumatic interface module

Prerequisite: You have installed the ET 200X (see Chapter 3.1).

If you want to install a pneumatic interface module or a PM 148 DO $4 \times$ DC 24V/2A power module directly next to a motor starter, the motor starter must be version \geq 02.

A maximum of six pneumatic interface modules can be plugged into an ET 200X.

To install, perform the followings steps:

- 1. Slide the pneumatic interface module into the expansion interface of the preceding module.
- 2. Tighten the securing screws of the extension interface.
- 3. Plug the valve island in the interface module.
- 4. Screw the valve island and the interface module tightly to the rail (see Section 3.1).



Figure 3-9 Installing a valve island with an interface module
Dimensioned drawing for installation holes on the pneumatic interface module



The diagram below contains the dimensions and positions of the mounting screw holes for one basic module and a pneumatic interface module.

Figure 3-10 Dimensions of installation holes on the pneumatic interface module

Disassembling modules featuring pneumatic functionality

Please take the following important note into account before disassembling pneumatic and pneumatic interface modules:



Caution

Before disassembling expansion modules featuring pneumatics, you must:

- disconnect all supply voltages for the ET 200X
- disconnect the supply of compressed air

If you fail to comply with these rules, the following effects are possible:

- damage to module electronics
- uncontrollable motions of detached tubing
- unwanted motions of the actuators connected

3.3 Setting/modifying the PROFIBUS address

The PROFIBUS address defines the address of the ET 200X distributed I/O device on PROFIBUS-DP which is used by the DP master.

Set the PROFIBUS address using the DIP switches on the basic module.

Valid PROFIBUS addresses

The PROFIBUS address can be anything from 1 to 125. The PROFIBUS address 0, which is set when the ET 200 distributed I/O system leaves the factory, is reserved for a programming device/PC.

Location of the DIP switches on the BM 141, BM 142 and BM 147/CPU

The DIP switches for setting the PROFIBUS address are inside the basic module underneath the connector plate for the connectors for PROFIBUS-DP and the supply voltage.

Location of the DIP Switches on the BM 143-DESINA and BM 141-ECOFAST

The DIL switches for setting the PROFIBUS address are in a removable configuration connector.

The configuration connector is secured to the basic module by an 8-pin M12 round plug.

This means that if the basic module has to be replaced it is not necessary to reset the PROFIBUS address.

Procedure for BM 141, BM 142 and BM 147/CPU

- 1. Remove the connector plate from the basic module before you set the PROFIBUS address. The DIL switches are concealed by the connector plate.
- 2. Set the PROFIBUS address using the DIL switches.

The diagram below shows the location of the DIL switches in the basic module as well as an example of the switch settings.



Figure 3-11 Setting the PROFIBUS address

Note: The PROFIBUS address in the basic module must always correspond to the PROFIBUS address specified in the configuration software for this ET 200X.

Procedure for BM 143-DESINA and BM 141-ECOFAST

1. Unscrew the configuration connector from the basic module and disconnect the plug (see Figure 3-12).



Figure 3-12 Position of the configuration connector on the ET 200X-DESINA/ET 200X-ECOFAST

- 2. On the configuration connector, slacken the screw securing the cover and remove the cover.
- 3. Set the PROFIBUS address using the DIL switches.

The diagram below shows the configuration connector with the cover removed, as well as an example of the switch settings.



Figure 3-13 Setting the PROFIBUS address at the configuration connector

Note: The PROFIBUS address in the basic module must always correspond to the PROFIBUS address specified in the configuration software for this ET 200X-DESINA/ET 200X-ECOFAST.

4. Reinstall the cover and plug the configuration connector back into the basic module. Secure the configuration connector to the basic module.

Modifying the PROFIBUS address

You can modify the PROFIBUS address in exactly the same way as you set it. Any change made to the PROFIBUS address takes effect when the supply voltage is turned on the ET 200X.

3.4 Terminating PROFIBUS with a terminating resistor

Purpose of the terminating resistor

A bus cable must be connected at both ends (i.e. at the first and last node in the network) with its characteristic impedance.

Note

The terminating resistor is only necessary with copper conductors with an RS-optic cables (FO).

Because the BM 143–DESINA FO basic module is connected to the PROFIBUS–DP by means of fiber-optic cables there is no terminating resistor there.

How to proceed with the ET 200X

In the case of the ET 200X you switch the terminating resistor using two DIP switches. The two DIP switches are inside the basic module of the ET 200X, under the connector plate for the connector for PROFIBUS-DP and the supply voltage for electronic components/sensors.

- 1. Remove the connector plate from the basic module before you connect the terminating resistor. The DIL switches are concealed by the connector plate.
- 2. Connect the terminating resistor using the DIL switches.

The diagram below shows the location of the DIL switches in the basic module as well as an example of the switch settings.

Note

The terminating resistor will not function correctly unless **both** DIP switches of the terminating resistor are set to "on" or "off".



Figure 3-14 Connecting the terminating resistor

How to proceed with the ET 200X-DESINA and ET 200X-ECOFAST with RS 485 Interface

Connect these bus nodes using DESINA hybrid cables with copper conductors (RS 485).

Attach the terminating resistor for the first and last bus node on the right-hand DESINA connector of the relevant BM 141-ECOFAST or BM 143-DESINA RS485 basic module.

You can find the order numbers for the terminating resistor in Appendix A.



Figure 3-15 Attaching the terminating resistor

Note

The terminating resistor is supplied by the non-switched DC 24 V-NS load voltage.

The terminating resistor can only be guaranteed to function without problems if the non-switched DC 24 V-NS load voltage has a tolerance range of $\pm 10\%$.

4

Wiring

In this Chapter

This chapter provides an overview of the rules and regulations for operating the ET 200X distributed I/O device.

It also shows you how you have to wire the ET 200X distributed I/O device.

Contents of Chapter

| Section | Subject | Page |
|---------|--|------|
| 4.1 | General rules and regulations for operating an ET 200X | 4-2 |
| 4.2 | Operating an ET 200X on a grounded supply | 4-4 |
| 4.3 | Electrical design of the ET 200X | 4-6 |
| 4.4 | Wiring the ET 200X | 4-11 |

Grounding

You can set up a grounded or ungrounded configuration for the ET 200X distributed I/O device.

For reasons of electromagnetic compatibility, the ET 200X and ET 200X-DESINA/ET 200X-ECOFAST distributed I/O devices must always be non-isolated (connect PE terminal to protective ground!).

4.1 General rules and regulations for operating an ET 200X

As a component part of a plant or system, the ET 200X distributed I/O device necessitates observance of special rules and regulations, depending on where it is to be used.

This chapter provides an overview of the most important rules which you have to observe for integrating the ET 200X distributed I/O device in a plant or system.

Specific application

Observe the safety and accident prevention regulations that apply to specific applications, e.g. the directive on machinery 89/392/EEC.

EMERGENCY STOP devices

EMERGENCY STOP devices conforming with IEC 204 (corresponds to DIN VDE 113) must remain effective in all the operating modes of the plant or system.

Plant Start-up after certain events

The following table shows the points you have to take into account upon start-up of a plant following certain events.

| lf | Then |
|--|---|
| Start-up follows a voltage drop or failure Start-up of the ET 200X follows an interruption of bus communications | No dangerous operating states may occur. If they do, an emergency stop must be triggered. |
| Start-up follows unlocking of the EMERGENCY STOP device | There must not be an uncontrolled or undefined start-up. |

24 VDC supply

The following table shows you the items you have to take into account in respect of the 24 VDC supply.

| With | Pay attention to | | |
|-----------------------------------|--|---|--|
| Buildings | Outdoor lightning protection | Take lightning protection precautions | |
| 24 VDC supply lines, signal lines | Indoor lightning protection | for example, lightning conductors | |
| 24 VDC supply | Safe (electrical) isolation of extra-low voltage | | |

Protection against external electrical phenomena

The following table shows you the items you have to take into account in respect of protection against electrical phenomena or faults.

| With | Make sure that |
|---|---|
| Any plant or system in which the ET 200X is installed | The plant or system is connected to a protective ground for diverting electromagnetic interference. |
| Supply, signal and bus lines | The wiring arrangement and installation are correct. |
| Signal and bus lines | Any break of a line or conductor does not result in undefined states of the plant or system. |

4.2 Operating the ET 200X on a grounded supply

In this section, you will find information on the overall configuration of an ET 200X distributed I/O device on a grounded supply (TN-S system). The specific subjects discussed are:

- Circuit-breaking devices, short-circuit and overload protection in accordance with DIN VDE 0100 and DIN VDE 0113
- Load power supplies and load circuits

Definition: Grounded supply

With grounded supplies, the neutral conductor of the system is grounded. A simple ground fault between a live conductor and ground or a grounded section of the plant causes the protective devices to trip.

Components and protective measures

Different components and protective measures are specified for erecting a complete plant. The types of component and the degree to which the protective measures are binding depend on the DIN VDE regulation that applies to the configuration of your plant. The following table refers to Figure 4-1.

| Compare | Ref. to Fig. 4-1 | DIN VDE 0100 | DIN VDE 0113 |
|---|---------------------|--|---|
| Circuit-breaking device for PLC, sensors and si- gnal control elements | 1 | Part 460: Main switch | Part 1: Disconnector |
| Short-circuit and overload protection: Grouped for sensors and signal control elements | 2 | Part 725: Single-pole pro- tection of circuits | Part 1: In the case of a grounded secondary circuit: provide single-pole protection Otherwise: Provide all-pole protection |

Safe electrical isolation

Safe electrical isolation must be provided for:

- Modules that must be supplied with voltages \leq 60 VDC or \leq 25 VAC
- 24 VDC load circuits

Configuring the ET 200X with grounded reference potential

When the ET 200X is configured with grounded reference potential, any interference currents are diverted to the protective ground. The connections must be connected externally or in the connector (see Figure 4-1).

Configuring the ET 200X with ungrounded reference potential

When the ET 200X is configured with ungrounded reference potential, any interference currents that occur are diverted to the protective ground via an RC network in the basic module.

Insulation monitor

You must set up an insulation monitor in the following cases:

- Ungrounded configuration of the ET 200X
- When dangerous system states can occur as a result of double faults

ET 200X in overall configuration

Figure 4-1 shows the location of the ET 200X distributed I/O device in the overall system (load power supply and grounding philosophy) for supply from a TN-S system.



Figure 4-1 Operating the ET 200X with reference potential

4.3 Electrical design of the ET 200X

Electrical isolation between ...

The electrical design of the ET 200X includes isolation between:

- The load circuits and all the other circuit components of the ET 200X
- The PROFIBUS-DP port in the basic module and circuit components

ET 200X configuration

The diagrams below show the potentials in an ET 200X configuration.



Figure 4-2 Potentials present in an ET 200X configuration with motor starter



Figure 4-3 Potentials present in an ET 200X configuration with frequency converter



Figure 4-4 Potentials present in an ET 200X-DESINA configuration



Figure 4-5 Potentials present in an ET 200X-ECOFAST configuration

Note

In the case of the ET 200X-DESINA/ET 200X-ECOFAST distributed I/O device, the frame potentials of the switched and non-switched load voltage are connected to each other.

Note

The following applies to the BM 143-DESINA FO, BM 143-DESINA RS485, and EM 143-DESINA modules:

- · All inputs receive the non-switched load voltage.
- Outputs (if present) of sockets X1, X3, X5, X7 are supplied by the switched load voltage.
- Outputs (if present) of sockets X2, X4, X6, X8 are supplied by the non-switched load voltage.

The outputs of all other expansion modules receive the switched load voltage.

Protection against destruction of components

In order to prevent the components of the ET 200X from being destroyed, you must always protect the supply voltage lines to the electronics/sensors and the load voltage with an external circuit–breaker – for example, Siemens Series 5SN1 that has the following characteristics:

- Protection of the supply voltage for the electronic components/sensors: 230 VAC (with rated current)/max. 6 A: tripping characteristic (type) B or C
- Protection of the load voltage: 230 VAC (with rated current)/max. 16 A: tripping characteristic (type) B or C

4.4 Wiring the ET 200X

Wiring procedure

You have to wire the ET 200X distributed I/O device in several steps. We recommend you adopt the following procedure:

| Step | Procedure | See |
|------|--|---------------|
| 1. | Install the connectors for PROFIBUS-DP, supply and load voltage, if required. | Section 4.4.1 |
| 2. | Wire the above connectors. | Section 4.4.2 |
| 3. | Wire the connectors for connection to the inputs and outputs on the modules. | Section 4.4.4 |
| 4. | Connect the protective ground to the basic module. | Section 4.4.5 |
| 5. | Connect the protective ground to expansion modules with analog inputs and outputs. | Section 4.4.6 |
| 6. | Install the connectors and the plugs for the inputs and outputs on the modules. | Section 4.4.7 |
| 7. | Seal unused sockets with M12 plugs. | |

Table 4-1 Order of steps for wiring the ET 200X

Note

Steps 1 and 2 do not apply to ET 200X-DESINA, because the cables used are of the ready-to-use DESINA hybrid type.

Suitable cable types

The table below shows the suitable cable types and their applications. You can find a list of cables and their order numbers in Appendix

A. If cables other those listed in Appendix A are used for connecting and looping through PROFIBUS-DP, these cables must meet the specification for cable type A as per PROFIBUS-DP.

Table 4-2 Cable types

| Cable type | Application | | |
|--|---|--|--|
| 5-core cable, shielded | Connecting and looping through PROFIBUS-DP and supply voltage to electronics/sensors via a common cable | | |
| 3-core copper cable, flexible | Connecting supply voltage to electronics/sensors or load voltage ¹ | | |
| 2-core cable, shielded (bus cable) | Connecting and looping through PROFIBUS-DP | | |
| DESINA hybrid cable (fiber-optic cable or RS 485, prepared | Connecting and looping through PROFIBUS-DP and non-switched and switched supply voltages via a common cable | | |
| with a DESINA connector) | The DESINA hybrid cable is supplied ready for use (wired) with DESINA connectors in various lengths. See Appendix A. | | |
| 3-, 4- or 5-core copper cable, flexible | Connecting the actuators and sensors to the digital inputs/outputs ² | | |
| 4-core copper cable, shielded | Connecting the actuators and sensors to the analog inputs/outputs ² | | |
| 4 or 6-core copper cable, flexible | Connecting the motor starter³: The load and brake supply voltage (with looping through) A load (with brake, only a 6-core cable can be used; see the <i>EM 300</i> Motor Starters manual for order number) | | |
| 4-, or 8-core copper cable, flexible, shielded | Connecting the frequency converter⁴: The load supply voltage (with looping through) A load with brake and thermistor (only an 8-core cable) For order number see <i>EM 148-FC frequency converter</i> Manual | | |

¹ Core cross-section must be $\leq 2.5 \text{ mm}^2$

² Core cross-section must be $\leq 0.75 \text{ mm}^2$

³ Core cross-section must be = $1.5 \text{ or } 2.5 \text{ mm}^2$

⁴ Core cross-section must be = 1.5, 2.5 or 4 mm^2

| Parameters | Value | |
|--|---|--|
| Type of cable | | |
| With PVC sheath | 02Y(ST)C 1×2×0.65/2.56-150 LI LIY-J Y 3×1×0.75 VI KF30 | |
| With PUR sheath, suitable for drum use | 02Y(ST)C 1×2×0.65/2.56-150 LI LIY-J Y 11 3×1×0.75 PETROL | |
| Cable structure | | |
| a) Core LIY 0.75/1.70 Copper strands 24 × 0.2 BLW Polyvinylchloride sheathing (PVC) Section thickness b) Core 02Y 0.65/2.56 LI Copper strands 19 × 0.13 BLW Celled polyethylene sheathing c) Pair LI02Y(ST)C 1×2×0.25/2.6 2 cores to b) RD, GN braided Aluminum coated foil, overlapped Braided shield made of Cu wires Outer sheath | Ø 1.23 mm Ø 1.7 mm approx. 0.23 mm Ø 0.65 mm Ø 2.56 mm 0.15 mm Ø VZN approx. 65 % | |
| Core | | |
| 1 bundle to c), 3 cores to a) GNYE, BK, BL Filler | | |
| Plastic foil, overlapped | Ø 7.9 mm | |
| Sheath | PVC or PUR | |
| Section thickness | approx. 0.8 mm | |
| Outside diameter | (9.5 ±0.5) mm | |
| Permissible minimum bending radius | | |
| recurrent bending | ≥ 70 mm | |
| once-only bending | ≥ 35 mm | |
| Operating temperature | −30 °C to +60 °C | |
| Weight | approx. 105 kg/km | |

 Table 4-3
 Technical specifications of the 5-core cable

| Parameters | Value |
|--|------------------------------------|
| Electrical properties at 20 °C Tests in accordance with DIN VDE 0472 | |
| Conductor resistance of cores to a) | ≤ 26 Ω/km |
| Conductor resistance of cores to b) | ≤ 84 Ω/km |
| Insulation resistance | ≥ 20 MΩ/km |
| Operating capacity ¹ | ≈ 30 pF/m |
| • Surge impedance at 3 to 20 MHz ¹ | 135 to 165 Ω |
| Wave attenuation at 0.2 MHz¹ | ≤ 0.6 dB/100 m |
| Operating voltage (peak voltage) | 35 V |
| Test voltage (core/core eff. 50 Hz 1 min) | 500 V |
| Test voltage (core/shield eff. 50 Hz 1 min) | 500 V |
| Flame test | to VDE 0472, Part 804, test type B |
| only cables with PUR sheath | |
| Oil resistance | to VDE 0471, Part 804, test type B |
| Suitable for drum use | Yes |

| Table 4-3 | Technical specifications of the 5-core | cable, continued |
|-----------|--|------------------|
|-----------|--|------------------|

1 Values for pair to c)

4.4.1 Installing/removing connectors

To affix the cables and provide IP 65, IP 66, and IP 67 protection, the connectors for PROFIBUS-DP, the supply voltage, and load voltage are supplied with M16 cable glands.

A connector assembly consists of a protective shell, a 6-pin connector, 1(2) M16 cable gland(s) and 1(2) lock nut(s). You can find the order numbers for the connectors in Appendix A.



Figure 4-6 Connector: protective shell with an M16 cable gland

Installing connectors

Proceed as follows to install a connector:

- Pierce the shell of the connector with a screwdriver at the point at which you want to feed through the cable. Risk of injury. Watch your fingers.
- 2. Place the lock nut in the shell over the pierced hole.
- 3. Screw the M16 cable gland tightly onto the protective shell.

Note: If you feed PROFIBUS-DP and the supply voltage for the electronic components/sensors to the basic module via 2 separate cables, you must install two M16 cable glands on the protective shell.

- 4. Feed the cable through the installed M16 cable gland.
- 5. Wire the 6-pin plug connector (see Section 4.4.2). In doing so, comply with the wiring rules listed in Table 4-4.
- 6. Withdraw the cable until the start of the sheath is roughly level with the start of the M16 cable gland, then screw the M16 cable gland tight (the sheath is clamped).
- 7. Feed the wired plug connector back into the shell until it snaps into place. This is shown in the diagram below (apart from the wiring).



Figure 4-7 Snapping the connector into place in the shell

Removing connectors

If you want to remove a connector, proceed as follows

- 1. Release the two locking hooks as illustrated in Figure 4-8 using a pointed implement.
- 2. Remove the connector from the shell.



Figure 4-8 Removing the connector from the shell

4.4.2 Wiring connectors

Rules for wiring connectors

The following table shows you the rules you have to take into account in respect of the wiring of the connectors.

| Table 4-4 | Wiring r | ules for | connectors |
|-----------|----------|----------|------------|
|-----------|----------|----------|------------|

| Rules for | Wiring connectors |
|---|--|
| Connectable core cross-sections: | |
| Solid conductors | Options for PROFIBUS-DP connection:2-core cable, shielded (bus cable)Direct-buried cable |
| Flexible conductors | |
| with wire end ferrule | 0.25 to 1.5 mm ² |
| without wire end ferrule | 0.25 to 2.5 mm ² |
| Number of cores per terminal connection | 1 or combination of 2 cores up to 1.5 mm ² (sum) in a common wire end ferrule |
| Permissible outside diameter of cable | Ø 4 to 10 mm |
| Bared length of cores (with or without insulation collar) | 6 mm |
| Bared length of cable sheath | 45 mm |
| Wire end ferrules to DIN 46228 | |
| without insulation collar | Form A up to 7 mm long |
| with insulation collar | Form E up to 8 mm long |

Bared Lengths: Example

The diagram below shows an example of bared lengths. These lengths apply to all cables that are suitable for use with the connector assembly. Braided shields must be twisted and inserted into wire end ferrules, and the projecting lengths cut off. The shield around the PROFIBUS cores must be brought as close as possible to the connectors.



Figure 4-9 Bared length of a 5-core cable

Connection alternatives

The following connection alternatives are available for the ET 200X in accordance with the configuration options:

- Supply voltage for the electronics/sensors and PROFIBUS-DP fed via a common cable
- Supply voltage for the electronics/sensors and PROFIBUS-DP fed via separate cables

The load voltage must either be fed separately to each ET 200X or looped through.

Wiring of PROFIBUS-DP and supply voltage

If you want to feed PROFIBUS-DP and the supply voltage for the electronics/sensors to the basic module separately, you will need:

- A connector
- A 2-core cable, shielded for the PROFIBUS-DP terminal connection (the braided shield must be twisted, inserted in a wire end ferrule and connected to pin 2 of the shield; see Figure 4-10)
- A 3-core, flexible copper cable for the supply voltage connection

If you want to feed PROFIBUS-DP and the supply voltage for the electronics/sensors to the basic module via a common cable, you will need a 5-core, shielded cable in addition to the connector (6ES7 194-1LY00-0AA0-Z).

Connector pinout

You must always wire the connector as shown in the diagram below, irrespective of whether you are using one or two cables. The pins for the PROFIBUS-DP terminal connection are highlighted in bold type.





Looping through PROFIBUS-DP and supply voltage

If you want to loop PROFIBUS-DP and/or the supply voltage for the electronics/sensors through to the next ET 200X, you have to wire the second connector. This connector must be wired in exactly the same way as the connector for feeding the first ET 200X (see Figure 4-10).

Wiring of load power supply

If you want to connect a load power supply (24 VDC), you will need:

- A connector
- A 3-core, flexible Cu cable

Wire the connector to pins 1, 2 and 3 as shown in the diagram below. Terminals 1 and 4; 2 and 5; 3 and 6 are internally jumpered.



Figure 4-11 Pinout of the load voltage connector



Caution

If you wire the connectors incorrectly, the device or its components may be damaged beyond repair!

Looping through load voltage

If you want to loop a load voltage (24 VDC) through to the next ET 200X, you must wire a 3-core, flexible, copper cable to the connector (pins 4, 5 and 6) in addition to the wiring arrangement shown in Figure 4-11. Then wire the other end of the cable to pins 1, 2 and 3 of the next load voltage connector.

Always use the same core colors for the same signals.

Note

The load voltage can be looped through from the power module only when the connector is plugged into the power module.

Looping through the load voltage from the power module

If you want to loop the load voltage through to the next power module or ET 200X, you must install a second M16 cable gland on the connector (see wiring in Figure 4-11).



Figure 4-12 Power module with connector and 2 M16 cable glands

Note

The load voltage can be looped through from the power module only when the connector is plugged into the power module.

Using a common power supply

You can feed the supply voltage for the electronics/sensors and for loads from a single power supply, providing no electrical isolation is necessary between the sensor and the load supply. You simply need to wire the two connectors together externally (L+, M and PE). Note the restrictions imposed by the current consumption (see Section 2.8)! If necessary, use a power module or a SITOP power 24V/10A.

Always plug in 3 connectors

Note

You must always plug all three connectors into the basic module, irrespective of whether or not they are wired, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

An alternative is to close unused connectors with covers. You can find the order numbers for the covers in Appendix A.

4.4.3 Pinout of the ET 200X-DESINA / ET 200X-ECOFAST



Figure 4-13 shows the pinout of the connector for the BM 143-DESINA FO basic module.

Figure 4-13 Pinout of the connector for the BM 143-DESINA FO

Figure 4-14 shows the pinout of the connector for the BM 141-ECOFAST and BM 143-DESINA RS485 basic modules.



Figure 4-14 Pinout of the connector for the BM 141-ECOFAST and BM 143-DESINA RS485 basic modules

4.4.4 Wiring the connectors for inputs and outputs

Connectors for digital inputs and outputs

You can connect digital inputs and outputs to the round, 5-pin M12 sockets on the front of the basic/expansion modules. Alternatively, you can use 5-pin M12 coupler plugs or Y connectors. Please refer to Appendix A for the order numbers.

Connectors for analog inputs and outputs

You connect analog inputs and outputs to the round, 5-pin M12 sockets on the front of the expansion module. You use 4- or 5-pin M12 coupler plugs. You can obtain further information on the connectors on request:

| • | 4-pin | Outgoing cable unit PG 7 | 99-1429-814-04 |
|---|-------|--------------------------|----------------|
| • | 4-pin | Outgoing cable unit PG 9 | 99-1429-812-04 |
| • | 5-pin | Outgoing cable unit PG 7 | 99-1437-814-05 |

• 5-pin Outgoing cable unit PG 9 99-1437-812-05

Address for ordering:

Franz Binder GmbH + Co. Elektrische Bauelemente KG Rötelstraße 27 D-74172 Neckarsulm

Wiring of M12 coupler plug for digital inputs

To connect the digital inputs, you require:

- A 5-pin, M12 coupler plug, possibly integrally molded
- A flexible 3-, 4- or 5-core copper cable with a core cross-section of $\leq 0.75 \text{ mm}^2$

Wire the coupler plug in accordance with the pinout table below. The pinout of the sockets X1 to X4/X8, which are used for the inputs on the ET 200X, is shown together with the data for the individual modules in Section 7.1 ff.

Table 4-5 Pinout of the coupler plug for digital inputs

| Pin | Assignment | View of coupler plug (wiring side) |
|-----|-------------------------------|---------------------------------------|
| 1 | 24 V power supply for sensor* | |
| 2** | Input signal | |
| 3 | Chassis ground, power supply | |
| 4 | Input signal | |
| 5 | PE | |

* Made available by the ET 200X for the connected sensor

* Only relevant if socket has 2 assigned channels

Note

If a sensor has a normally-closed contact and a normally-open contact, the normally-closed contact is automatically wired to pin 2. The channel assigned to pin 2 can thus no longer be used for the adjacent socket.

Wiring of M12 coupler plug for digital inputs (DESINA/ECOFAST)

To connect the digital inputs, you require:

- A 5-pin, M12 coupler plug, possibly integrally molded
- A flexible 4- or 5-core copper cable with a core cross-section of $\leq 0.75 \text{ mm}^2$

Wire the coupler plug in accordance with the pinout table below. The pinout of sockets X1 to X8, which are used for the inputs on the

ET 200X-DESINA/ECOFAST, is shown together with the data for the individual modules in Section 7.5 ff.

Connecting digital inputs (DESINA):

You have set the following parameters: Pin 2 as diagnostic input and pin 4 as digital input.

- Channel type (pin 4): digital input
- Input functionality (pin 2): diagnostic input

| Pin | Assignment for digital input (DESINA) | View of coupler plug (wiring side) |
|-----|---------------------------------------|---------------------------------------|
| 1 | 24 V power supply for sensor* | Digital input |
| 2 | Diagnostic input of DESINA sensor | |
| 3 | Chassis ground, power supply | |
| 4 | Input signal from DESINA sensor | |
| 5 | not assigned | |

| Table 4-6 F | Pinout of the coupler p | plug for digita | inputs (DESINA) |
|-------------|-------------------------|-----------------|-----------------|
|-------------|-------------------------|-----------------|-----------------|

* Made available by the ET 200X-DESINA/ET 200X-ECOFAST for the connected sensor

Connecting digital inputs (standard):

You have set the following parameters: Pin 2 as input with NC function and pin 4 as digital input.

- Channel type (pin 4): digital input
- Input functionality (pin 2): input with NC function

Table 4-7 Pinout of the coupler plug for digital inputs (standard)

| Pin | Assignment for digital input (standard) | View of coupler plug (wiring side) |
|-----|---|---------------------------------------|
| 1 | 24 V power supply for sensor* | Digital inputs (standard) |
| 2 | Input signal** (NC function) | |
| 3 | Chassis ground, power supply | |
| 4 | Input signal | |
| 5 | not assigned | |

Made available by the ET 200X-DESINA/ET 200X-ECOFAST for the connected sensor
 NC function:

Non-switched means:To the process when status is "1", in PII status "0";switched means:To the process when status is "0", in PII status "1"

Wiring of M12 coupler plug for digital outputs

To connect the digital inputs, you require:

- A 5-pin, M12 coupler plug, possibly integrally molded
- A flexible, 3- or 4-core copper cable with a core cross-section of $\leq 0.75 \text{ mm}^2$

Wire the coupler plug in accordance with the pinout table below. The pinout of sockets X1 to X4/X8, which are used for the outputs on the ET 200X, is shown in Section 7.4 ff.

| Pin | Assignment | View of coupler plug (wiring side) |
|-----|------------------------------|---------------------------------------|
| 1 | - | |
| 2* | Output signal | |
| 3 | Chassis ground, load voltage | |
| 4 | Output signal | |
| 5 | PE | |

Table 4-8 Pinout of the coupler plug for digital outputs

* Only relevant if socket has 2 assigned channels

Wiring of M12 coupler plug for digital inputs (DESINA/ECOFAST)

To connect the digital inputs, you require:

- A 5-pin, M12 coupler plug, possibly integrally molded
- A flexible 4- or 5-core copper cable with a core cross-section of $\leq 0.75 \text{ mm}^2$

Wire the coupler plug in accordance with the pinout table below. You can find the pinout of sockets X1 to X8 which are used for the outputs on the ET 200X-DESINA/ET 200X-ECOFAST as of Section 7.5.

Connecting digital outputs (DESINA):

Your parameter settings are as follows:

- Channel type (pin 4): digital output
- Input functionality (pin 2): diagnostic input

| Table 4-9 | Pinout of the coupler plug for digital outputs (DESI | NA) |
|-----------|--|-----|
|-----------|--|-----|

| Pin | Assignment for digital output (DESINA) | View of coupler plug (wiring side) |
|-----|---|---------------------------------------|
| 1 | 24 V power supply for diagnostics input* | Digital output (DE- SINA) |
| 2 | Diagnostic input | |
| 3 | Chassis ground, load supply | |
| 4 | Output signal to DESINA actuator | |
| 5 | not assigned | |

* Made available by the ET 200X-DESINA for the diagnostics input

Connecting digital outputs (standard):

Your parameter settings are as follows:

- Channel type (pin 4): digital output
- Input functionality (pin 2): diagnostic input

Table 4-10 Pinout of the coupler plug for digital outputs (standard)

| Pin | Assignment for digital output (standard) | View of coupler plug (wiring side) |
|-----|---|---------------------------------------|
| 1 | 24 V power supply for diagnostics input* | |
| 2 | Diagnostic input | Digital output |
| 3 | Chassis ground, load supply | |
| 4 | Output signal to actuator | Diagnostics |
| 5 | not assigned | input |

* Made available by the ET 200X-DESINA/ET 200X-ECOFAST for the diagnostic input

Y connector

The Y connector permits double wiring of actuators and sensors at the inputs or outputs of the ET 200X.

It is advisable to use the Y connector if each socket of a module has two assigned channels. The Y connector divides the two channels between two coupler plugs (see Tables 4-11 and 4-12 for pinout).

Note: You cannot use the Y connector in conjunction with the M12, 5-pin angular coupler plug.





Note

The Y connector **cannot** be used on the expansion modules EM 141 DI 8 x DC 24V (long type of construction) and EM 142 DO 8 x DC 24V/1.2A.

Wiring of coupler plugs (DI) for Y connector

To connect the digital inputs using a Y connector, you require:

- A Y connector and 2 M12 coupler plugs
- A flexible, 3- or 4-core copper cable with a core cross-section of $\leq\,0.75~\text{mm}^2$

Wire the two M12 coupler plugs for the Y connector in accordance with the pinout table below. The assignment of pin 4 depends on the socket of the ET 200X to which you screw the Y connector.

Table 4-11 Pinout of the coupler plugs for digital inputs when a Y connector is used

| Pin | Coupler plug assignment | | View of |
|-----|---|---|---|
| | A (top) | B (bottom) | Y connector |
| 1 | 24 V power supply for sensor* | | |
| 2 | - | - | |
| 3 | Chassis ground, power supply | | $\bigcirc 3 \bigcirc 5 \bigcirc 1$ (top) |
| 4 | Input signal on socket X1: channel 0 socket X2: channel 1 socket X3: channel 2 socket X4: channel 3 | Input signal on so. X1: channel 4/1** so. X2: channel 5/-** so. X3: channel 6/3** so. X4: channel 7/-** | $\bigcirc 2 \\ \bigcirc 2 \\ \bigcirc 0 \\ \bigcirc 2 \\ \bigcirc 1 \\ \bigcirc 5 \\ \bigcirc 3 \\ \bigcirc 4 \\ B \\ \bigcirc 4 \\ B \\ \bigcirc 4 \\ B \\ \bigcirc B \\ \bigcirc 4 \\ \bigcirc B \\ \bigcirc 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\$ |
| 5 | PE | | (bottom) |

* Made available by the ET 200X for the connected sensor

** Channel specified after the "/" valid if the BM/EM has four channels
Wiring of coupler plugs (DO) for Y connector

To connect the digital outputs using a Y connector, you require:

- A Y connector
- Two M12 coupler plugs
- A flexible, 3- or 4-core copper cable with a core cross-section of $\leq 0.75 \text{ mm}^2$

Wire the two M12 coupler plugs for the Y connector in accordance with the pinout table below. The assignment of pin 4 depends on the socket of the ET 200X to which you screw the Y connector.

Table 4-12 Pinout of the coupler plugs for digital outputs when a Y connector is used

| Pin | Coupler plug | View of | |
|-----|--|--|--|
| | A (top) | B (bottom) | Y connector |
| 1 | _ | | <u> </u> |
| 2 | _ | _ | $\begin{pmatrix} 04 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 $ |
| 3 | Chassis ground, load | | |
| 4 | Output signal on socket X1: channel 0 socket X2: channel 1 socket X3: channel 2 socket X4: channel 3 | Output signal on socket X1: channel 1 socket X2: – socket X3: channel 3 socket X4: – | $\begin{array}{c} 02 \\ 02 \\ 01 \\ 05 \\ 03 \\ 04 \end{array}$ |
| 5 | PE | | (bottom) |

Pinout of the sockets for inputs/outputs

The pinout of the sockets for inputs/outputs is shown together with the data for the individual modules in Section 7.1 ff.

Wiring the M12 coupler plug for analog inputs and outputs

To connect the analog inputs and analog outputs, you require:

- A 4- or 5-pin, M12 coupler plug
- A shielded 4-core copper cable with a core cross-section of $\,\leq\,0.75~\text{mm}^2$

Wire the coupler plug in accordance with the pinout of the sockets on the expansion module. You will find the pinout in the information on the various modules as of Section 7.21.9. You may have to connect the expansion module to the protective ground (see Section 4.4.6).

4.4.5 Connecting the protective ground to the basic module

Protective ground connection

You must connect the protective ground to the basic module. A grounding screw is provided on the basic module for this purpose.

Minimum cross-section from the conductor to the protective ground: 4 mm².

The connection to the protective ground is also required to divert the interference currents and for EMC resistance. To improve the EMC performance, it is advisable to select the largest possible cross-section for the wire to the protective ground (e.g. copper braided cable).

Note

Make sure that the protective ground connection always has a low impedance.

Figure 4-16 shows how the protective ground connects to the BM 141, BM 142 and BM 147/CPU basic modules. The fixing screw M5 is enclosed with the basic module as standard.



Figure 4-16 Connecting the protective ground to the BM 141, 142 and 147/CPU basic modules

Figure 4-17 shows how the basic modules BM 143-DESINA FO, BM 143-DESINA RS485, and BM 141 DI $8 \times$ DC 24V ECOFAST must be connected to protective ground.



Figure 4-17 Connecting the basic modules BM 143-DESINA FO, BM 143-DESINA RS485, and BM 141 DI $8 \times DC$ 24V ECOFAST to protective ground

EMC

You will find additional notes on EMC installation and wiring in the manual for the DP master you are using or for the host system.

4.4.6 Connecting a protective ground to expansion modules with analog inputs and outputs

Grounding expansion modules with AI/IO

To ensure the ET 200X remains operative even when subject to interference (especially RF coupling in accordance with ENV 50141), you must ground every expansion module with analog inputs or outputs **separately**.

Connection to protective ground

You must connect the protective ground to the expansion module. A grounding screw is provided on the expansion module for this purpose. You either connect the protective ground to the PE screw of the basic module (see Section 4.4.5) or directly to protective ground. Minimum cross-section from the conductor to the protective ground: 4 mm².

Note

Make sure that the protective ground has a low impedance (Figure 4-18).

Figure4-18 shows you how to connect the protective earth to the analog module. The M5 fixing screw is attached to the analog module such that it cannot get lost.



Figure 4-18 Connecting the protective ground to the analog module

EMC

You will find additional notes on EMC installation and wiring in the manual for the DP master you are using or for the host system.

4.4.7 Plugging the connectors into the ET 200X

Requirements for plugging in connectors

You must have wired the cables to the connectors. In addition, you must have set the PROFIBUS address (in accordance with your configuration) and if necessary connected the terminating resistance.

Plugging connectors into the ET 200X

Proceed as follows after you have completed the wiring:

- 1. Press two fixing screws into each connector and plug the connectors into the plate.
- 2. Plug the plate with the two connectors and the connector for the load voltage into the basic module. Note the mechanical polarization of the connector plate.

Note: You must always plug all three connectors into the basic module irrespective of whether or not they are wired in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved. An alternative is to close unused connectors with covers.

- 3. Screw the connectors tightly onto the basic module with a torque of max. 0.8 Nm.
- 4. Plug all the other connectors into the appropriate sockets on the front of the basic module/expansion modules.



Caution

The connector for the load voltage, the coupler plugs and the Y connectors must not be removed from the sockets for the inputs/outputs while the ET 200X is operating, nor must the power connectors be removed from the motor starters or frequency converters.

You should therefore always either disconnect the ET 200X from PROFIBUS-DP (by removing the PROFIBUS-DP connector) or switch off the supply voltage to the electronics/sensors, the load voltage and the load before you remove the above connectors!

Installing the connector on the ET 200X-DESINA/ET 200X-ECOFAST

Proceed as follows after you have completed the wiring of the sensors and actuators:

- 1. Push up the latch for the DESINA connectors on the basic module.
- Plug the DESINA connectors (non-switched and switched load voltages and PROFIBUS-DP via fiber-optic or copper cables) into the sockets on the basic module. Note the mechanical coding of the connectors for feed and loop-through.

Note: You must always plug both DESINA connectors into the basic module in order to ensure that the degree of protection (IP 65, IP 66, or IP 67) is achieved. Fit a cover if a DESINA socket remains unused. You can find the order numbers for the covers in Appendix A.

3. Push down the latch for the DESINA connectors.



Figure 4-19 Plugging connectors into the ET 200X-DESINA/ET 200X-ECOFAST

4. Plug all the other connectors into the appropriate sockets on the front of the basic module/expansion modules.



Caution

Do not unplug the DESINA connectors or the coupler plugs for the inputs/outputs or the power connector for the motor starters or frequency converters while the ET 200X-DESINA/ET 200X-ECOFAST is operating, or the modules may be damaged or possibly even destroyed.

Always switch off the non-switched and switched load voltages and loads before unplugging the connectors.

Installing connectors on analog modules

Note

You must push the M12 coupler plug securely into the analog socket (against the resistance of the shield plate) so that the thread of the coupler plug is engaged. When doing this, watch the mechanical coding on the connector.

Installing connectors on power modules

Install the connector with the two **short** screws on the power module. The short screws are enclosed with the power module as standard.

Covering up unused sockets

You must seal off any sockets which are not required with M12 screw caps in order to ensure the degree of protection (IP 65, IP 66 or IP 67) is maintained. You can find the order numbers for the M12 screw caps in Appendix A.

Wired ET 200X

The diagram below shows a wired ET 200X. (The power connectors for the load supply voltage and the load on the motor starter are not featured here.)



Figure 4-20 Wired ET 200X

4.4.8 Wiring the SITOP power power supply and adapting It to deployment conditions

Only very little wiring work is required to integrate the SITOP power 24V/10A power supply into the ET 200X. The output voltage can either be used as supply voltage for electronics/sensors and/or load voltage. The power supply response in the event of a fault can be parameterized.

Wiring



Warning

Before starting the installation work, the main switch on the system is to be switched off and secured to prevent it from being turned on again. If this point is not observed, death or severe physical injury may be caused through touching live components.

Proceed as follows to wire the SITOP power:

 The connections for the incoming voltage are accessible once the terminal cover has been removed. Undo the four screws to gain access ¹



Caution

Only qualified personnel may open the device. They must know how to handle electrostatic sensitive devices (ESD).



Figure 4-21 Removing the terminal cover

- 2. Take off the terminal cover. When doing this, make sure that the seal is not damaged.
- 3. Feed the power cable through the M16 cable gland. The outside diameter of the mains power supply cable must be between 4 mm and 10 mm and be suitable for special operating conditions (environmental influences).
- Connect the mains power supply cable to supply terminals L1, N and PE (≟). Conductor cross-sections between 0.5 mm² and 2.5 mm² can be clamped.

Note

The screw-type terminals can be plugged in as a unit.



Figure 4-22 Connecting the mains power supply cable

Note

When installing the SITOP power 24V/10A power supply, the relevant DIN/VDE regulations or the regulations specific to the country are to be observed.

The supply voltage (120/230 VAC) must be in accordance with VDE 0100 and VDE 0160. A protective device (fuse) and disconnecting device to isolate the power supply must be provided.

Operation on 120 VAC

When operating on a 120 VAC power supply, a bridge must be wired between the two "AC 120V LINK" terminals. The bridge must have the same cross-section and insulation as the mains power supply cable. The length must not exceed 100 mm.



Warning

Even the optional bridge carries dangerous electrical voltage!

5. Install the M16 cable gland(s).

6. If required, make the following settings:

Setting the output voltage

The output voltage can be set in the range from 22.8 V to 25.2 V using potentiometer R306.



Figure 4-23 Potentiometer R306 for setting the output voltage



Warning

Potentiometer R306 may only be operated with an insulated screwdriver in accordance with DIN 7437, because components carrying dangerous electrical voltage may be touched unintentionally.

Switching the output voltage to the bus segment of the ET 200X

The top section of the SITOP power must be removed to make the following settings.



Warning

The top section may only be removed when the mains voltage has been switched off and measures put in place to ensure that it cannot be turned on again.

Undo the six screws **2** and remove the top section. When doing this, make sure that the seal is not damaged.



Figure 4-24 Removing the top section

The output voltage can be switched on the underside of the top section by rearranging adapter plate A1 on the various bus segments of the ET 200X. For this, the combinations listed in Table 4-13 are possible. In the case of adapter position IV, basic insulation is provided between the bus segments and the output terminals (for an insulation rating voltage of 400 VAC).

The reference potential of the supply voltage for electronics/sensor 1L+ and load voltage supply 2L+ are not floating.

| Position of Supply adapter plate Voltage for A1 electronics/ sensor 1L+ | | Load voltage supply 2L+ | Output terminals | |
|--|---|-------------------------------|---------------------|--------------------------|
| I | x | - | x | |
| П | x | x | x | |
| III | - | x | x | "As delivered" condition |
| IV | - | - | x | |

x: Voltage present

-: No voltage present



Figure 4-25 Positions of adapter plate A1

Switching over the short circuit response

The SITOP power response in the event of a short circuit on the output side can be switched over using potentiometer R230.

Table 4-14 Switching over the short circuit response

| Position of potentiometers R230 | Response in the event of a short circuit | |
|---------------------------------|--|--------------------------|
| Right-hand stop "RESTART" | Automatic attempts to start up | "As delivered" condition |
| Left-hand stop "STORE" | Stored shutdown. RESET by switching off the mains voltage for at least 5 minutes. | |



Figure 4-26 Position of the R230 potentiometer

Switching over the power supply

Output current limitation can be changed by rearranging adapter plate A2.

Note

Switching over to 10 A is only permissible at ambient temperature < 40 °C.

| Table 4-15 | Switching over | current limiting |
|------------|----------------|------------------|
|------------|----------------|------------------|

| Position of adapter plate A2 | Application of current limiting at approx. | |
|------------------------------|--|--------------------------|
| 8 A | 9.5 A | "As delivered" condition |
| 10 A | 11 A | |



Figure 4-27 Positions of the adapter plate A2

7. Refit the top section and the terminal cover and screw down both units securely.

Note

In order to ensure that IP 65 degree of protection is maintained, once the wiring and setting is complete, all M16 cable glands and covers must be screwed together correctly.

Tightening torque

- For casing screws: 0.5 Nm
- For M16 cable glands: tighten the cap nut until the rubber seal lies on the cable. Then tighten for a further ¹/₂ turn.

Commissioning and Diagnostics

Contents of Chapter

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5.1 Configuring ET 200X-DESINA

Introduction

An ET 200X-DESINA channel assumes the functionality determined by the settings sent to it on parameterization.

The possibilities are:

- Digital input
- Digital output
- Diagnostic input
- Diagnostics input with diagnostics frame
- Input with NC function

Parameterization for the functional input (Pin 2) is displayed and analyzed in accordance with Table5-1.

≻ pin 2

| Table 5-1 | Display and analysis of the parameters for the DESINA functional input |
|-----------|--|
| | |

| Pin 2 is "1" (+24 V) Process image is always "0" | LEDs | Analysis | | |
|---|-----------|---|--|--|
| Diagnostics input (default) | Red⇒off | Process image | | |
| Diagnostics input with diagnostics frame | Red⇒off | Process image and SFC 13, for example (see Section 5.6.1) | | |
| Input with NC function | Yellow⇒on | Process image | | |

| Pin 2 is "0" Process image is always "1" | LEDs | Analysis |
|---|------------|---|
| Diagnostics input (default) | Red⇒on | Process image |
| Diagnostics input with diagnostics frame | Red⇒on | Process image and SFC 13, for example (see Section 5.6.1) |
| Input with NC function | Yellow⇒off | Process image |

Configuration

2 bytes for inputs and 2 bytes for outputs are reserved for data transfer in the process image (PI). In the process image the input and output ranges must not be at the same address.

Figure 5-1 shows the arrangement of the digital inputs and outputs on the BM 143-DESINA and EM 143-DESINA in relation to the bits of the inputs and outputs in the PI.



Figure 5-1 Correlation of DIs/DOs on BM 143-DESINA/EM 143-DESINA with bits of inputs/outputs in the PI

Signals (user data) and diagnostics data are mutually independent. The diagnostics input merely shows the state of the sensor or actuator; there is no defined effect on the signal. The necessary or desired reaction can only be derived from the application.

The examples below illustrate the relationship between the individual signals and the diagnostic inputs.

Bit assignment of the inputs

In the PI, inputs are assigned as shown in Figure 5-2.

| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Bit |
|---|---------------------------|------|--|-----|-----|-----|-----|-----|-----|
| Byte 0 | ND7 | ND6 | ND5 | ND4 | ND3 | ND2 | ND1 | ND0 | |
| Byte 1 | FI7 | FI6 | FI5 | FI4 | FI3 | FI2 | FI1 | FI0 | |
| ND0 ND7: Signal (user datum, digital) channel 0 to channel 7 | | | | | | | | | |
| | FI0 F | ·17: | Functional input (diagnostics datum) channel 0 to channel 7 Each functional input can be parameterized – as a diagnostics input or – as an input with NC function. | | | | | | |
| | Default: diagnostic input | | | | | | | | |

Figure 5-2 Assignment of the inputs in the process image (PI)

Bit assignment of the outputs

In the PI, outputs are assigned as shown in Figure 5-3.

| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Bit |
|--------------------------|-----|------|----------------|----------------------|------------------|-----------------|-----|-----|-----|
| Byte 0 | ND7 | ND6 | ND5 | ND4 | ND3 | ND2 | ND1 | ND0 | |
| Byte 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| | ND0 | ND7: | Signa chann | l (user o el 0 to | datum, channe | digital) I 7 | | | |
| Byte 1 is not used (= 0) | | | | | | | | | |



Examples of assignment

1. The 8 channels of a BM 143-DESINA are to be parameterized as $5 \times DIs + 3 \times DOs$. The functional inputs are parameterized as diagnostics inputs.

| Channel |
|---------|---------|---------|---------|---------|---------|---------|---------|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| DI | DI | DO | DI | DO | DI | DO | DI |

PII: 7 6 5 4 3 2 0 Bit 1 Byte 0 ND7 ND6 0 ND4 0 ND2 0 ND0 FI7 FI6 FI5 FI4 FI3 FI2 FI1 FI0 Byte 1 (D) (D) (D) (D) (D) (D) (D) (D) PIO: Byte 0 0 0 ND5 0 ND3 0 ND1 0 0 0 0 0 0 0 0 0 Byte 1

The input/output assignment in the process image is thus:

FEn (D): Diagnostics input n

The arrows indicate the permanent relationship between signal and diagnostics input.

The following applies in the example: Diagnosis for channel 0 (DI) is in bit 0 of byte 1 of the PII Diagnosis for channel 1 (DO) is in bit 1 of byte 1 of the PII Diagnosis for channel 2 (DI) is in bit 2 of byte 1 of the PII

- •

This assignment has to be taken into account when the application is programmed.

2. The 8 channels of a EM 143-DESINA are to be parameterized as $5 \times DIs + 3 \times DOs$. Of these, two DIs should have NC functionality. The remaining six functional inputs are parameterized as diagnostics inputs.

| Channel | Channel | Channel | Channel | channel | Channel | Channel | Channel |
|-----------------------|---------|-----------------------|---------|---------|---------|---------|---------|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| DI (NC contact) | DI | DI (NC contact) | DI | DI | DO | DO | DO |



The input/output assignment in the process image is thus:

FEn (D): Diagnostics input n

FEn (Ö): Input with NC functionality

The arrows indicate the permanent relationship between signal and diagnostics input. This assignment has to be taken into account when the application is programmed.

5.2 Commissioning and starting up the DP slave

Software requirements

| Project software used | Version | Explanations |
|--|--------------------|--|
| STEP 7 | \leq Version 3.1 | The type file of the DP slave is integrated in <i>STEP 7</i> . |
| | > Version 3.1 | Included in STEP 7 or new modules to be embedded with OM or type file |
| COM PROFIBUS | \geq Version 2.1 | You have embedded the type file of the DP slave in <i>COM PROFIBUS</i> . |
| Configuration software for a different DP master being used | | You require the device master file and the contents of the configuration frame and parameter assignment frame for the DP slave (refer to Appendix B and the <i>configuration and parameter</i> <i>assignment frame for ET 200X</i> at http://www.ad.siemens.de/simatic-cs). |

| <u> </u> | | | | | | | | |
|-----------|------------|--------------|-----|-----------------|-------|------|------|------------|
| Table 5-2 | Software | requirements | f∩r | commissioning : | an FT | 200X | AUXO | nt DESINA) |
| | Soliware i | equiremento | iui | commissioning a | | 2007 | | |

| Project software used | Version | Explanations |
|--|-----------------------------------|--|
| | ET 200X with BM | 143-DESINA FO |
| STEP 7 | \geq Version 5.0 and Service | You have embedded the device master file of the DP slave in STEP 7 or |
| | Pack 3 | You use HWCONFIG. As of Service Pack 3, the ET 200X-DESINA with fiber-optic cable is included in the hardware catalog. |
| | ET 200X with BM BM 141 DI 8×DC | 143-DESINA RS485/ 24V ECOFAST |
| STEP 7 | \geq Version 5.1 and Service | You have embedded the device master file of the DP slave in STEP 7 or |
| | Pack 2 | You use HWCONFIG. As of Service Pack 2, the ET 200X with RS 485 is included in the hardware catalog. |
| | ET 200X with BM | 141 DI 8×DC 24V ECOFAST DIAG |
| STEP 7 | \geq Version 5.1 and Service | You have embedded the device master file of the DP slave in STEP 7 or |
| | Pack 4 | You use HWCONFIG. As of Service Pack 4, the ET 200X with RS 485 is included in the hardware catalog. |
| COM PROFIBUS | \geq Version 2.1 | You have embedded the device master file of the DP slave in <i>COM PROFIBUS</i> (refer to Appendix B). |
| Configuration software for a different DP master being used | | You require the device master file and the contents of the configuration frame and parameter assignment frame for the DP slave (refer to Appendix B and <i>configuration and parameter</i> <i>assignment frame for ET 200X</i> at http://www.ad.siemens.de/simatic-cs). |

| Table 5-3 | Software requirements for comm | issioning an ET 200X-DESINA |
|-----------|--------------------------------|-----------------------------|
|-----------|--------------------------------|-----------------------------|

Device master file

You can download the DDB file

• From the Internet at http://www.ad.siemens.de/csi_e/gsd

Integrating the DDB file in the configuration software

The following table 5-4 tells you how to integrate the type file in SIMATIC S7 or SIMATIC S5 (COM PROFIBUS).

| Step | STEP 7, as of V3.1 | COM PROFIBUS, as of V2.1 ¹ |
|------|---|---|
| 1 | Start STEP 7 and in HWCONFIG call the Options ► Install New GSD menu command. | Copy the DDB file from the ET 200X to the COM PROFIBUS directory:CPBV.\GSD (default) |
| | | Copy the bitmap file to the directory:CPBV\BITMAPS |
| 2 | Select the DBB file you want to install from the following dialog box and confirm with OK. Result: The ET 200X is displayed in the hard- ware catalog in the PROFIBUS-DP directory. | Start COM PROFIBUS, and choose the File ► Read GSD File menu command. Result: The ET 200X is displayed in the hardware catalog at slave configuration. |
| 3 | Configure the ET 200X with STEP 7 (see the integrated help system in STEP 7). | Configure the ET 200X with COM PROFIBUS (see the integrated help system in COM PROFIBUS). |

 Table 5-4
 Integrating the DDB file in the configuration software

¹ If you are using a different configuration software package, refer to its software documentation

Function: Direct communication between basic modules

In *STEP* 7 V5.0 and later, you can configure direct communication for PROFIBUS nodes. The following basic modules can participate in direct communication as the sender (publisher):

| • | BM 141 DI 8×DC 24V, | 6ES7 141-1BF01-0XB0, from product version 08 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01 | | | | | |
|----|---|--|--|--|--|--|--|
| • | BM 141 DI 8×DC 24V ECOFAST, | 6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01 | | | | | |
| • | BM 141 DI 8×DC 24V ECOFAST DIAG, | 6ES7 141-1BF40-0AB0, from product version 01 | | | | | |
| • | BM 142 DO 4×DC 24V/2A, | 6ES7 142-1BD11-0XB0, from product version 08 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01 | | | | | |
| • | BM 143-DESINA FO, | 6ES7 143-1BF00-0XB0, from product version 01 | | | | | |
| • | BM 143-DESINA RS485, | 6ES7 143-1BF00-0AB0, from product version 01 | | | | | |
| Yc | You will find a detailed description of direct communication in the STEP 7 Online | | | | | | |

Requirements for commissioning

Help.

| Table 5-5 | Requirements | for commissioning the | DP slave |
|-----------|--------------|-----------------------|----------|
| | | | |

| Presumed activity | See | | | | | |
|--|---|--|--|--|--|--|
| 1. DP slave installed Section 3.1 | | | | | | |
| 2. PROFIBUS address set on DP slave | Section 3.3 | | | | | |
| 3. If the bus signals are transferred using copper conductors and the DP slave is at the end of the segment, the terminating resistor must be activated on the DP slave: | Section 3.4 | | | | | |
| In the case of the BM 141, BM 142 and BM 147/CPU by bringing it into the circuit | | | | | | |
| In the case of the BM 141-ECOFAST and BM 143-DESINA RS485 by mounting the terminating resistor on the right-hand DESINA connector | | | | | | |
| 4. DP slave wired | Section 4.4 | | | | | |
| 5. DP slave configured | Online Help/configuration software manual | | | | | |
| 6. Supply voltage turned on for DP master | Manual for DP master | | | | | |
| 7. DP master set to RUN mode | Manual for DP master | | | | | |

Commissioning the DP slave

| Step | Procedure |
|------|--|
| 1. | Turn on the supply voltage to the DP slave. |
| 2. | Turn on the supply voltage to the load as necessary. |

Table 5-6 Order of steps for commissioning the DP slave

Starting up the ET 200X



Figure 5-4 Start-up of the ET 200X

Starting up the ET 200X-DESINA



Figure 5-5 Start-up of the ET 200X-DESINA

5.3 Diagnostics using LEDs

All the basic and some of the ET 200X expansion modules have LEDs for displaying the status and errors.

5.3.1 LEDs on BM 141 and BM 142 basic modules

| | | SF BF ON 24 VD | (system fault):red(bus fault):red(supply voltage):greenC (load supply voltage):green | |
|-----|--------|-------------------------|--|--|
| SE | LEDs | ON | Meaning | Action |
| Off | Off | Off | There is either no supply voltage to the electronics/sensors on the DP slave or it is too low. | Turn on the supply voltage to the DP slave. |
| | | | • A hardware fault has occurred. | • Replace the basic module. |
| * | * | On | Supply voltage is applied to the DP slave. | - |
| * | On | On | • The DP slave is starting up. | - |
| | | | The connection to the DP master has failed. The DP slave does not detect a baud rate. | Check the PROFIBUS-DP connection. Check the DP master. |
| | | | Bus interruptThe DP master is not operating | Check all the cables in your PROFIBUS-DP network. Check whether the cable connectors for PROFIBUS-DP are firmly attached to the basic module. |
| On | Off | On | Diagnostic message has been issued. The PROFIBUS address set on the DP slave is not allowed. A DP slave hardware fault has occurred. | Evaluate the diagnosis. Change the PROFIBUS address set on the basic module. Check whether the modules are securely connected together. |
| On | Flash. | On | The configuration data sent by the DP master to the DP slave does no agree with the configuration of the DP slave. | Check the configuration of the DP slave (input/output, PROFIBUS address). |

Table 5-7 Status and error display by means of LEDs on the BM 141 and BM 142 basic modules

| | | SF BF ON 24 VD0 | (system fault): (bus fault): (supply voltage): C (load supply voltage): | red red green green | |
|--------|--------|--------------------------|---|------------------------------|---|
| LEDs | | | Meaning | | Action |
| SF | BF | ON | | | |
| Off | Flash. | On | The DP slave has detected the baud rate but is not being addressed by the DP master. The DP slave has not been configured. | | Check the PROFIBUS address set in the DP slave or in the configuration software. Check the configuration of the DP slave (station type). |
| Flash. | On | On | A basic module hardware fault has occurred. | | Replace the basic module. |

* Not applicable

SF LED

On the BM 141 and BM 142 basic modules, version 06 or later, the red system fault LED (SF) comes on as soon as a diagnostic event is registered. The SF LED goes not go out unless all diagnostic events have been acknowledged.

24 VDC LED

The 24 VDC LED is on when the ET 200X is connected to a load power supply.

5.3.2 LEDs on basic modules

- BM 143-DESINA FO,
- BM 143-DESINA RS485
- BM 141 DI 8 \times DC 24V ECOFAST
- BM 141 DI 8 \times DC 24V ECOFAST DIAG
- BM 141 DI 8 \times DC 24V DIAG

| Table 5-8 | Status and fault dis | nlavs using | I EDs on the | basic modules |
|-----------|----------------------|-------------|--------------|---------------|
| Table 5-6 | Status and fault dis | piays using | LEDS ON the | basic modules |

| SF (system fa RUN (status in DC 24 V-NS (non-switt DC 24 V-S (switched LEDs | | | (system f (status in NS (non-swit S (switched | ault): r dicator): c ched load voltage): c l load voltage): c Meaning | ed green green Action |
|---|--------|------------|--|--|---|
| SF | RUN | DC 24 V-NS | DC 24 V-S | | |
| On | * | * | * | Diagnostic message has been issued. The PROFIBUS address set on the DP slave is not allowed. A DP slave hardware fault has occurred. | Evaluate the diagnosis. Change the PROFIBUS address for the basic module as set by means of the configuration connector. Check whether the modules are securely connected together. |
| On | Flash. | On | On | • The configuration data sent by the DP master to the DP slave does not agree with the configuration of the DP slave. | Check the configuration of the DP slave (input/output, PROFIBUS address). |
| Off | Flash. | On | On | PROFIBUS address is incorrect Bus interruption at PROFIBUS-DP | Correct the PROFIBUS address Rectify the bus interruption |

* Not applicable

RUN LED

The RUN LED lights up when the DP slave is in the process of exchanging data with the DP master.

DC 24-NS LED

The DC 24V-NS LED is on when the DC 24V-NS non-switched supply voltage is applied.

DC 24V-S LED

The DC 24V-S LED is on when the switched DC 24V-S supply voltage is available along with the DC 24V-NS supply voltage.

BM 143-DESINA FO and BM 143-DESINA RS485 status display

The ET 200X-DESINA has two LEDs per channel (X1 to X8) 2 LEDs for status indication:

• "Yellow" LED (for digital input or output, pin 4)

The LED is yellow when the input or output is active.

• LED "red/yellow" (for pin 2 input functionality, see Table 5-1)

The LED is red when

- the functional input is parameterized as a diagnostics input for DESINA and
- a DESINA fault (status "0") is registered for the sensor/actuator.

The LED is yellow when

- the functional input is parameterized as an input with NC function and
- The status of the sensor connected to the input is non-switched ("1").

Status display of the BM 141 DI 8 imes DC 24V ECOFAST

In the case of the BM 141 DI 8 \times DC 24V ECOFAST basic module there is one LED for each channel (X1 to X8) for status display:

• Green LED (for digital input)

The LED is green when the input is active.

Status display of the BM 141 DI 8 imes DC 24V ECOFAST DIAG

In the case of the BM 141 DI 8 \times DC 24V ECOFAST DIAG basic module there are two LEDs for each channel (X1 to X8) for status display:

Green LED

The LED is green when the input is active.

Red LED

The LED is red if there is a fault on the channel:

- Short circuit of the 24 V sensor power supply
- Digital input wire break

5.3.3 LEDs on expansion modules (except DESINA)

SF LED (system fault display)

Some ET 200X expansion modules have an "SF" LED:

- EM 142 DO 4 \times DC 24V/2A expansion module with digital outputs (6ES7 142-1BD40-0XB0)
- PM 148 DO 4 \times DC 24V/2A power module
- · All expansion modules with analog inputs
- All expansion modules with analog outputs

Parameterizable and non-parameterizable diagnostic messages

There are parameterizable and non-parameterizable diagnostic messages.

Non-parameterizable diagnostic messages are issued without you having to take any action. You have to set parameterizable diagnostic messages in the configuration software for them to be issued (refer to Table 5-10 onwards).

SF LED On

The SF LED on the expansion module is turned on as soon as a diagnostic message is triggered by the expansion module.

Status display

In addition, all the ET 200X modules have a status display for every input and output. The LEDs are lit when the inputs and outputs are active.

Status display of the EM 141 DI 8 \times DC 24V DIAG (6ES7 141-1BF40-0AB0)

In the case of the expansion module there are 2 LEDs for each channel (X1 to X8) for status display:

Green LED

The LED is green when the input is active.

Red LED

The LED is red when there is a fault on the channel:

- Short circuit of the 24 V sensor power supply
- Digital input wire break

Status display of the EM 141 DI 8 \times DC 24V DIAG (6ES7 141-1BF30-0AB0)

In the case of the expansion module there is 1 LED (with two colors) for each channel (X1 to X4) for status display:

Green/red LED

The LED is green when the input is active.

The LED is red when there is a fault on the channel:

- Short circuit of the 24 V sensor power supply
- Digital input wire break

24 VDC LED

The power module also has a 24 VDC LED. The 24 VDC LED is on when the power module is connected to a load-voltage supply.

If no load voltage is available:

- the SF LED on the power module is on
- the 24 VDC LED on the power module is off

5.3.4 LEDs on EM 143-DESINA expansion modules

Status display

The ET 200X-DESINA has two LEDs per channel (X1 to X8) 2 LEDs for status indication:

- "Yellow" LED (for digital input or output, pin 4)
 The LED is yellow when the input or output is active.
- Red/yellow LED (for pin 2 input functionality, see Table 5-1)
 The LED is red when
 - the functional input is parameterized as a diagnostics input for DESINA and
 - a DESINA fault (status "0") is registered for the sensor/actuator.

The LED is yellow when

- the functional input is parameterized as an input with NC function and
- the status of the sensor connected to the input is non-switched ("1").

LED on SITOP power 5.3.5

| Q 24 VDC (24 V at output terminals): green ELECTRONIC/SENSOR 1L+ (supply voltage for electronic components/sensors): green LOAD 2L+ (load voltage supply): green TEMP > (temperature rise): red | | | | | |
|---|---------------------------|----------|--------|---|--|
| | LEDs | | | Meaning | Action |
| 24 VDC | ELECTRONIC/ SENSOR 1L+ | LOAD 2L+ | TEMP > | | |
| Off | Off | Off | * | No supply voltage Short circuit at output¹⁾ | Switch on the mains voltage.Repair the short circuit. |
| Flash. | Flash. | Flash. | * | Overload in RESTART mode | Check the current consumption and reduce, if appropriate, the number of modules (see Section 2.7) |
| | | | | Short circuit at output ¹⁾ | Repair the short circuit. |
| On | * | * | * | • 24 V is applied to the output terminals. | - |
| * | On | On | * | Associated bus segment is supplied with 24 V | - |
| * | * | * | Flash. | Switch off as maximum temperature exceeded | Check environmental and load conditions |

Table 5-9 Status and error displays by means of LEDs on SITOP power

* Not applicable1) Depends on parameterized short-circuit response

5.4 Parameterizable diagnostic messages

You can assign parameters to diagnostic messages for the following modules with *STEP 7* or *COM PROFIBUS*:

- EM 142 DO 4 \times DC 24V/2A expansion module with digital outputs (6ES7 142-1BD40-0XB0)
- PM 148 DO 4 \times DC 24V/2A power module
- All expansion modules with analog inputs
- · All expansion modules with analog outputs

Diagnostics messages of the EM 142 DO 4 \times DC 24V/2A (6ES7 142-1BD40-0XB0) and the PM 148 DO 4 \times DC 24V/2A

| Table 5-10 | Diagnostics messages of the EM 142 DO 4 x DC 24V/2A and |
|------------|---|
| | PM 148 DO 4 x DC 24V/2A |

| Diagnostic message | Area affected by diagnostics | Configurable |
|---|---------------------------------|------------------|
| Configuration or parameter assignment error | Expansion module | Not configurable |
| Wire break | Channel | Configurable |
| Short-circuit to M | Channel | Configurable |
| Short circuit to L+ | Channel | Configurable |

The broken wire signal is triggered at a current value of < 6 mA and only if the corresponding channel has been set.
Diagnostic messages of expansion modules with analog inputs

When a fault is detected, modules with analog inputs supply a signal value of " $7FFF_H$ ", irrespective of parameter assignment.

| Diagnostic message | Area affected by diagnostics | Configurable |
|---|---------------------------------|------------------------------|
| Configuration or parameter assignment error | Expansion module | Not configurable |
| Wire break (only with current inputs and over the measuring ranges 4 to 20 mA) ¹ | Channel | Configurable |
| Upper limit violation | Channel | Parameterizable ² |
| Lower limit violation | Channel | Parameterizable ² |

Table 5-11 Diagnostic messages for modules with AI

¹ The broken wire signal is triggered at a current value of \leq 3.6 mA.

² Perform the setting by activating the "group diagnosis" parameter in the configuration software.

Diagnostic messages of expansion modules with analog outputs

| Diagnostic message | Area affected by diagnostics | Configurable |
|---|---------------------------------|------------------------------|
| Configuration or parameter assignment error | Expansion module | Not configurable |
| Wire break (with current outputs only) ¹ | Channel | Parameterizable ² |
| Short-circuit to M (with voltage outputs only) ³ | Channel | Parameterizable ² |

Table 5-12 Diagnostic messages for modules with AO

¹ In the case of EM 145 AO 2 \times I (6ES7 145-1GB31-0XB0) the broken wire signal is triggered at a current value of ≤ -2 mA or $\geq +2$ mA.

² Perform the setting by activating the "group diagnosis" parameter in the configuration software.

³ In the case of EM-circuit signal is triggered at a voltage value of ≤ -750 mV or $\geq +750$ mV.

Action following diagnostic message in STEP 7

Every diagnostic message results in the following action:

- If you have selected the "enable diagnostic interrupt" parameter, a diagnostic interrupt is triggered (refer to Section 5.5.1).
- A diagnostic interrupt is followed by the diagnostic message being entered in the diagnostic buffer of the master CPU or – if you are using the BM 147/CPU on the ET 200X – in the diagnostic buffer of the BM 147/CPU.
- The SF LED on the expansion module goes on.
- The OB 82 is called. If it is not present, the CPU then switches to STOP mode (either the master CPU or, if the BM 147/CPU is being used on the ET 200X, the CPU of the BM 147/CPU).

Action following diagnostic message in COM PROFIBUS

If you have enabled diagnostic interrupts with *COM PROFIBUS*, diagnostic interrupts are shown in the device-specific diagnosis of the ET 200X. In other words, the module that triggered the interrupt and the cause of the interrupt are entered in the device-specific diagnosis (see Section 5.6.9).

The SF LED on the expansion module goes on.

Causes and action

The following table shows all the diagnostic messages possible for expansion modules, together with their causes and remedial action.

| Table 3-13 Diagnostic messages – causes and remedial action |
|---|
|---|

| Diagnostic message | Possible cause | Remedial action | | | |
|---|---|--|--|--|--|
| Configuration/parameter assignment error | You have assigned different parameters to the module in the user program (possible in <i>STEP</i> 7 SFC call). | Assign new parameters to module | | | |
| | The new values are not within the permissible range or are not consistent. | | | | |
| Wire break | Resistance of sensor/actuator wiring too high | Use a different sensor/actuator type or wire differently – for example, use wires having a larger cross-section | | | |
| | Interruption of the cable between the module and the sensor/actuator | Establish cable connection | | | |
| | Channel not wired (open) | Deactivate channel at AI (by means of "measurement type" parameter) | | | |
| | | Wire up channel | | | |
| Short-circuit to M | Output overloaded | Clear overloading | | | |
| (error detection only when output at "1") | Output short-circuited to M | Clear short-circuit | | | |
| Short-circuit to L+ | Output short-circuited to L+ of module supply | Replace module | | | |
| Lower limit violation | Input value below underrange, fault possibly caused by: | | | | |
| | Sensor connected with reverse polarity | | | | |
| | Incorrect measuring range set | Check connections | | | |
| | | Assign parameters to other range | | | |
| Lower limit violation | Input value higher than overrange | Assign parameters to other range | | | |

Parameters

The parameters you can set and their ranges can be found in the technical data applicable to expansion modules:

- for EM 142 DO 4 \times DC 24V/2A (6ES7 142-1BD40-0XB0) in Table 7-28
- + for PM 148 DO 4 \times DC 24V/2A in Table 7-37
- for the expansion modules with analog inputs in Table 7-41
- for the expansion modules with analog outputs in Table 7-42

5.5 Evaluating ET 200X interrupts

With certain faults, interrupts are triggered by the DP slave. Interrupts are evaluated differently from each other, depending on the DP master being used.

Evaluating interrupts with S7 DP master

Prerequisite: You have configured the ET 200X with STEP 7 as of version 3.1.

When an interrupt occurs, interrupt OBs are processed automatically in the CPU of the DP master if you have programmed them (refer to the *System Software for S7-300/S7-400, Program Design* programming manual).

Evaluating interrupts with a different DP master

If you are operating the ET 200X with a different DP master, the alarms are simulated within the extended diagnosis of the ET 200X (see Section 5.6.7 onwards). You must continue processing the results of the diagnosis in the application of the DP master.

Note

In order to be able to evaluate alarms by means of the extended diagnosis with a different DP-master, take note of the following:

- The DP master must be able to save the diagnostic messages; it might store the diagnostic messages in a ring buffer, for example. If the DP master cannot store diagnostic messages, only the latest diagnostic message to be received is stored, for instance.
- You have to poll regularly in your user program the corresponding bits in the extended diagnosis. Take into account the bus transit time with PROFIBUS-DP so that you can retrieve the bits at least in synchronism with the bus transit time, for example.
- With an IM 308-C as a DP master you cannot use process alarms and cycle end alarms within the extended diagnosis.

5.5.1 Module interrupts (STEP 7)

You can assign parameters to diagnostic and hardware interrupts for modules having analog inputs with *STEP 7*.

For

- modules with analog outputs
- EM 142 DO 4 × DC 24V/2A (6ES7 142-1BD40-0XB0)
- PM 148 DO 4 \times DC 24V/2A
- BM 143-DESINA and EM 143-DESINA
- + BM 141 DI 8 \times DC 24V ECOFAST DIAG and EM 141 DI 8 \times DC 24V DIAG

it is possible to configure diagnostic interrupts.

Triggering a diagnostic interrupt

With a coming or going event – for example, wire break fault – the module triggers a diagnostic interrupt if the "enable diagnostic interrupt" parameter has been assigned.

| Event | EM 142 DO 4 × DC 24V/2A | Module with ana- log inputs | Module with ana- log outputs | BM 143-DE- SINA | BM 141 DI 8×DC 24V ECOFAST DIAG |
|--|-------------------------------|--------------------------------------|---------------------------------------|-----------------------|--|
| | PM 148 DO 4 × DC 24V/2A | | | EM 143-DE- SINA | EM 141 DI 8 × DC 24V DIAG |
| Configuration/ parameter assignment error* | Yes | Yes | Yes | Yes | Yes |
| Wire break | Yes | Yes | Yes | Yes | Yes |
| Short-circuit to M | Yes | Yes | Yes | No | Yes |
| Short circuit to L+ | Yes | No | No | No | No |
| Lower limit violation | No | Yes | No | No | No |
| Upper limit violation | No | Yes | No | No | No |
| Rising edge | No | No | No | No | Yes |
| Falling edge | No | No | No | No | Yes |

Table 5-14 Events that can trigger diagnostic interrupt

* MAINS OFF/MAINS ON for the ET 200X is required following rectification of the configuration/parameter-assignment error.

The CPU interrupts the processing of the user program and processes the diagnostic interrupt block (OB 82). The event that led to the interrupt is entered in the start information of OB 82.

Triggering a hardware interrupt from modules with analog inputs

You define a work area by assigning parameters to an upper and lower limit value. If the process signal – for example, the ignition temperature – of a module leaves this work area, the module triggers a hardware interrupt the "enable hardware interrupt upon limit exceeded" parameter has been assigned. The CPU interrupts the processing of the user program and processes the hardware interrupt block OB 40.

The channels violating a limit value and the limit value concerned are entered in the start information of the OB 40 in tag OB40_POINT_ADDR. You will find an assignment of the bits to local data double word 8 in the figure below.



Figure 5-6 Start information of OB 40: modules with analog inputs

Triggering of a hardware interrupt in the case of the BM 141 DI 8 DC 24V ECOFAST DIAG and EM 141 DI 8 DC 24V DIAG

The channel that triggered the hardware interrupt is entered in the start information of the OB 40 in the variable OB40_POINT_ADDR. You will find an assignment of the bits to local data double word 8 in the figure below.





Note

You will find a description of OBs 40 and 82 in the *System and Standard Functions* reference manual.

5.5.2 Module interrupts (COM PROFIBUS)

You can assign parameters to diagnostic and hardware interrupts for modules having analog inputs with *COM PROFIBUS*.

For

- modules with analog outputs
- EM 142 DO 4 × DC 24V/2A (6ES7 142-1BD40-0XB0)
- PM 148 DO 4 \times DC 24V/2A
- BM 143-DESINA and EM 143-DESINA
- BM 141 DI 8 \times DC 24V ECOFAST DIAG
- EM 141 DI 8 \times DC 24V DIAG

it is possible to configure diagnostic interrupts.

The alarms are simulated in the extended diagnosis of the ET 200X (see Section 5.6.9). You can continue processing the interrupt messages in the user program of the DP master.

5.6 ET 200X diagnostics with STEP 7 and STEP 5

Slave diagnosis

The slave diagnosis behaves in accordance with the IEC 61784-1:2002 Ed1 CP 3/1 standard. Depending on the DP master, It can be read using *STEP 7* or *STEP 5* for all DP slaves that comply with the standard.

Displaying and structuring the slave diagnostics is described in the following sections.

BM 141, BM 141-ECOFAST, BM 142 and BM 143-DESINA provide the slave diagnosis that complies with the Standard. Note the differences in the diagnostic frame depending on which version and which release you have.

The basic modules provide an extended diagnosis, depending on the DP master and the parameterization.

Note

- The extended diagnosis can only be used in the slave mode that complies with the Standard (not in S7 slave operation).
- Diagnosis as per the Standard and module diagnosis will always be signaled, even if no alarm is enabled during parameterization of the basic module.

S7 diagnostics

S7 diagnosis can be requested for all modules in the SIMATIC S7/M7 range of modules. The structure of the S7 diagnosis is identical for base unit and distributed modules.

The diagnosis data of a module is in data records 0 and 1 of the system data part of the module. Data record 0 contains 4 bytes of diagnostic data describing the current state of a module. Data record 1 contains module diagnostics data in addition.

Data records 0 and 1 are contained in the slave diagnosis (refer to Section for its structure 5.6.2).

5.6.1 Reading out the diagnosis

Options for reading out the diagnosis

| Programmable logic controller with DP master | Block or register in STEP 7 | Application | See |
|--|---|---|---|
| SIMATICS7/M7 | "DP slave diagnosis" register | Display slave diagnostics as plain text on the <i>STEP 7</i> user interface | The section on hardware diagnostics in the <i>STEP</i> 7 online help system |
| | SFC 13 "DP NRM_DG" | Display slave diagnosis (store in data area of the user program) | Configuration, see Section 5.6.2; for the SFC see System |
| | SFC 59 "RD_REC" | Read out data records of S7 diagnosis (store in data area of the user program) | and Standard Functions reference manual |
| | FB 125/FC 125 Evaluate slave diagnostics | Evaluate slave diagnostics | On the Internet at http://www.ad.siemens.de/ simatic-cs under the ID 387 257 |
| | SFB 52 | Read data record from a DP slave | See online help system in STEP 7 |
| | SFB 54 | Receive interrupts from the interrupt OBs | |
| SIMATIC S5 with the IM 308-C as DP master | FB192 "IM308C" | Display slave diagnosis (store in data area of the user program) | Configuration, see Section 5.6.2; for the FB see the <i>ET200</i> |
| SIMATIC S5 with S5-95U as DP master | FB 230 "S_DIAG" | Note: not for enhanced diagnosis | Distributed I/O Device manual |

Table 5-15 Reading out the diagnosis of ET 200X with STEP 7 and STEP 5

Example of reading out the slave diagnosis with SFC 13 "DPNRM_DG"

Here you will find an example of how to use SFC 13 to display the slave diagnosis for a DP slave in the STEP 7 user program.

Assumptions

The following assumptions apply to this STEP 7 user program:

- The diagnosis address of the ET 200X is 1022 (3FE_H).
- The slave diagnosis should be stored in DB 82: as of address 0.0, length 64 bytes.
- The slave diagnosis consists of 64 bytes.

STEP 7 user program

| STL | Description |
|--|---|
| CALL SFC 13 | |
| REQ :=TRUE LADDR :=W#16#3FE RET_VAL :=MW 0 RECORD :=P#DB82.DBX 0.0 BYTE 64 BUSY :=M2.0 | Read request Diagnosis address of the ET 200X RET_VAL of SFC 13 Data mailbox for the diagnosis in DB 82 Read operation runs over several OB1 cycles |

Example of displaying the slave diagnosis with FB 192 "IM308C"

Here you will find an example of how you use FB 192 to read out the slave diagnosis for a DP slave in the *STEP 5* user program.

Assumptions

The following assumptions apply to this STEP 5 user program:

- The IM 308-C is assigned pages 0 to 15 (number 0 of the IM 308-C) as the DP master.
- The DP slave has PROFIBUS address 3.
- The slave diagnosis is required to be stored in DB 20. However, you can also use any other data block for this.
- The slave diagnosis consists of 26 bytes.

STEP 5 user program

| STL | | | Description |
|------|---------|----------|--|
| | :A | DB 30 | |
| | :JU | FB 192 | |
| Name | :IM3080 | 2 | |
| DPAD | : | КН F800 | Default address area of the IM 308-C |
| IMST | : | ку 0, 3 | IM No. = 0, PROFIBUS address of DP slave = 3 |
| FCT | : | KC SD | Function: Read slave diagnosis |
| GCGR | : | КМ 0 | Not evaluated |
| TYPE | : | ку 0, 20 | S5 data area: DB 20 |
| STAD | : | KF +1 | Diagnostic data from data word 1 |
| LENG | : | KF -1 | Diagnosis length = joker length (all permissible |
| | | | bytes) |
| ERR | : | DW 0 | Error code stored in DW 0 of DB 30 |

5.6.2 Structure of the slave diagnosis, ET 200X



Structure of slave diagnosis, ET 200X

Figure 5-8 Structure of the slave diagnosis, ET 200X

Data records of the S7 diagnosis contained in the station diagnosis

Bytes 13 to 16 of the device-specific diagnosis correspond to data record 0 of the S7 diagnosis. Bytes 13 to 28 of the station diagnosis correspond to data record 1 of the S7 diagnosis. (Data record 1 contains data record 0 in the first 4 bytes.)

5.6.3 Station statuses 1 to 3

Definition

Station statuses 1 to 3 provide an overview of the status of a DP slave.

Station status 1

| Table 5-16 | Structure of station status | 1 (Byte 0) ET 200X |
|------------|-----------------------------|--------------------|
|------------|-----------------------------|--------------------|

| Bit | Meaning | Cause/remedy |
|-----|--|--|
| 0 | The DP slave cannot be addressed by the DP master. The bit in the DP slave is always 0. | Correct PROFIBUS address set on the DP slave? Bus connector/fiber-optic cable connected? Voltage at DP slave? RS 485 repeater set correctly? Reset on the DP slave executed (switch on/off) |
| 1 | 1: The DP slave is not yet ready to ex- change data. | Wait while the DP slave starts up. |
| 2 | 1: The configuration data sent by the DP master to the DP slave does not agree with the configuration of the DP slave. | Correct station type or correct configuration of the DP slave entered in the configuration software? |
| 3 | 1: External diagnosis available. | • Evaluate the module diagnostics, the module status and/or the channel-specific diagnostics. Bit 3 is reset as soon as all the faults have been rectified. The bit is reset when there is a new diagnostic message in bytes of the above-mentioned diagnostics. |
| 4 | 1: The requested function is not sup- ported by the DP slave (e.g. SYNC/FREEZE). | Check the configuration. |
| 5 | 1: The bit is always "0". | Note: When reading the station status from the DP master, is the bit at "1"? The DP master cannot interpret the response of the DP slave. |

| Bit | Meaning | Cause/remedy |
|-----|---|---|
| 6 | 1: The DP slave type does not agree with the software configuration. | • Compare the desired configuration with the actual configuration. |
| 7 | 1: Parameters have been assigned to the DP slave by a different DP ma- ster (not that which currently has access to the DP slave). | The bit is always "1" when you are accessing the DP slave with the programmer or another DP master, for example. The PROFIBUS address of the DP master which assigned parameters to the DP slave is located in the "master PROFIBUS. |
| | | address" diagnostic byte. |

| Table 5-16 | Structure of station status 1 | (B | vte 0 |) ET | 200X |
|------------|-------------------------------|----|-------|------|------|
| | | (Ľ | , | , | 200/ |

Station status 2

Table 5-17 Structure of station status 2 (Byte 1) ET 200X

| Bit | Meaning |
|-----|--|
| 0 | 1: New parameters have to be assigned to the DP slave. |
| 1 | 1: A diagnostic message has been issued. The DP slave will not work until the fault has been corrected (static diagnostic message). |
| 2 | 1: The bit is always "1" in the DP slave. |
| 3 | 1: Response monitoring has been enabled for this DP slave. |
| 4 | 1: The DP slave has received the "FREEZE" control command. |
| 5 | 1: The DP slave has received the "SYNC" control command. |
| 6 | 0: The bit is always at 0. |
| 7 | The bit is always at 0. Note: When the station status is read by the DP master, the bit is at "1" if the DP slave in the DP master has been deactivated. The DP slave is deactivated – that is, it has been removed from current processing. |

Station Status 3

Table 5-18 Structure of Station Status 3 (Byte 2) ET 200X

| Bit | Meaning |
|--------|---|
| 0 to 6 | 0: The bits are always at "0". |
| 7 | 1: There are more channel-specific diagnostic messages than can be represented in the diagnostic frame. |

5.6.4 Master PROFIBUS address

Definition

The PROFIBUS address of the DP master is stored in diagnostics byte 3: this is the master

- · which assigned parameters to the DP slave
- which has read and write access to the DP slave

FF_H in byte 3

If the value FF_H is defined as the master PROFIBUS address in byte 3, the DP slave has not been parameterized by the DP master.

5.6.5 Manufacturer identification

Definition

A code is stored in the manufacturer ID that describes the type of the DP slave.

Manufacturer identification

| Byte 4 | Byte 5 | Manufacturer ID for |
|-----------------|-----------------|-----------------------------------|
| 80 _H | 3D _H | BM 141 DI 8 x DC 24V |
| 80 _H | D2 _H | BM 141 DI 8 x DC 24V ECOFAST |
| 80 _H | D3 _H | BM 141 DI 8 x DC 24V EDOFAST DIAG |
| 80 _H | 3C _H | BM 142 DO 4 x DC 24V/2A |
| 80 _H | 9A _H | BM 143-DESINA FO |
| 80 _H | 9A _H | BM 143-DESINA RS485 |

Table 5-19 Structure of the manufacturer ID (Byte 4, 5) ET 200X

5.6.6 ID-specific diagnosis

Definition

The ID-specific diagnosis states whether or not the modules of the ET 200X are defective. The module diagnosis begins as of byte 6 and comprises 3 bytes.

Module diagnosis

The module diagnosis for the ET 200X is structured as follows:



Figure 5-9 Structure of ID-specific diagnosis for ET 200X

5.6.7 Module status

Definition

The module status indicates the status of the configured modules and provides details of the ID-specific diagnosis in respect of the configuration. The module status begins after the module diagnosis and comprises 7 bytes.

The module is only contained in the diagnosis frame if you have activated "extended diagnosis" during parameterization.

Module status

The module status for ET 200X is configured as follows:



Figure 5-10 Configuration of the module status for ET 200X

5.6.8 Channel-specific diagnosis

Definition

The channel-specific diagnosis gives information on channel errors of modules and expands on the module diagnosis. Channel-specific diagnosis begins after the module status. Channel-specific diagnosis does not affect the module status.

Channel-specific diagnosis

Important: The diagnostic interrupt must be switched on for each module!

The channel-specific diagnosis is only contained in the diagnosis frame if have activated the "extended diagnosis" during parameterization.

The maximum number of channel-specific diagnoses is limited by the maximum overall length of the slave diagnosis of 64 Bytes. The length of the slave diagnosis is dependent on the number of the channel-specific diagnoses currently present. If more channel-specific diagnoses are present than can be shown in the slave diagnosis, bit 7 "diagnosis overrun" is set in the station status 3.

Tip: If you disable the interrupts for the ET 200M during parameter assignment, there are still up to 20 additional bytes available in the interrupt section for the channel-specific diagnosis (see also Figure 5-8).



Figure 5-11 Configuration of channel-specific diagnosis, ET 200X

Channel-specific error messages

| Error type Error text Meaning | | Meaning | Action | |
|-------------------------------|----------------|-----------------------|--|---|
| 00001 _B | 1 _D | Short circuit | Short circuit because, for example: Sensor wiring to P potential short-circuited Sensor wiring to M potential short-circuited Output wiring to P potential short-circuited Output wiring to ground short-circuited | Correct the pro- cess wiring. |
| 00010 _B | 2 _D | Undervol- tage | Main voltage failed or too low | Correct mains voltage |
| 00011 _B | 3 _D | Overvoltage | Mains voltage too high | Correct mains voltage |
| | | | Braking power too high | Increase ramp- down time param- eter on EM 148-FC |
| 00100 _B | 4 _D | Overload | The output level is overloaded | Correct the mod- ule/actuator match. |
| 00101 _B | 5 _D | Tempera- ture rise | The output level is overloaded and is too hot | Correct the mod- ule/actuator match. |
| 00110 _B | 6 _D | Open circuit | Wire break because, for example: The signal line to a sensor is interrupted The signal line from an actuator is interrupted Power cable of the sensor interrupted | Correct the pro- cess wiring |
| 00111 _B | 7 _D | Upper limit violation | Value is above the overrange. | Correct the mod- ule/actuator match. |
| 01000 _B | 8 _D | Lower limit violation | Value is below the underrange. | Correct the mod- ule/actuator match. |
| 01001 _B | 9 _D | Error | Internal module fault | Exchange the fre- quency converter |

 Table 5-20
 Channel-specific error messages to PROFIBUS standard

| Error t | уре | Error text | Meaning | Action |
|--------------------|-----------------|-------------------------------|---|---|
| 10000 _B | 16 _D | Parameteriz ation error | Parameter assignment error, for example, because: The module cannot use the parameter (unknown, impermissible combination) Module is not parameterized. | Correct the parameter assignment. |
| 10001 _B | 17 _D | Load voltage is missing | The following voltages may be missing: Load voltage at BM 141/BM 142 Switched load voltage in the case of BM 143 DESINA and BM 141-ECOFAST 8DI | Correct the process wiring |
| 10110 _B | 22 _D | Hardware interrupt lost | Hardware interrupt lost | Correction, coordination of program, process, module |
| 11000 _B | 24 _D | Actuator fault | Excess temperature on motor | Check mechanical loading of motor |
| | | | Thermistor not connected | Connect thermistor or deactivate thermistor monitoring, motor parameter on EM 148-FC |
| 11010 _B | 26 _D | External fault | External (process-related) error, for example: Sensor error Actuator error Sensor data is not correct Break in wire to EM | Replace the sensor/actuator; correct the process wiring. |

| Table 5-21 | Channel-specific error messages | s – manufacturer-specific |
|------------|---------------------------------|---------------------------|
| | | |

5.6.9 Interrupts

Definition

The interrupts section of the slave diagnosis provides information on the type of interrupt and the cause that triggered the interrupt. The interrupt section has a maximum of 20 bytes. A maximum of one interrupt can be used per slave diagnosis.

Position in the diagnostic frame

The position of the interrupt section in the slave diagnosis depends on the structure of the diagnostic frame and on the number of channel-specific diagnoses (see also Figure 5-8):

- · No enhanced diagnosis: always as of byte 9 after the module diagnosis
- Enhanced diagnosis: after the channel-specific diagnoses.

For example: if there are 3 channel-specific diagnoses, the interrupt section begins as of byte 25.

More than one interrupt

Interrupt information in the slave diagnosis is overwritten by the interrupt information of the next interrupt to be triggered.

Contents

The contents of the interrupt information depend on the type of interrupt:

In the case of **diagnostic interrupts**, the diagnostic data record 1 for SIMATIC S7 (16 bytes) is sent as interrupt information (as of byte x+4). You can find out what these bytes mean for digital and analog modules in Figures 5-14 to 5-17. In the case of **hardware interrupts**, the additional interrupt information is 4 bytes long. You can find out what these bytes mean in Figure 5-18.

Alarms

The alarm unit for ET 200X is configured as follows.







Diagnostic interrupt of modules with digital inputs

Figure 5-13 Structure as of byte x+4 for diagnostic interrupt (digital input)



Diagnostic interrupt of modules with digital outputs



Short-circuit to M

Wire break

Byte x+13: Assignment for channel 1 as for byte x+12 **Byte x+14:** Assignment for channel 2 as for byte x+12

Byte x+19: Assignment for channel 7 as for byte x+12

Temperature rise

•



Diagnosis alarm from EM 143-DESINA modules



In channel-specific diagnostics, a diagnostic interrupt from the EM 143-DESINA expansion module leads to error type 11010_B (see Table 5-20).



Diagnostic interrupt of modules with analog inputs



Diagnostic interrupt of modules with analog outputs

Figure 5-17 Configuration as of byte x+4 for diagnostic interrupt (analog outputs)

Hardware interrupt of analog input modules



Figure 5-18 Structure as of byte x+4 for hardware interrupt (analog inputs)

Hardware interrupt of digital input modules



Figure 5-19 Structure as of byte x+4 for hardware interrupt (digital inputs)

Byte x+4 to x+7 (x+10) for diagnosis of ET 200X

If byte x+2 contains the slot number 02, this indicates that a basic module is generating diagnostic messages. These diagnostic messages are contained in bytes x+4 to x+7 (x+10).

Table 5-22 gives you the meaning of bytes x+4 to x+7 (x+10) when the following basic modules are used:

| Basic module | MLFB |
|--|--|
| BM 141 DI 8 $	imes$ DC 24V | 6ES7 141-1BF11-0XB0 6ES7 141-1BF12-0XB0 |
| BM 141 DI 8 $	imes$ DC 2 ECOFAST | 6ES7 141-1BF00-0AB0 6ES7 141-1BF01-0AB0 |
| BM 141 DI 8 $	imes$ DC 24V ECOFAST DIAG | 6ES7 141-1BF40-0AB0 |
| BM 142 DO 4 \times DC 24V/2A | 6ES7 142-1BD21-0XB0 6ES7 142-1BD22-0XB0 |
| BM 143-DESINA FO | 6ES7 143-1BF00-0XB0 |
| BM 143-DESINA RS485 | 6ES7 143-1BF00-0AB0 |
| | |

Table 5-22 Bytes x+4 to x+10 in the diagnosis of ET 200X

| Byte | Bit | Meaning | Remarks | | |
|--------------------|--------|-----------------------------------|---|-------------------|--|
| | 0 | Error | 1: 0: | Error No error | |
| | 1 | Internal error | Cause of fault is in BM | | |
| | 2 | External error | Cause of fault is in configuration of ET 200X | | |
| | 3 | Module fault | BM cannot access one or more plugged-in modules | | |
| X+4 | 4 | Load voltage | 1: 0: | Error No error | |
| | 5 | not assigned | - | | |
| | 6 | Parameters not assigned to module | - | | |
| | 7 | Parameter assignment | 1: 0: | Error No error | |
| x+5 | 0 to 7 | 1B _H | Fixed | | |
| x+6 | 0 to 7 | not assigned | - | | |
| x+7 | 0 to 7 | not assigned | - | | |
| x+8 | 0 to 7 | Module ID | 55 _H for basic module | | |
| x+9 | 0 to 7 | 08 _H | Length of channel-specific diagnosis | | |
| x+10 | 0 to 7 | 08 _H | Fixed | | |
| x+11 to x+19 | 0 to 7 | not assigned | - | | |

Table 5-23 gives you the meaning of bytes x+4 to x+7 (x+10) when the following basic modules are used:

| Basic module | MLFB |
|--------------|---------------------|
| BM 141 | 6ES7 141-1BF01-0XB0 |
| BM 142 | 6ES7 142-1BD11-0XB0 |

| Table 5 22 | Bytoc x 14 to x | 7 in the diagr | onic of ET 200X |
|------------|-----------------|--------------------|-------------------|
| Table 3-23 | Dyles X+4 10 X | τ in the ulay | 10515 01 E 1 2007 |

| Byte | Bit | Meaning | Remarks | | |
|------|--------|--|--|----------------------|--|
| | 0 | Module malfunction (power supply for sensor/logic too low or Bits 2 and 4 are set) | 1: 0: | Error No error | |
| | 1 | not assigned | - | | |
| | 2 | External error | Cause of fault is configuration if ET 200X (EM can no longer be addressed) | | |
| | 3 | not assigned | - | | |
| x+4 | 4 | No external auxiliary voltage (no load voltage supply or it is too low) | 1: 0: | Error No error | |
| | 5 | not assigned | - | | |
| | 6 | not assigned | - | | |
| | 7 | Parameter assignment | 1: 0: | Error No error | |
| x+5 | 0 to 3 | 1011 | Fixed (Module o | class: Basic module) | |
| | 4 to 7 | not assigned | - | | |
| x+6 | 0 to 7 | not assigned | - | | |
| x+7 | 0 to 7 | not assigned | - | | |

5.6.10 Analyzing interrupts from station diagnosis

The structure of the station diagnosis is the same as the structure of the interrupt section, as described in Section 5.6.9.

Interrupts with S7 DP master

The ET 200X supports the following alarms:

- Diagnostic interrupt
- Hardware interrupt

You can evaluate these interrupts with an S7 DP master. In the case of an interrupt, interrupt OBs run automatically in the CPU (see the *System Software for S7-300/S7-400, Program Design* programming manual).

Interrupts with another DP master

If you operate the ET 200X with another DP master, these alarms will be simulated as device-specific diagnosis of the ET 200X. You must postprocess the relevant diagnostic events in the DP master's user program.

Saving the diagnosis

Depending on byte x+1, transfer the contents of the station diagnosis to a data block because:

- The interrupts are updated cyclically.
- The contents of the diagnosis as of byte x+3 depend on whether the S7 diagnosis or S7 hardware interrupt is reported.

Note

The following points are important in evaluating diagnostic interrupts and hardware interrupts with a different DP master by means of the station diagnosis:

- The DP master should be able to store the diagnostic messages, that is, the DP master should have a ring buffer in which to place these messages. If the DP master cannot store diagnostic messages, only the latest diagnostic message to be received is stored, for instance.
- You have to poll regularly in your user program the corresponding bits in the station diagnosis. You must also take PROFIBUS-DP's bus cycle time into consideration so that you can scan the bits at least once in sync with the bus cycle time, for example.
- You cannot use hardware interrupts in the station diagnosis in an IM 308-C as DP master, because only coming – and not going – interrupts are reported. For example, the "upper limit violation" bit is only reset when the "lower limit violation" bit is set.

General Technical Specifications

What are general technical specifications?

The general technical specifications contain the standards and test values with which the ET 200X conforms and which it fulfills, and the test criteria by which the ET 200X distributed I/O device was tested.

In this Chapter

| Section | Subject | Page |
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| 6.1 | Standards, certificates and approvals | 6-2 |
| 6.2 | Electromagnetic compatibility | 6-4 |
| 6.3 | Mechanical and climatic environmental conditions | 6-6 |
| 6.4 | Details of insulation testing, safety class, degree of protection and rated voltage of the ET 200X | 6-9 |

6.1 Standards, certificates and approvals

This chapter contains the following information about the components of the ET 200X:

- The most important standards for which the ET 200X satisfies the criteria
- The certificates and approvals available for the ET 200X

PROFIBUS standard

The ET 200X distributed I/O device is based on IEC 61784-1:2002 Ed1 CP 3/1.

Identification code for Australia



The ET 200X distributed I/O device complies with AS/NZS 2064 (Class A).

IEC 61131

The ET 200X distributed I/O device meets the requirements and criteria of IEC 61131-2, (programmable controllers, part 2 on equipment requirements and tests).

CE certification



The ET 200X distributed I/O device meets the requirements and protection objectives of the following EC directives and complies with the harmonized European standards (ENs) that have been published in the Official Gazettes of the European Community for programmable logic controllers:

- 73/23/EEC "Electrical equipment for use within fixed voltage ranges" (low-voltage directive)
- 89/336/EEC "Electromagnetic compatibility" (EMC directive)

The EC declarations of conformity are being kept available for the cognizant authorities at:

Siemens Aktiengesellschaft Bereich Automatisierungs- und Antriebstechnik A&D AS RD42 Postfach 1963 D-92209 Amberg

UL Recognition

UL Recognition Mark Underwriters Laboratories (UL) as per Standard UL 508, File No. 116536
CSA Certification

CSA Certification Mark Canadian Standard Association (CSA) to Standard C22.2 No. 142, File No. LR 48323

The SITOP power power supply has cUL certification.

DESINA

The ET 200X-DESINA fulfills the requirements of the DESINA specification.

6.2 Electromagnetic compatibility

Definition

Electromagnetic compatibility is the ability of an electric device to function satisfactorily in its electromagnetic environment without interfering with this environment.

The ET 200X distributed I/O device complies with the requirements of the EMC legislation of the European internal market. A requirement for this is that the ET 200 distributed I/O system meets the specifications and directives concerning electrical installation.

Bus parameter settings for the PROFIBUS-DP

Note

To maintain the EMC values, you must increase the "Retry Limit" bus parameter to at leas "3" in your configuration software (e.g. *COM PROFIBUS* or *STEP 7*) for transmission rates of 500 kbps and 1.5 Mbps. Leave all the other bus parameters as they are, in accordance with your selected bus profile.

Pulse-shaped interference

The following table shows the electromagnetic compatibility of the ET 200X distributed I/O device with regard to pulse-shaped interference.

| Pulse-shaped interference | Tested with | Corresponds to severity |
|---|--|---|
| Electrostatic discharge to IEC 61000-4-2. | 8 kV 4kV | 3 (air discharge)2 (contact discharge) |
| Burst pulses (fast transient interference) in ac- cordance with IEC 61000-4-4. | 2 kV (supply line) 1 kV (signal line) | 3 |
| | | 2 |
| Surge in accordance with IEC 61000-4-5 Only with lightning protection elements (refer to DP master manual) | | |
| Asymmetrical connection | 2 kV (supply line) 2 kV (signal line/ data line) | 3 |
| Symmetrical connection | 1 kV (supply line) 1 kV (signal line/ data line) | |

Sine-shaped interference

The following table shows the electromagnetic compatibility of the ET 200X distributed I/O device with regard to sine-shaped interference.

| RF radiation in accordance with IEC 61000-4-3 Electromagnetic RF field | | RF coupling in accordance with |
|---|-----------------------------|-----------------------------------|
| Amplitude-modulated | Pulse-modulated | IEC 61000-4-6 |
| 80 to 1000 MHz 900 MHz ±5 MHz | | 0.15 to 80 MHz |
| 10 V/m | | 10 V _{rms} unmodulated |
| 80 % AM (1 kHz) | 50 % ED | 80 % AM (1 kHz) |
| | 200 Hz repetition frequency | 150 Ω source impedance |

Emission of radio interference

Emitted interference of electromagnetic fields in accordance with EN 55011: limit value class A, group 1 (measured at a distance of 30 m).

| Frequency | Emitted interference |
|----------------------|----------------------|
| From 30 to 230 MHz | < 30 dB (µV/m)Q |
| From 230 to 1000 MHz | < 37 dB (µV/m)Q |

6.3 Mechanical and climatic environmental conditions

Shipping and storage conditions

The ET 200X distributed I/O device exceeds the requirements of EC 61131-2 with regard to transport and storage conditions. The following figures are valid for modules that have been transported or stored in their original packaging.

| Type of condition | Permissible range |
|--|---|
| Free fall | BM/EM/frequency converter: $\leq 1 \text{ m}$ Motor starter: $\leq 0.35 \text{ m}$ |
| Temperature BM/EM, except the pneumatic module from -40 °C to +70 °C | |
| | Pneumatic module: from –30 °C to +70 °C |
| Temperature variation | 20 K/h |
| Air pressure | From 1080 to 660 hPa (corresponds to an altitude of -1000 to 3500 m) |
| Relative humidity | From 5 to 95 %, without condensation |

Climatic environmental conditions

The following climatic environmental conditions apply:

| Environmental conditions | Operating ranges | Remarks |
|---------------------------|--|---|
| Temperature | From 0 to 55 °C | For horizontal installation; not for pneumatic components |
| | From 0 to 50 °C | For horizontal installation of pneumatic components |
| | From 0 to 40 °C | For all other installation posi- tions |
| Temperature variation | 10 K/h | |
| Relative humidity | From 5 to 100 % | |
| Air pressure | From 1080 to 795 hPa | Corresponds to an altitude of -1000 to 2000 m |
| Contaminant concentration | SO_2 : < 0.5 ppm; rel. humidity < 60 %, no moisture con- densation H_2S : < 0.1 ppm; rel. humidity < 60 %, no moisture con- densation | Test: 10 ppm; 4 days 1 ppm; 4 days |

Mechanical environmental conditions

The mechanical environmental conditions are shown in the following table in the form of sinusoidal oscillations. For this, each module of the ET 200X is secured to the substrate.

| Basic and expansion mo- dules | Frequency range | Permanent | Tested with |
|---|------------------------------|---------------------------|---------------------------------|
| All except motor starters/fre- quency converters and pneu- matic components | 5 ≤ f ≤ 8 Hz | 0.35 mm amplitude | 0.75 mm amplitude |
| | 8 ≤ f ≤ 150 Hz | 5 g constant acceleration | 10 g constant accelera- tion |
| Motor starters/frequency con- verters and pneumatic com- ponents | 5 ≤ f ≤ 8 Hz | 0.15 mm amplitude | 0.15 mm amplitude |
| | $8 \le f \le 150 \text{ Hz}$ | 2 g constant acceleration | 2 g constant acceleration |

Testing mechanical environmental conditions

The following tables provide information about the type and scope of tests for mechanical ambient conditions. For this, each module of the ET 200X is secured to the substrate.

| Test for | Test standard | Basic and expansion modules without motor starter/ frequency converter and pneumatic components |
|---------------------|--------------------------------------|---|
| Oscillations | Oscillation test to IEC 60068-2-8 | Type of oscillation: frequency sweeps with a rate of change of 1 octave per minute. 5 Hz \leq f \leq 8 Hz, constant amplitude of 0.75 mm 8 Hz \leq f \leq 150 Hz, constant acceleration of 10 g Duration of oscillation: 10 frequency sweeps per axis in each of the three perpendicular axes |
| Shock | Shock test to IEC 60068-2-27 | Type of shock: half-sine Shock strength: 30 g peak value, 18 ms duration Direction of the shock: 3 shocks per +/– direction in each of the three perpendicular axes |
| Repetitive shock | Shock test to IEC 60068-29 | Type of shock: half-sine Shock strength: 25 g peak value, 6 ms duration Direction of the shock: 1000 shocks per +/– direction in each of the three perpendicular axes |
| Test for | Test standard | Motor starters/frequency converters and pneumatic components |
| Oscillations | Oscillation test to IEC 60068-2-8 | Type of oscillation: frequency sweeps with a rate of change of 1 octave per minute. $5 \text{ Hz} \le f \le 8 \text{ Hz}$, constant amplitude of 0.15 mm $8 \text{ Hz} \le f \le 150 \text{ Hz}$, constant acceleration of 2 g Duration of oscillation: 10 frequency sweeps per axis in each of the three perpendicular axes |
| Shock | Shock test to IEC 60068-2-27 | Type of shock: half-sine Shock strength: 15 g peak value, 11 ms duration Direction of the shock: 3 shocks per +/– direction in each of the three perpendicular axes |

6.4 Details of insulation testing, safety class, degree of protection and rated voltage of the ET 200X

Test voltage

Insulation strength is demonstrated in the routine test with the following test voltage in accordance with IEC 61131-2:

| Circuits with rated voltage U _e to other circuits and ground | Test voltage |
|---|---|
| $0 \text{ V} < \text{U}_{\text{e}} \le 50 \text{ V}$ | 500 VDC |
| $300 \text{ V} < \text{U}_{\text{e}} \le 600 \text{ V}$ | 2.6 kVDC to ground 4 kVDC to backplane bus |

Pollution severity

Pollution severity 3 in accordance with IEC 61131

Safety class

Safety class I in accordance with IEC 60536

IP 65 degree of protection

Degree of protection IP 65 in accordance with IEC 60529 for all basic and expansion modules, EM 148-FC frequency converters, motor starters and pneumatic components of the ET 200X. This means:

- Protection against the ingress of dust and complete protection against electric shock
- Protection against water jets from nozzles which are aimed at the casing from all directions. (There must be no harmful effects from the water.)

IP 66 and IP 67 degrees of protection

Degree of protection IP 66 and IP 67 in accordance with IEC 60529 for all basic and expansion modules (except motor starters, EM 148-FC frequency converters and pneumatic components):

- Protection against the ingress of dust and complete protection against electric shock
- IP 66: Protection against heavy seas or strong water jets. (There must be no ingress of harmful quantities of water into the casing.)
- IP 67: Protection against water when the casing is immersed in it under defined pressure and time conditions. (There must be no ingress of harmful quantities of water into the casing.)

Note

The above-mentioned degrees of protection are only warranted when the ET 200X is completely closed. Therefore:

- Always plug all connectors for PROFIBUS-DP and the supply voltage for the electronics/sensors and the load into the basic module (BM 141, BM 142, BM 147/CPU), irrespective of whether or not they are all wired. An alternative is to close unused connectors with covers.
- Plug all the DESINA connectors into the BM 141-ECOFAST or BM 143-DESINA basic modules. Fit a cover if a DESINA socket remains unused.
- Seal off any terminal connections which are not required with screw caps.

NEMA classification of the ET 200X (for the US market)

All the basic and expansion modules of the ET 200X (except motor starters, EM 148-FC frequency converters, CPV 10 and CPV 40 valve terminals, and pneumatic modules) meet the requirements of NEMA: Enclosure rating Type: 4X – indoor use only.

Rated voltage for operation

The ET 200X distributed I/O device operates with the rated voltage and corresponding tolerances shown in the following table.

| Rated voltage | Tolerance range |
|---------------|------------------|
| 24 VDC | 20.4 to 28.8 VDC |

7

Technical Specifications

The ET 200X consists of different components that are connected together to form the ET 200X distributed I/O device. In this chapter, we have summarized the technical specifications relating to the different types of component.

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7.1 BM 141 DI 8 × DC 24V basic module (6ES7 141-1BF12-0XB0)

Features

The basic module BM 141 DI $8 \times DC$ 24V with the order number 6ES7 141-1BF12-0XB0 has the following features:

- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)

Pinout of the sockets for DI

The following table shows the pinout of the four sockets used to connect the digital inputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets 1 to 4 on the module in Appendix C.

| Table 7-1 | Pinout of the sockets for 8-channel digital inputs |
|-----------|--|
| | i modi or the societs for o charmer digital inputs |

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front view) |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|---|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | Ø ● 2 |
| 3 | Chassis ground, | (◯1 ◯5 ◯3) | | | |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | |
| 5 | PE | · | | | |

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram



The basic circuit diagram of the basic module is shown below.

Figure 7-1 Basic circuit diagram of the BM 141 DI 8 x DC 24V basic module

Parameters

The following tables provide an overview of the parameters on the basic module that can be set.

Table 7-2 Parameters of the BM 141 DI 8 × DC 24V

| | Parameters | | | Default | Area |
|---------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM803D.GSG ¹ | Standard slave with DDB file SI03803D.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | | Yes/no | Yes | ET 200X |
| Hardware interrupt | | | Yes/no | Yes | ET 200X |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load | voltage (S) | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 141-1BF12-0XB0, version 1

² The length of the diagnostic frame is \ge 32 bytes

| Dimensions ar | id weight | Electrical isolation | | |
|--|--|---|---|--|
| Dimensions | 134 $	imes$ 110 $	imes$ 55 | Between channels | No | |
| $W \times H \times D$ (mm) | | Between load voltage | Yes | |
| Weight | Approx. 500 g | components | | |
| Module-specific data | | • Between | Yes | |
| Baud rate | 9.6/19.2/93.75/187.5 /500 kbps 1.5/3/6/12 Mbps | PROFIBUS-DP and all other circuit components | | |
| Bus protocol | PROFIBUS-DP | Permissible potential diffe- | | |
| FREEZE compatibility | Yes | Between different | 75 VDC, 60 VAC | |
| SYNC compatibility | Yes | circuits | | |
| Number of inputs | 8 | Insulation tested with | 500 VDC | |
| Cable length | | Power input | | |
| Unshielded | Max. 30 m | From supply voltage 11 + | Max. 180 mA | |
| Manufacturer identification 803D _H | | | | |
| Voltages, currents | s, potentials | Status elerme diagnestice | | |
| Rated supply voltage for | 24 VDC | Status, alarms, diagnostics | | |
| electronic components and sensors 1L+ | | Status display | Green LED per channel | |
| Max. perm. current for | Up to 40 °C 1 A; | Alarms | Diagnostic interrupt | |
| electronic components and sensors | Up to 55 °C 0.8 A | Diagnostic functions | Configurable | |
| Reverse polarity | Yes | Group error | Red LED (SF) | |
| protection | | PROFIBUS-DP bus | Red LED (BF) | |
| Short circuit protection | Yes. electronic | monitoring | | |
| | , | Manitaring of the | | |
| Rated load voltage 2L + | 24 VDC | Monitoring of the electronics power | Green LED (ON) | |
| Rated load voltage 2L + Reverse polarity | 24 VDC No | Monitoring of the electronics power supply | Green LED (ON) | |
| Rated load voltage 2L + Reverse polarity protection | 24 VDC No | Monitoring of the electronics power supply Load voltage monitor | Green LED (ON) Green LED (24VDC) | |
| Rated load voltage 2L + Reverse polarity protection Max. perm. power input from load | 24 VDC No Up to 40 °C 10 A; Up to 55 °C 8 A | Monitoring of the electronics power supply Load voltage monitor Reading diagnostic information | Green LED (ON) Green LED (24VDC) Possible | |
| Rated load voltage 2L + Reverse polarity protection Max. perm. power input from load Maximum number of inputs | 24 VDC No Up to 40 °C 10 A; Up to 55 °C 8 A | Monitoring of the electronics power supply Load voltage monitor Reading diagnostic information | Green LED (ON) Green LED (24VDC) Possible r outputs | |
| Rated load voltage 2L + Reverse polarity protection Max. perm. power input from load Maximum number of inputs driven simultaneously All installation positions | 24 VDC No Up to 40 °C 10 A; Up to 55 °C 8 A | Monitoring of the electronics power supply Load voltage monitor Reading diagnostic information Sensor supply Outputs | Green LED (ON) Green LED (24VDC) Possible y outputs 4 | |
| Rated load voltage 2L + Reverse polarity protection Max. perm. power input from load Maximum number of inputs driven simultaneously All installation positions To 55 °C | 24 VDC No Up to 40 °C 10 A; Up to 55 °C 8 A | Monitoring of the electronics power supply Load voltage monitor Reading diagnostic information Sensor supply Outputs Output current* | Green LED (ON) Green LED (24VDC) Possible / outputs 4 Up to 40 °C | |
| Rated load voltage 2L + Reverse polarity protection Max. perm. power input from load Maximum number of inputs driven simultaneously All installation positions To 55 °C | 24 VDC No Up to 40 °C 10 A; Up to 55 °C 8 A | Monitoring of the electronics power supply Load voltage monitor Reading diagnostic information Sensor supply Outputs Output current* | Green LED (ON) Green LED (24VDC) Possible / outputs 4 Up to 40 °C max. 0.9A; Up to 55 °C max. 0.7A | |

| | Sensor selection data | | Input characteristic | To IEC 61131, |
|---------------|-----------------------|---------------|--|---------------|
| Input voltage | | | Туре 1 | |
| • | Rated value | 24 VDC | Connection of two-wire | Possible |
| • | With signal "1" | 13 to 30 V | BERUS | |
| • | With signal "0" | –3 to 5 V | Permissible closed-circuit current | Max. 1.5 mA |
| In | out current | | | |
| • | With signal "1" | Typ. 7 mA | * Please note the total current p | ber ET 200X. |
| In | out delay | | | |
| • | From "0" to "1" | 1.2 to 4.8 ms | | |
| • | From "1" to "0" | 1.2 to 4.8 ms | | |

7.2 BM 141 DI 8 × DC 24V ECOFAST basic module (6ES7 141-1BF01-0AB0)

Features

The BM 141 DI $8 \times$ DC 24V ECOFAST basic module with the order number 6ES7 141-1BF01-0AB0 has the following features:

- PROFIBUS-DP connection via copper conductors (RS 485)
- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)

Pinout of the sockets for DI

The following table shows the pinout of the eight sockets used to connect the digital inputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets in Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, | power supply | | | |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | 04 |
| 5 | PE | | | | |
| Pin | Assignment of socket X5 | Assignment of socket X6 | Assignment of socket X7 | Assignment of socket X8 | |
| 1 | Sensor supply o | utput 1L+ | · | · | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, | | | | |
| 4 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | |
| 5 | PE | • | | | 1 |

Table 7-3 Pinout of sockets X1 to X8 for digital inputs

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram



The basic circuit diagram of the basic module is show below.

Figure 7-2 Basic circuit diagram for the BM 141 DI 8 × DC 24V ECOFAST basic module (6ES7 141-1BF01-0AB0)

Parameters

The following tables provide an overview of the parameters on the basic module that can be set.

Table 7-4 Parameters of the BM 141 DI 8 × DC 24V ECOFAST

| | Parameters | | | Default | Area |
|---------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM80D2.GSG ¹ | Standard slave with DDB file SI0380D2.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | | Yes/no | Yes | ET 200X |
| Hardware interrupt | | | Yes/no | Yes | ET 200X |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load | voltage (S) | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 141-1BF01-0AB0, version 1

² The length of the diagnostic frame is \ge 32 bytes

| Dimensions a | Dimensions and weight | | No |
|---|----------------------------------|------------------------------------|----------------------------|
| Dimensions | 175 × 180 × 110 | Between load voltages | No |
| $W \times H \times D$ (mm) | | Between load voltage | No |
| Weight | Approx. 650 g | and all other circuitry | |
| Module-spec | Module-specific data | | Yes |
| Baud rate | 9.6/19.2/45.45/93.75/1 | other circuitry | |
| | 87.5/500 kbps 1.5/3/6/12 Mbps | Permissible potential diffe- | |
| Bus protocol | PROFIBUS-DP | rence | |
| FREEZE compatibility | Yes | Between different circuits | 75 VDC, 60 VAC |
| SYNC compatibility | Yes | Insulation tested with | 500 VDC |
| Number of channels | 8 digital inputs | Power input | |
| Cable length | | • From backplane bus | Max. 180 mA |
| Unshielded | Max. 30 m | (1L+) | |
| Manufacturer identification | 80D2 _H | Power loss of module | Typ. 3.5 W |
| Voltages, curren | ts, potentials | Status, alarms, | diagnostics |
| Non-switched rated load voltage (NS) | 24 VDC | Status display | Green LED per chan- nel |
| Max. perm. power | Up to 40 °C 10 A; | Alarms | Diagnostic interrupt |
| input from load | Up to 55 °C 8 A | Diagnostic functions | Configurable |
| Reverse polarity protection | No | Group error | Red LED (SF) |
| Short circuit protection | No | Status indicator | Green LED (RUN) |
| Switched rated load voltage (NS) | 24 VDC | Indicator for non-switched load | Green LED (DC 24V-NS) |
| Max. perm. power input from load | Up to 40 °C 10 A; | Indicator for switched | Green LED |
| Reverse polarity | No | load voltage | (DC 24V-S) |
| protection | | Reading diagnostic information | Possible |
| Maximum number of in- puts driven simulta- | | Sensor supp | ly outputs |
| neously | 8 | | 2 2 |
| all installed positions to max. 55 °C | | Output current* | Up to 40 °C max. 1A; |
| Electrical isolation | | Short circuit protection | Yes, electronic |
| Between channels and backplane bus | No | | |

| Sensor selection data | | | | | |
|-------------------------------------|---------------|--|--|--|--|
| Input voltage | | | | | |
| Rated value | 24 VDC | | | | |
| With signal "1" | 13 to 30 V | | | | |
| With signal "0" | – 3 to 5 V | | | | |
| Input current | | | | | |
| • With signal "1" | Typ. 7 mA | | | | |
| Input delay | | | | | |
| • From "0" to "1" | 1.2 to 4.8 ms | | | | |
| • From "1" to "0" | 1.2 to 4.8 ms | | | | |

| Input characteristic | To IEC 61131, Type 1 |
|--|----------------------|
| Connection of two-wire BEROs | Possible |
| Permissible closed-circuit current | Max. 1.5 mA |

Please note the total current per ET 200X.

7.3 BM 141 DI 8 × DC 24V ECOFAST DIAG basic module (6ES7 141-1BF40-0AB0)

Features

The BM 141 DI 8 \times DC 24V ECOFAST DIAG with the order number 6ES7 141-1BF40-0AB0 has the following features:

- PROFIBUS-DP connection via copper conductors (RS 485)
- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)
- Diagnostic interrupt for short circuit and wire break for each channel (I/O component of the basic module)
- Hardware interrupt at rising and falling edges for each channel (I/O component of the basic module)
- Direct communication
- Parameterizable input delays

Pinout of the sockets for DI

The following table shows the pinout of the eight sockets used to connect the digital inputs. You can find the wiring of the connector in the ET 200X manual, Section 4.4.4. You can find the layout of the sockets in the ET 200X manual, Appendix C.

| Table 7-5 | Pinout of sockets X1 to X8 for digit | al inputs |
|-----------|--------------------------------------|-----------|
| | | arinputs |

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, | power supply | | | |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | 01 05 03 |
| 5 | PE | | | | |
| Pin | Assignment of socket X5 | Assignment of socket X6 | Assignment of socket X7 | Assignment of socket X8 | |
| 1 | Sensor supply o | utput 1L+ | · | · | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, | | | | |
| 4 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | |
| | official filler | 0.101.110.0 | | | |

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram



The basic circuit diagram of the basic module is show below.

Figure 7-3 Basic circuit diagram for the BM 141 DI 8 \times DC 24V ECOFAST DIAG basic module (6ES7 141-1BF40-0AB0)

Parameters

The following tables provide an overview of the parameters on the basic module that can be set.

Table 7-6 Parameters of the BM 141 DI 8 × DC 24V ECOFAST DIAG

| Parameters | | | Range | Default | Area |
|---------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM80D3.GSG ¹ | Standard slave with DDB file SI0380D3.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | | Yes/no | Yes | ET 200X |
| Hardware interrupt | | | Yes/no | Yes | ET 200X |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load | voltage (S) | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 141-1BF40-0AB0, version 2

² The length of the diagnostic frame is \ge 32 bytes

| Table 7-7 | Parameters of the BM 141 DI 8 > | × DC 24V ECOFAST DIAG for | digital inputs |
|-----------|---------------------------------|---------------------------|----------------|
|-----------|---------------------------------|---------------------------|----------------|

| Parameters | Range | Default | Area affected |
|---|-------------------------------|---------|---------------|
| Input delay ¹ | 0.5 ms/ 3 ms/ 15 ms/ 20 ms | 3 ms | Module |
| Diagnosis: short circuit to M | Yes/no | No | Channel |
| Diagnosis: wire break | Yes/no | No | Channel |
| Diagnostic interrupt | Yes/no | No | Module |
| Hardware interrupt | Yes/no | No | Module |
| Hardware interrupt on rising edge ² | Yes/no | No | Channel |
| Hardware interrupt on falling edge ² | Yes/no | No | Channel |

¹ The input delay applies at "0" to "1" and at "1" to "0".

 2 These parameters can only be set if you enable the hardware interrupt parameter.

Technical data

| | Dimensions and weight | | | ermissible potential diffe- | |
|----------------|--|--------------------------------------|---------|-----------------------------------|--|
| Dii | mensions | 175 × 180 × 110 | re • | nce Between different | 75 VDC. 60 VAC |
| We | \times $\Pi \times D$ (mm) | Approx 650 g | | circuits | |
| | Module-spe | cific data | In | sulation tested with | 500 VDC |
| Ba | ud rate | 9 6/19 2/45 45/93 75/1 | Po | ower input | |
| | | 87.5/500 kbps 1.5/3/6/12 Mbps | • | From backplane bus (1L+) | Max. 180 mA |
| Bu | is protocol | PROFIBUS-DP | Po | ower loss of the module | Тур. 3.5 W |
| FR | REEZE compatibility | Yes | | Status, alarms, | diagnostics |
| SY | NC compatibility | Yes | St | atus display | Green LED per chan- nel |
| Nu Ca | imber of channels ible length | 8 digital inputs | Al | arms | Hardware interrupt Diagnostic interrupt |
| • | Unshielded | Max. 30 m | • | Hardware interrupt | Configurable |
| Ma | anufacturer identification | 80D3 _H | • | Diagnostic interrupt | Configurable |
| | Voltages, curren | ts, potentials | Di | agnostic functions | Configurable |
| No | on-switched rated load | 24 VDC | • | Group error | Red LED (SF) |
| • | Itage (NS) Max perm power | Lin to 40 °C 10 A | • | Status indicator | Green LED (RUN) |
| | input from load | Up to 55 °C 8 A | • | Indicator for | Green LED |
| • | Reverse polarity protection | No | | voltage | (DC 24V-NS) |
| • | Short-circuit protection | No | • | Indicator for switched | Green LED |
| Sv vo | vitched rated load Itage (NS) | 24 VDC | • | Channel error display | red LED per channel |
| • | Max. perm. power input from load | Up to 40 °C 10 A; Up to 55 °C 8 A | • | Reading diagnostic information | Possible |
| • | Reverse polarity protection | No | | | |
| Ma pu ne | aximum number of in- ts driven simulta- ously all installed positions | 8 | | | |
| | max. 55 °C | | | | |
| • | Between channels and | No | | | |
| | backplane bus | NO | | | |
| • | Between channels | No | | | |
| • | Between load voltages | No | | | |
| • | Between load voltage and all other circuitry | No | | | |
| • | Between PROFIBUS-DP and all other circuitry | Yes | | | |

| Sensor sup | oly outputs | At "0" to "1" and at "1" | Typ. 0.5 ms | |
|-------------------------------------|----------------------|---|----------------------|--|
| Outputs | 8 | to "0" | Typ. 3 ms | |
| Output current* | Up to 40 °C max. 1A; | | Typ. 15 ms | |
| Oh ant airea it ana ta ati an | to 55 °C max. 0.8A | | Typ. 20 ms | |
| Short-circuit protection | Yes, electronic | Input characteristic | To IEC 61131. Type 2 | |
| Sensor selection data | | Compaction of two wine | Descible | |
| Input voltage | | BEROs | Possible | |
| Rated value | 24 VDC | Permissible | Max. 1.5 mA ** | |
| With signal "1" | 13 to 30 V | closed-circuit current | | |
| • With signal "0" | – 3 to 5 V | | | |
| Input current | | * Please note the total current per ET 200X. ** The required closed-circuit current for wire | | |
| With signal "1" | Typ. 10 mA | detection is 0.6 mA < I < 1.5 | mA | |
| Input delay (parameteriza ble) | - | | | |

7.4 BM 142 DO 4 x DC 24V/2A basic module (6ES7 142-1BD22-0XB0)

Features

The BM 142 DO 4 x DC 24V/2A basic module, order number 6ES7 142-1BD22-0XB0, has the following features:

- 4 digital outputs
- Output current 2 A per output
- Rated load voltage 24 VDC
- Suitable for solenoids, DC contactors and indicator lights

Pinout of the sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets X1 to X4 on the module in Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front) |
|-----|---------------------------|---------------------------|---------------------------|------------------------------|------------------------------------|
| 1 | - | | | | |
| 2 | Output signal, channel 1* | - | Output signal, channel 3* | - | Ø ● 2 |
| 3 | Chassis ground, | | (◯1 ◯5 ◯3 | | |
| 4 | Output signal, channel 0 | Output signal, channel 1* | Output signal, channel 2 | Output signal, channel 3* | 04 |
| 5 | PE | • | | | |

 Table 7-8
 Pinout of the sockets for 4-channel digital outputs

* Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram



The basic circuit diagram of the basic module is shown below.

Figure 7-4 Basic circuit diagram of the BM 142 DO 4 x DC 24V/2A basic module

Parameters

The following table provides an overview of the parameters that can be set on the basic module.

Table 7-9 Parameters of the BM 142 DO 4 × DC 24V/2A

| | Parameters | | | Default | Area |
|---------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM803C.GSG ¹ | Standard slave with DDB file SI03803C.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | | Yes/no | Yes | ET 200X |
| Hardware interrupt | | | Yes/no | Yes | ET 200X |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load | voltage (S) | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 142-1BD22-0XB0, version 3

² The length of the diagnostic frame is \geq 32 bytes.

| Dimension | s and weight | Bus protocol | PROFIBUS-DP |
|----------------------------|-----------------------------------|-----------------------------|-------------------|
| Dimensions | 134 $	imes$ 110 $	imes$ 55 | FREEZE compatibility | Yes |
| $W \times H \times D$ (mm) | | SYNC compatibility | Yes |
| Weight | Approx. 500 g | Number of outputs | 4 |
| Module-s | pecific data | Cable length | |
| Baud rate | 9.6/19.2/93.75/187.5 /500 kbps | Unshielded | Max. 30 m |
| 1.5/3/6/12 Mbps | | Manufacturer identification | 803C _H |

| Voltages, currents, potentials | | | Status, alarms, diagnostics | | |
|--------------------------------|---|--------------------------------------|--|--|--|
| Ra ele | ated supply voltage for ectronic components and | 24 VDC | Status display Green LED per channel | | |
| se | Max perm current for | Lin to 40 °C 1 A. | Alarms Diagnostic interrupt | | |
| | electronic components | Up to 55 °C 0.8 A | Diagnostic functions Configurable | | |
| | and sensors | Yes | Group error Red LED (SF) | | |
| • | Reverse polarity protection | Yes, electronic | PROFIBUS-DP bus Red LED (BF) monitoring | | |
| • | Short-circuit protection | | Monitoring of the Green LED (ON) | | |
| Ra | ated load voltage 2L + | 24 VDC | electronics power supply | | |
| • | Reverse polarity | No | Load voltage monitor Green LED (DC24V) | | |
| | | | Reading diagnostic | | |
| fro | ax. perm. power input | Up to 40 °C 10 A; Up to 55 °C 8 A | information Possible | | |
| ۵c | areaste current of out- | | Actuator selection data | | |
| pu | ts | | Output voltage | | |
| • | All installation positions | Max 6 A | • With signal "1" Min. of 2L+ (- 0.8 V) Output current | | |
| | Up to 55 °C | Max. 4 A | With signal "1" | | |
| EI | ectrical isolation | | Rated value 2 A | | |
| • | Between channels and | Yes | Permissible range 5 mA to 2.4 A | | |
| | backplane bus | 100 | With signal "0" (residual Max. 0.5 mA current) | | |
| • | Between channels and supply voltage for electronic components | Yes | Load resistance range 12Ω to $4 k\Omega$ | | |
| • | Between channels | No | Lamp load Max. 10 W | | |
| • | Between load power supply and all other | Yes | Parallel connection of two outputs | | |
| | circuit components | | For redundant control of Possible (outputs of load same basic module) | | |
| • | Between | Yes | only) | | |
| | other circuit components | | For performance Not possible improvement | | |
| Pe | ermissible potential diffe- | | Driving a digital input Possible | | |
| • | Retween different | | Switching frequency | | |
| | circuits | 75 VDC, 60 VAC | Resistive load Max. 100 Hz | | |
| Ins | sulation tested with | 500 VDC | Inductive load to Max. 0.5 Hz IEC 947-5-1, DC13 | | |
| Po | ower input | | Lamp load Max. 1 Hz | | |
| • | From supply voltage 1L+ | Max. 180 mA | Limitation (internal) of vol- tage induced on circuit in- | | |
| • | From load voltage 2L+ (without load) | Max. 12 mA | Short-circuit protection for Yes, electronic | | |
| Pc | ower loss of module | Typ. 4 W | output | | |
| L | | | Response threshold Typ. 3 A | | |

7.5 BM 143-DESINA FO basic module (6ES7 143-1BF00-0XB0)

Features

The BM 143-DESINA FO basic module (order number 6ES7 143-1BF00-0XB0) has the following features:

- PROFIBUS-DP connection via fiber-optic cables
- 8 digital inputs or outputs (individually parameterizable as input or output) plus 8 diagnostic inputs or inputs with NC functionality (individually parameterizable).
- Rated input voltage of 24 VDC
- Digital inputs are suitable for switches and proximity switches (BERO switches)
- Digital outputs are suitable for solenoid valves, DC contactors and indicator lights

Pinout of the sockets for DI/DO

The tables below show the pinouts of the 8 sockets for connecting digital inputs and outputs. The connector wiring is described in Section 4.4.4. The arrangement of sockets X1 to X8 on the module in Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X3 | Assignment of socket X5 | Assignment of socket X7 | Front view of socket (Front view) |
|-----|---|---|---|---|---|
| 1 | Non-switched su | upply voltage DC | 24V-NS | | |
| 2 | Diagnostics input or input with NC functionality | |
| 3 | Chassis ground | power supply | 1 | J | |
| 4* | Digital input or output (DESINA) channel 0 | Digital input or output (DESINA) channel 2 | Digital input or output (DESINA) channel 4 | Digital input or output (DESINA) channel 6 | 04 |
| 5 | not assigned | 1 | 1 | 1 | 1 |

Table 7-10 Pinout of sockets X1, X3, X5 and X7 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-S switched supply voltage.

| Pin | Assignment of socket X2 | Assignment of socket X4 | Assignment of socket X6 | Assignment of socket X8 | Front view of socket (Front view) |
|-----|---|---|---|---|---|
| 1 | Non-switched su | upply voltage DC | 24V-NS | | |
| 2 | Diagnostics input or input with NC functionality | A Q2 |
| 3 | Chassis ground | power supply | 1 | | (◯1 ◯5 ◯3 |
| 4* | Digital input or output (DESINA) channel 1 | Digital input or output (DESINA) channel 3 | Digital input or output (DESINA) channel 5 | Digital input or output (DESINA) channel 7 | 04 |
| 5 | not assigned | 1 | 1 | 1 | 1 |

Table 7-11 Pinout of sockets X2, X4, X6 and X8 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-NS non-switched supply voltage.

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram

The basic circuit diagram of the basic module is shown below.



Figure 7-5 Basic circuit diagram of the BM 143-DESINA FO basic module

Parameters

The following table provides an overview of the parameters you can set for the basic module.

Table 7-12 Parameters of the BM 143-DESINA FO

| | Parameters | | | Default | Area |
|---------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM809A.GSG ¹ | Standard slave with DDB file SI03809A.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | | Yes/no | Yes | ET 200X |
| Hardware interrupt | | | Yes/no | Yes | ET 200X |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load | voltage (S) | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 143-1BF00-0XB0, version 5

² The length of the diagnostic frame is \geq 32 bytes.

| Parameters | Range | Default | Area affected |
|----------------------------------|---|---|---------------|
| Channel type for I/On (n= 07) | Digital input/ digital output | Digital output (Channel K0, K2, K4, K6) Digital input (Channel K1, K3, K5, K7) | Channel |
| Functional input In (n=815) | Diagnostic input/ diagnostic input with diagnostic frame/ Input with NC function | Diagnostic input | Channel |
| Response to CPU/master STOP | Output No current or voltage hold last value/ Apply substitute value/ | Output No current or voltage | Channel |
| Substitute value On (n=07) | 0/1 | 0 | Channel |
| Diagnostic interrupt | Yes/no | No | Module |

Table 7-13 Parameters of the BM 143-DESINA FO for digital inputs and outputs

| Dimensions and weight | | Between channels No | | |
|--|---|---|-------------------------------|--|
| Dimensions | 175 × 180 × 110 | Between load voltages | No | |
| $W \times H \times D$ (mm) Weight | Approx. 650 g | Between load voltage and all other circuitry | No | |
| Module-specific data | | Between | Yes | |
| Baud rate | 9.6/19.2/45.45/93.75/ 187.5/500 kbps 1.5/3/6/12 Mbps | PROFIBUS-DP and all other circuitry | | |
| | | Permissible potential diffe- | | |
| Bus protocol | PROFIBUS-DP | Between different | 75 VDC, 60 VAC | |
| FREEZE compatibility | Yes | circuits | | |
| SYNC compatibility | Yes | Insulation tested with | 500 VDC | |
| Number of channels | 8 digital inputs and outputs 8 functional inputs (diagnostics inputs or inputs with | Power loss of module | Тур. 3.5 W | |
| | | Status, alarms, diagnostics | | |
| | | Status display | Yellow LED per channel | |
| Cable length | NC functionality) | Indicator for functional input | Yellow/red LED per channel | |
| Unshielded | Max. 30 m | Alarms | Diagnostic interrupt | |
| Manufacturer identification | 809A _H | Diagnostic functions | Configurable | |
| Voltages, currents, potentials | | Group error | Red LED (SF) | |
| Non-switched rated load | 24 VDC | Status indicator | Green LED (RUN) | |
| Max. perm. power input from load | Up to 40 °C 10 A; Up to 55 °C 8 A | Indicator for non-switched load voltage | Green LED (DC 24V-NS) | |
| Reverse polarity protection | No | Indicator for switched load voltage | Green LED (DC 24V-S) | |
| Short-circuit protection | No | Reading diagnostic | Possible | |
| Switched rated load voltage (NS) | 24 VDC | information | | |
| • Max. perm. power input | Up to 40 °C 10 A; | Sensor suppry | ouipuis | |
| from load | Up to 55 °C 8 A | Outputs Output current | 8 Up to 40 °C | |
| Reverse polarity protection | No | | max. 1 A; Up to 55 °C | |
| Maximum number of inputs | | Shart airquit protaction | max. 0.8 A | |
| all installed positions max. 55 °C | 8 | Short-circuit protection | | |
| Aggregate current of out- | | | | |
| All installation positions | | | | |
| To 20 °C | Max. 10 A | | | |
| To 50 °C | Max. 6 A | | | |
| To 55 °C | Max. 5 A | | | |
| Electrical isolation | | | | |
| Between channels and backplane bus | No | | | |

| Sensor selection data | | Actuator selection data | | |
|---|-------------------------|---|------------------------------|--|
| Input voltage for paramete- | | Output voltage | | |
| rized DI (pin 4) | | With signal "1" | Min. NS/S (– 0.8 V) | |
| Rated value | 24 VDC | Output current | | |
| With signal "1" | 13 to 30 V | With signal "1" | | |
| With signal "0" | -30 to 5V | Rated value | 1.2 A | |
| Input voltage for functional input (pin 2) | | Permissible rangeWith signal "0" (residual | 7 mA to 1.3 A Max. 0.5 mA | |
| Rated value | 24 VDC | current) | | |
| With signal "1" | 13 to 30 V | Load resistance range | 21 ohms to 4 kohms | |
| With signal "0" | –30 to 2 V | Lamp load | Max. 10 W | |
| Input current | | Parallel connection of two | No | |
| With signal "1" | Typ. 5 mA | outputs | | |
| Input delay | | Driving a digital input | Possible | |
| • From "0" to "1" | 1.2 to 4.8 ms | Switching frequency | | |
| • From "1" to "0" | 1.2 to 4.8 ms | Resistive load | Max. 100 Hz | |
| Input characteristic | To IEC 61131, Type 2 | Inductive load to IEC 947-5-1, DC13 | Max. 2 Hz | |
| Connection of two-wire BE- | Possible | Lamp load | Max. 1 Hz | |
| ROs | | Limitation (internal) of vol- | Typ. NS/S (– 47 V) | |
| Permissible closed-circuit current | Max. 1.5 mA | terruption | | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 1.8 А | |

7.6 BM 143-DESINA RS485 basic module (6ES7 143-1BF00-0AB0)

Features

The BM 143-DESINA RS485 basic module with the order number 6ES7 143-1BF00-0AB0 has the following features:

- PROFIBUS-DP connection via copper conductors (RS 485)
- 8 digital inputs or outputs (individually parameterizable as input or output) plus 8 diagnostic inputs or inputs with NC functionality (individually parameterizable).
- Rated input voltage of 24 VDC
- Digital inputs are suitable for switches and proximity switches (BERO switches)
- Digital outputs are suitable for solenoid valves, DC contactors and indicator lights

Pinout of the sockets for DI/DO

The following tables show the pinouts of the eight sockets used to connect the digital inputs or outputs. The connector wiring is described in Section 4.4.4. The arrangement of sockets X1 to X8 on the module in Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X3 | Assignment of socket X5 | Assignment of socket X7 | Front view of socket (Front view) |
|-----|---|---|---|---|---|
| 1 | Non-switched su | | | | |
| 2 | Diagnostics input or input with NC functionality | |
| 3 | Chassis ground, | | | | |
| 4* | Digital input or output (DESINA) channel 0 | Digital input or output (DESINA) channel 2 | Digital input or output (DESINA) channel 4 | Digital input or output (DESINA) channel 6 | 04 |
| 5 | not assigned | | | 1 | 1 |

Table 7-14 Pinout of sockets X1, X3, X5 and X7 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-S switched supply voltage.
| Pin | Assignment of socket X2 | Assignment of socket X4 | Assignment of socket X6 | Assignment of socket X8 | Front view of socket (Front view) |
|-----|---|---|---|---|---|
| 1 | Non-switched su | upply voltage DC | 24V-NS | | |
| 2 | Diagnostics input or input with NC functionality | |
| 3 | Chassis ground | , power supply | | | |
| 4* | Digital input or output (DESINA) channel 1 | Digital input or output (DESINA) channel 3 | Digital input or output (DESINA) channel 5 | Digital input or output (DESINA) channel 7 | 04 |
| 5 | not assigned | 1 | 1 | 1 | 1 |

Table 7-15 Pinout of sockets X2, X4, X6 and X8 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-NS non-switched supply voltage.

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram

The basic circuit diagram of the basic module is shown below.



Figure 7-6 Basic circuit diagram of the BM 143-DESINA RS485 basic module

Parameters

The following table provides an overview of the parameters you can set for the basic module.

Table 7-16 Parameters of the BM 143-DESINA RS485

| | Parameters | | | | Area |
|--------------------------------|--|--|-----------|---------|----------|
| S7 slave with HWCONFIG | Standard slave with DDB file SIEM809A.GSG ¹ | Standard slave with DDB file SI03809A.GSG ¹ | | | affected |
| | | DP interrupt mode | DPV0/DPV1 | DPV1 | ET 200X |
| Diagnostic interrupt | | Yes/no | Yes | ET 200X | |
| Hardware interrupt | Yes/no | Yes | ET 200X | | |
| | Enhanced diagnostics ² | | Yes/no | Yes | ET 200X |
| | | Startup when expected/actual config. differ | Yes/no | No | ET 200X |
| Diagnosis: no load voltage (S) | | | Yes/no | Yes | ET 200X |
| | | Module diagnosis | Yes/no | Yes | ET 200X |
| | | Module status | Yes/no | Yes | ET 200X |
| | | Channel-specific diagnosis | Yes/no | Yes | ET 200X |

¹ As of basic module 6ES7 143-1BF00-0AB0, version 2

² The length of the diagnostic frame is \geq 32 bytes.

| Parameters | Range | Default | Area affected |
|----------------------------------|---|---|---------------|
| Channel type for I/On (n= 07) | Digital input/ digital output | Digital output (Channel K0, K2, K4, K6) Digital input (Channel K1, K3, K5, K7) | Channel |
| Functional input In (n=815) | Diagnostic input/ diagnostic input with diagnostic frame/ Input with NC function | Diagnostic input | Channel |
| Response to CPU/master STOP | Output No current or voltage hold last value/ Apply substitute value/ | Output No current or voltage | Channel |
| Substitute value On (n=07) | 0/1 | 0 | Channel |
| Diagnostic interrupt | Yes/no | No | Module |

Table 7-17 Parameters of the BM 143-DESINA RS485 for digital inputs and outputs

| Dimensions an | d Weight | Electrical isolation | |
|---|---|---|--|
| Dimensions W \times H \times D (mm) | 175 × 180 × 110 | Between channels and backplane bus | No |
| Weight | Approx. 650 g | Between channels | No |
| Module-speci | fic data | Between load voltages | No |
| Baud rate | 9.6/19.2/45.45/93.75/ 187.5/500 kbps | Between load voltage and all other circuitry | No |
| Bus protocol | PROFIBUS-DP | Between PROFIBUS-DP and all other circuitry | Yes |
| FREEZE compatibility SYNC compatibility | Yes Yes | Permissible potential diffe- rence | 75 VDC, 60 VAC |
| Number of channels | 8 digital inputs and outputs | Between different circuits | |
| | 8 functional | Insulation tested with | 500 VDC |
| | inputs or inputs with | Power loss of module | Typ. 3.5 W |
| | NC functionality) | Status, alarms, d | iagnostics |
| Cable length Unshielded | Max. 30 m | Status display | Yellow LED per channel |
| Manufacturer identification | 809A _H | Indicator for functional input | Yellow/red LED per channel |
| Voltages, currents, potentials | | Alarms | Diagnostic interrupt |
| Non-switched rated load voltage (NS) | 24 VDC | Diagnostic functions | Configurable |
| Max. perm. power input from load | Up to 40 °C 10 A; | Group error | Red LED (SF) |
| Reverse polarity | No | Status indicator | Green LED (RUN) |
| Short-circuit protection | No | Indicator for non-switched load (DC 24V-NS) | Green LED (DC 24V-NS) |
| Switched rated load voltage (NS) | 24 VDC | Indicator for switched load voltage | Green LED (DC 24V-S) |
| Max. perm. power input from load Boyoroo polority | Up to 40 °C 10 A; Up to 55 °C 8 A | Reading diagnostic information | Possible |
| protection | NO | Sensor supply | outputs |
| Maximum number of inputs driven simultaneously • all installed positions max 55 °C | 8 | Outputs Output current | 8 Up to 40 °C max. 1 A; Up to 55 °C |
| Aggregate current of out- puts | | Short-circuit protection | max. 0.8 A Yes, electronic |
| All installation positions | | | |
| To 20 °C | Max. 10 A | | |
| To 50 °C | Max. 6 A | | |
| To 55 °C | Max. 5 A | | |

| Sensor select | ion data | Actuator selection data | | |
|--|-------------------------|---|---------------------|--|
| Input voltage for paramete- | | Output voltage | | |
| Rated value | 24 VDC | With signal "1" Output current | Min. NS/S (– 0.8 V) | |
| With signal "1" | 13 to 30 V | With signal "1" | | |
| With signal "0" | –30 to 5V | Rated value | 1.2 A | |
| Input voltage for functional | | Permissible range | 7 mA to 1.3 A | |
| input (pin 2) | | • With signal "0" (residual | Max. 0.5 mA | |
| Rated value | 24 VDC | current) | | |
| With signal "1" | 13 to 30 V | Load resistance range | 21 ohms to 4 kohms | |
| With signal "0" | –30 to 2 V | Lamp load | Max. 10 W | |
| Input current | | Parallel connection of two | No | |
| With signal "1" | Typ. 5 mA | outputs | | |
| Input delay | | Driving a digital input | Possible | |
| • From "0" to "1" | 1.2 to 4.8 ms | Switching frequency | | |
| • From "1" to "0" | 1.2 to 4.8 ms | Resistive load | Max. 100 Hz | |
| Input characteristic | To IEC 61131, Type 2 | Inductive load to IEC 947-5-1, DC13 | Max. 2 Hz | |
| Connection of two-wire BE- | Possible | Lamp load | Max. 1 Hz | |
| ROs | | Limitation (internal) of vol- | Typ. NS/S (– 47 V) | |
| Permissible closed-circuit current | Max. 1.5 mA | tage induced on circuit in- terruption | | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 1.8 А | |

7.7 EM 141 DI 4 \times DC 24V expansion module (6ES7 141-1BD31-0XA0)

Features

The EM 141 DI 4 \times DC 24V expansion module; order number 6ES7 141-1BD31-0XA0 has the following features:

- 4 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)

Pinout of the sockets for DI

The following table shows the pinout of the four sockets used to connect the digital inputs. You can find the wiring of the connector in Section 4.4.3. You can find the layout of the sockets in Appendix C.

Table 7-18 Pinout of the sockets for 4-channel digital inputs

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|------------------------------|-----------------------------|-----------------------------|-----------------------------|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | Input signal, channel 1* | - | Input signal, channel 3* | - | Ø ● 2 |
| 3 | Chassis ground, power supply | | | | (◯1 ◯5 ◯3 |
| 4 | Input signal, channel 0 | Input signal, channel 1* | Input signal, channel 2 | Input signal, channel 3* | |
| 5 | PE | | | I | 1 |

* Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

Covering up unused connections

The basic circuit diagram of the expansion module is shown below.



Figure 7-7 Basic circuit diagram of expansion module EM 141 DO 4 x DC 24V

| Dimensions ar | nd weight | Status, alarms, diagnostics | | |
|--|---|--|--------------------------|--|
| Dimensions W \times H \times D (mm) | $87 \times \times 110 \times \times 55$ | Status display | Green LED per channel | |
| Weight | Approx. 250 g | Alarms | None | |
| Module-spec | fic data | Sensor supp | ly outputs | |
| Number of inputs | 4 | Outputs | 4 | |
| Cable length | | Output current* | Up to 40 °C | |
| Unshielded | Max. 30 m | | Up to 55 °C | |
| Voltages, currents | s, potentials | | max. 0.7A | |
| Maximum number of inputs | - | Short-circuit protection | Yes, electronic | |
| driven simultaneously | | Sensor selec | ction data | |
| All installation positions | 4 | Input voltage | | |
| Up to 55 °C | | Rated value | 24 VDC | |
| Electrical isolation | No | With signal "1" | 13 to 30 V | |
| Permissible notential diffe- | | With signal "0" | - 3 to 5 V | |
| rence | | Input current | | |
| Between different | 75 VDC. 60 VAC | With signal "1" | Typ. 7 mA | |
| circuits | | Input delay | | |
| Insulation tested with | 500 VDC | • From "0" to "1" | 1.2 to 4.8 ms | |
| Power input | | • From "1" to "0" | 1.2 to 4.8 ms | |
| From backplane bus (1L+) | Max. 16 mA | Input characteristic | To IEC 61131, Type 1 | |
| Power loss of module | Тур. 1.5 W | Connection of two-wire BEROs | Possible | |
| | | Permissible closed-circuit current | Max. 1.5 mA | |

* Please note the total current per ET 200X.

7.8 EM 141 DI 8 × DC 24V expansion module (6ES7 141-1BF31-0XA0)

Features

The EM 141 DI 8 x DC 24V expansion module with the order number 6ES7 141-1BF31-0XA0 has the following features:

- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)

Pinout of the sockets for DI

The following table shows the pinout of the four sockets used to connect the digital inputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets in Appendix C.

Table 7-19 Pin assignment of sockets for 8-channel digital inputs

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|------------------------------|----------------------------|----------------------------|----------------------------|----------------------|
| 1 | Sensor supply c | output 1L+ | | | |
| 2 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | Ø ● 2 |
| 3 | Chassis ground, power supply | | | | (◯1 ◯5 ◯3 |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | |
| 5 | PE | 1 | 1 | | 1 |

Covering up unused connections

The basic circuit diagram of the expansion module is shown below.



Figure 7-8 Basic circuit diagram for expansion module EM 141 DI 8 x DC 24V (6ES7 141-1BF31-0XA0)

| Dimensions ar | nd weight | Status, alarms, | diagnostics |
|--|----------------|--------------------------|------------------------------|
| Dimensions W \times H \times D (mm) | 87 × 110 × 55 | Status display | Green LED per channel |
| Weight | Approx. 250 g | Alarms | None |
| Module-spec | ific data | Sensor supp | ly outputs |
| Number of inputs | 8 | Outputs | 4 |
| Cable length | | Output current* | Up to 40 °C max, 0.9A: |
| Unshielded | Max. 30 m | | Up to 55 °C |
| Voltages, currents | s, potentials | Short-circuit protection | max. 0.7A Yes, electronic |
| Maximum number of inputs driven simultaneously | | | |
| All installed positions max. 55 °C | 8 | | |
| Electrical isolation | No | | |
| Permissible potential diffe- rence | | | |
| Between different circuits | 75 VDC, 60 VAC | | |
| Insulation tested with | 500 VDC | | |
| Power input | | | |
| From backplane bus (1L+) | Max. 16 mA | | |
| Power loss of module | Typ. 1.5 W | | |

| Sensor se | Input characteristic | |
|---|----------------------|----------------------------------|
| Input voltage Rated value With signal "1" | 24 VDC 13 to 30 V | Connection of two BEROs |
| With signal "0" | – 3 to 5 V | Permissible closed-circuit c |
| With signal "1" | typ. 7 mA | * Please note the to |
| Input delay From "0" to "1" From "1" to "0" | 1.2 to 4.8 ms | |

| Input characteristic | To IEC 61131, Type 1 |
|--|-------------------------|
| Connection of two-wire BEROs | Possible |
| Permissible closed-circuit current | Max. 1.5 mA |

* Please note the total current per ET 200X.

7.9 EM 141 DI 8 \times DC 24V DIAG expansion module (6ES7 141-1BF30-0XB0)

Hardware

The expansion module can be used together with the following basic modules:

| • | BM 141 DI 8×DC 24V, | 6ES7 141-1BF01-0XB0, from product version 05 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01 |
|---|---------------------------|--|
| • | BM 141 DI 8 × DC 24V ECOF | AST, 6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01 |
| • | BM 141 DI 8×DC 24V ECO | FAST DIAG, 6ES7 141-1BF40-0AB0, from product version 01 |
| • | BM 142 DO 4×DC 24V/2A, | 6ES7 142-1BD11-0XB0, from product version 05 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01 |
| • | BM 143-DESINA FO, | 6ES7 143-1BF00-0XB0, from product version 01 |
| • | BM 143-DESINA RS485, | 6ES7 143-1BF00-0AB0, from product version 01 |
| • | BM 147/CPU, | 6ES7 147-1AA00-0XB0, from product version 01 |

Features

The EM 141 DI 8 x DC 24V DIAG expansion module with the order number 6ES7 141-1BF30-0XB0 has the following features:

- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)
- Diagnostic interrupt for short circuit and wire break for each channel
- Hardware interrupt for rising and falling pulse edge for each channel
- Short type (110 mm)
- Parameterizable input delays

Pinout of the sockets for DI

The following table shows the pinout of the four sockets used to connect the digital inputs. You can find the wiring of the connector in the ET 200X manual, Section 4.4.4. You can find the layout of the sockets in the ET 200X manual, Appendix C.

Table 7-20 Pinout of socket X1 to X4 for digital inputs

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | |
| 3 | Chassis ground | power supply | | | 04 |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | |
| 5 | PE | | | | 1 |

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram

The basic circuit diagram of the expansion module is show below.



Figure 7-9 Basic circuit diagram for expansion module EM 141 DI 8 x DC 24V DIAG (6ES7 141-1BF30-0XB0)

Parameters

The following table summarizes the parameters that you can set for the expansion module.

Table 7-21 Parameters of the EM 141 DI 8 \times DC 24V DIAG

| Parameters | Range | Default | Area affected |
|---|-------------------------------|---------|---------------|
| Input delay ¹ | 0.5 ms/ 3 ms/ 15 ms/ 20 ms | 3 ms | Module |
| Diagnosis: short circuit to M | Yes/no | No | Channel |
| Diagnosis: wire break | Yes/no | No | Channel |
| Diagnostic interrupt | Yes/no | No | Module |
| Hardware interrupt | Yes/no | No | Module |
| Hardware interrupt on rising edge ² | Yes/no | No | Channel |
| Hardware interrupt on falling edge ² | Yes/no | No | Channel |

1

The input delay applies at "0" to "1" and at "1" to "0". These parameters can only be set if you enable the hardware interrupt parameter. 2

Technical data

| Dimensions and weight | | Sensor supply outputs | | |
|--|--|-------------------------------------|--|--|
| Dimensions W \times H \times D (mm) | 87 × 110 × 55 | Outputs Output current* | 4 Up to 40 °C max. 0.5A; | |
| Weight | Approx. 250 g | | Up to 55 °C | |
| Module-spe | cific data | + | max. 0.4A | |
| Number of inputs | 8 | Aggregate current | Up to 40 °C | |
| Cable length | | | max. 0.9A; | |
| Unshielded | Max. 30 m | | Up to 55 °C max, 0.7A | |
| Voltages, curren | its, potentials | | | |
| Maximum number of in- | | Short-circuit protection | Yes, electronic | |
| puts driven simulta- | | Sensor sele | ction data | |
| All installed positions | 8 | Input voltage | | |
| max. 55 °C | | Rated value | 24 VDC | |
| Electrical isolation | Νο | With signal "1" | 13 to 30 V | |
| Dormissible notential diffe | | With signal "0" | – 3 to 5 V | |
| rence | | Input current | | |
| • Detugen different | | With signal "1" | Typ. 10 mA | |
| Between different circuits | 75 VDC, 60 VAC | Input delay (parameteriza- ble) | | |
| Insulation tested with | 500 VDC | At "0" to "1" and at "1" | Tvp. 0.5 ms | |
| Power input | | to "0" | Typ. 3 ms | |
| From backplane bus | Max. 30 mA | | Typ. 15 ms | |
| (1L+) | | | Typ. 20 ms | |
| Power loss of module | Typ. 1.5 W | Input characteristic | To IEC 61131, Type 2 | |
| Status, alarms, | diagnostics | Connection of two-wire | Possible | |
| Status display | Green LED per chan- | BEROs | | |
| | nel | Permissible | Max. 1.5 mA ** | |
| Alarms | Hardware interrupt Diagnostic interrupt | closed-circuit current | | |
| Hardware interrupt | Configurable | ** The required closed-circu | t per ET 200X. uit current for wire break | |
| Diagnostic interrupt | Configurable | detection is 0.6 mA < I < 1.5 | mA | |
| Diagnostic functions | Configurable | | | |
| Group error | Red LED (SF) | | | |
| Channel error display | Red LED per channel | | | |
| Reading diagnostic | Possible | | | |

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information

7.10 EM 141 DI 8 × DC 24V expansion module (6ES7 141-1BF41-0XA0)

Features

The EM 141 DI 8 x DC 24V expansion module with the order number 6ES7 141-1BF41-0XA0 has the following features:

- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)

Pinout of the sockets for DI

The following table shows the pinout of the eight sockets used to connect the digital inputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets in Appendix C.

| Table 7-22 | Pinout of so | ocket X1 to | X8 for | digital in | outs |
|------------|---------------|-------------|--------|------------|-------|
| | i inout of st | | 70 101 | uigitai ii | ipuis |

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|---|---|--|--|--|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | not assigned | | | | |
| 3 | Chassis ground | power supply | | | |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | |
| 5 | PE | | | 1 | |
| Dia | | | | | |
| PIN | Assignment of socket X5 | Assignment of socket X6 | Assignment of socket X7 | Assignment of socket X8 | |
| 1 Pin | Assignment of socket X5 Sensor supply o | Assignment of socket X6 utput L+ | Assignment of socket X7 | Assignment of socket X8 | - |
| 1 2 | Assignment of socket X5 Sensor supply o not assigned | Assignment of socket X6 utput L+ | Assignment of socket X7 | Assignment of socket X8 | |
| 1 2 3 | Assignment of socket X5 Sensor supply of not assigned Chassis ground, | Assignment of socket X6 utput L+ power supply | Assignment of socket X7 | Assignment of socket X8 | |
| Pin 1 2 3 4 | Assignment of socket X5 Sensor supply of not assigned Chassis ground, Input signal, channel 4 | Assignment of socket X6 utput L+ power supply Input signal, channel 5 | Assignment of socket X7 Input signal, channel 6 | Assignment of socket X8 Input signal, channel 7 | |

Covering up unused connections

The basic circuit diagram of the expansion module is show below.



Figure 7-10 Basic circuit diagram of expansion module EM 141 DI 8 x DC 24V (6ES7 141-1BF41-0XA0)

| Dimensions and weight | | Status, alarms, diagnostics | |
|--|----------------|---|--|
| Dimensions W \times H \times D (mm) | 87 × 180 ×≡≡ | Status display | Green LED per chan- nel |
| Weight | Approx. 350 g | Alarms | None |
| Module-spe | cific data | Sensor supp | ly outputs |
| Number of inputs Cable length • Unshielded | 8 Max. 30 m | Outputs Output current* | 8 Up to 40 °C max. 1A; Up to 55 °C max_0.8A |
| Voltages, curren | ts, potentials | Short-circuit protection | Yes, electronic |
| Maximum number of in- | | Sensor sele | ction data |
| puts driven simulta- neously All installed positions max. 55 °C | 8 | Input voltage Rated value With signal "1" With signal "0" | 24 VDC 13 to 30 V – 3 to 5 V |
| Electrical isolation | No | Input current | |
| Permissible potential diffe- rence | | With signal "1" | Typ. 7 mA |
| Between different circuits | 75 VDC, 60 VAC | Input delay • From "0" to "1" • From "1" to "0" | 1.2 to 4.8 ms |
| | 500 VDC | | |
| From backplane bus (1L+) | Max. 10 mA | Connection of two-wire BEROs | To IEC 61131, Type 1 Possible |
| Power loss of module | Тур. 1.5 W | Permissible closed-circuit current | Max. 1.5 mA |

*

Please note the total current per ET 200X.

7.11 EM 141 DI 8 \times DC 24V DIAG expansion module (6ES7 141-1BF40-0XB0)

Hardware

The expansion module can be used together with the following basic modules:

| • | BM 141 DI 8×DC 24V, | 6ES7 141-1BF01-0XB0, from product version 05 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01 |
|---|---------------------------|--|
| • | BM 141 DI 8 × DC 24V ECOF | AST, 6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01 |
| • | BM 141 DI 8×DC 24V ECO | FAST DIAG, 6ES7 141-1BF40-0AB0, from product version 01 |
| • | BM 142 DO 4×DC 24V/2A, | 6ES7 142-1BD11-0XB0, from product version 05 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01 |
| • | BM 143-DESINA FO, | 6ES7 143-1BF00-0XB0, from product version 01 |
| • | BM 143-DESINA RS485, | 6ES7 143-1BF00-0AB0, from product version 01 |
| • | BM 147/CPU, | 6ES7 147-1AA00-0XB0, from product version 01 |

Features

The EM 141 DI 8 x DC 24V DIAG expansion module with the order number 6ES7 141-1BF40-0XB0 has the following features:

- 8 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)
- Diagnostic interrupt for short circuit and wire break for each channel
- Hardware interrupt for rising and falling pulse edge for each channel
- Long type (180 mm)
- Parameterizable input delays

Pinout of the sockets for DI

The following table shows the pinout of the eight sockets used to connect the digital inputs. You can find the wiring of the connector in the ET 200X manual, Section 4.4.4. You can find the layout of the sockets in the ET 200X manual, Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket |
|-----|------------------------------|----------------------------|----------------------------|----------------------------|----------------------|
| 1 | Sensor supply o | utput 1L+ | | | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, | power supply | | | |
| 4 | Input signal, channel 0 | Input signal, channel 1 | Input signal, channel 2 | Input signal, channel 3 | |
| 5 | PE | | 1 | 1 | |
| Pin | Assignment of socket X5 | Assignment of socket X6 | Assignment of socket X7 | Assignment of socket X8 | |
| 1 | Sensor supply o | utput 1L+ | | · | |
| 2 | not assigned | | | | |
| 3 | Chassis ground, power supply | | | | |
| 4 | Input signal, channel 4 | Input signal, channel 5 | Input signal, channel 6 | Input signal, channel 7 | |
| 5 | PE | | | | 1 |

Table 7-23 Pinout of sockets X1 to X8 for digital inputs

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram

The basic circuit diagram of the expansion module is show below.



Figure 7-11 Basic circuit diagram of expansion module EM 141 DI 8 x DC 24V DIAG (6ES7 141-1BF40-0XB0)

Parameters

The following table summarizes the parameters that you can set for the expansion module.

Table 7-24 Parameters of the EM 141 DI 8 \times DC 24V DIAG

| Parameters | Range | Default | Area affected |
|---|-------------------------------|---------|---------------|
| Input delay ¹ | 0.5 ms/ 3 ms/ 15 ms/ 20 ms | 3 ms | Module |
| Diagnosis: short circuit to M | Yes/no | No | Channel |
| Diagnosis: wire break | Yes/no | No | Channel |
| Diagnostic interrupt | Yes/no | No | Module |
| Hardware interrupt | Yes/no | No | Module |
| Hardware interrupt on rising edge ² | Yes/no | No | Channel |
| Hardware interrupt on falling edge ² | Yes/no | No | Channel |

1

The input delay applies at "0" to "1" and at "1" to "0". These parameters can only be set if you enable the hardware interrupt parameter. 2

Technical data

| Dimensions a | and weight | Sensor supply outputs | | |
|--|--|--|--------------------------|--|
| Dimensions $W \times H \times D$ (mm) | 87 × 180 × 55 | Outputs Output current* | 8 Up to 40 °C | |
| Weight | Approx. 350 g | | Up to 55 °C | |
| Module-spe | cific data | | max. 0.4A | |
| Number of inputs | 8 | Aggregate current | Up to 40 °C max. 1A; | |
| Cable length | | | Up to 55 °C max. | |
| Unshielded | Max. 30 m | | U.0A | |
| Voltages, curren | ts, potentials | Short-circuit protection | Yes, electronic | |
| Maximum number of in- | | Sensor selec | ction data | |
| puts driven simulta- neously | 0 | Input voltage | | |
| All installed positions | 8 | Rated value | 24 VDC | |
| max. 55 °C | | With signal "1" | 13 to 30 V | |
| Electrical isolation | No | With signal "0" | – 3 to 5 V | |
| Permissible potential diffe- | | Input current | | |
| rence | | With signal "1" | Typ. 10 mA | |
| Between different circuits | 75 VDC, 60 VAC | Input delay (parameteriza- ble) | | |
| Insulation tested with | 500 VDC | At "0" to "1" and at "1" | Typ. 0.5 ms | |
| Power input | | to "0" | Typ. 3 ms | |
| From backplane bus (1L+) | Max. 30 mA | | Typ. 15 ms Typ. 20 ms | |
| Power loss of module | Typ. 1.5 W | Input characteristic | To IEC 61131, Type 2 | |
| Status, alarms, | diagnostics | Connection of two-wire BEROs | Possible | |
| Status display | Green LED per chan- nel | Permissible closed-circuit current | Max. 1.5 mA ** | |
| Alarms | Hardware interrupt Diagnostic interrupt | * Please note the total current | per ET 200X. | |
| Hardware interrupt | Configurable | detection is 0.6 mA < I < 1.5 | mA | |
| Diagnostic interrupt | Configurable | | | |
| Diagnostic functions | Configurable | | | |
| Group error | Red LED (SF) | | | |
| Channel error display | red LED per channel | | | |
| Reading diagnostic information | Possible | | | |

7.12 EM 142 DO 4 x DC 24V/0.5A expansion module (6ES7 142-1BD30-0XA0)

Features

The EM 142 DO 4 \times DC 24V/0.5A expansion module; order number 6ES7 142-1BD30-0XA0 has the following features:

- 4 digital outputs
- Output current 0.5 A per output
- Rated load voltage 24 VDC
- Suitable for solenoids, DC contactors and indicator lights

Pinout of the sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. You can find the layout of the sockets in Appendix C. The connector wiring is described in Section 4.4.3.

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front) |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|------------------------------------|
| 1 | - | | | | |
| 2 | Output signal, channel 1* | _ | Output signal, channel 3* | _ | Ø ● 2 |
| 3 | Chassis ground, | load power supply | / | | (◯1 ◯5 ◯3 |
| 4 | Output signal, channel 0 | Output signal, channel 1* | Output signal, channel 2 | Output signal, channel 3* | 04 |
| 5 | PE | • | | | |

Table 7-25 Pinout of the sockets for 4-channel digital outputs

* Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

The basic circuit diagram of the expansion module is shown below.





Covering up unused connections

| Dimensions ar | nd weight | Status, alarms, diagnostics | | |
|--|----------------|--|------------------------------|--|
| Dimensions W \times H \times D (mm) | 87 × 110 × 55 | Status display | Green LED per channel | |
| Weight | Approx. 250 g | Alarms | None | |
| Module-specific data | | Actuator selec | tion data | |
| Number of outputs | 4 | Output voltage | | |
| Cable length | | With signal "1" Output current | Min. of 2L+ (-0.8 V) | |
| Unshielded | Max. 30 m | With signal "1" | | |
| Voltages, currents | s, potentials | Rated value | 0.5 A | |
| Aggregate current of out- | | Permissible range | 5 mA to 0.6 A | |
| • All installation positions | Max. 2 A | • With signal "0" (residual current) | Max. 0.1 mA | |
| To 55 °C | | Load resistance range | 48 Ω to 4 k Ω | |
| Electrical isolation | | Lamp load | Max. 5 W | |
| Between backplane bus and all other circuit components | Yes | Parallel connection of two outputs | | |
| Between channels | No | For redundant control of load | Possible (outputs in same | |
| Permissible potential diffe- | | | group only) | |
| Between different circuits | 75 VDC, 60 VAC | For performance improvement | Not possible | |
| Insulation tested with | | Driving a digital input | Possible | |
| Power input | | Switching frequency | | |
| From backplane bus | Max 28.5 mA | Resistive load | Max. 100 Hz | |
| (1L+) | Max. 20.0 m/ | Inductive load to IEC 947-5-1, DC13 | Max. 0.5 Hz | |
| From load voltage 2L+ (without load) | Max. 6 mA | Lamp load | Max. 1 Hz | |
| (without load) Power loss of module Typ. 1.2 W | | Limitation (internal) of vol- tage induced on circuit in- terruption | Typ. 2L+ (– 47 V) | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 1 А | |

7.13 EM 142 DO 4 \times DC 24V/2A expansion module (6ES7 142-1BD40-0XA0)

Features

The EM 142 DO 4 \times DC 24V/2A expansion module; order number 6ES7 142-1BD40-0XA0 has the following features:

- 4 digital outputs
- Output current 2 A per output
- Rated load voltage 24 VDC
- Suitable for solenoids, DC contactors and indicator lights

Pinout of the sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. You can find the layout of the sockets in Appendix C The connector wiring is described in Section 4.4.3.

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front) |
|-----|-----------------------------------|---------------------------|----------------------------|----------------------------|------------------------------------|
| 1 | - | | | | |
| 2 | Output signal, channel 1* | ∅ 2 | | | |
| 3 | Chassis ground, load power supply | | | | (◯1 ◯5 ◯3 |
| 4 | Output signal, channel 0 | Output signal, channel 1* | Output signal, channel 2 | Output signal, channel 3* | 04 |
| 5 | PE | | • | | |

Table 7-26 Pinout of the sockets for 4-channel digital outputs

* Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

The basic circuit diagram of the expansion module is shown below.



Figure 7-13 Basic circuit diagram of expansion module EM 142 DO 4 x DC 24V/2A

Covering up unused connections

| Dimensions and weight | | Status, alarms, diagnostics | | |
|---|----------------|--|---------------------------------|--|
| | | Status display | Green LED per channel | |
| Weight | Approx. 250 g | Alarms | None | |
| Module-spec | ific data | Actuator selec | tion data | |
| Number of outputs 4 | | Output voltage | | |
| Cable length | | • With signal "1" | Min. of 2L+ (-0.8 V) | |
| Unshielded | Max. 30 m | Output current | | |
| Voltages, current | s, potentials | With signal Rated value | 2 4 | |
| Aggregate current of out- | | Permissible range | 5 mA to 2.4 A | |
| PutsAll installation positions | | • With signal "0" (residual current) | Max. 0.5 mA | |
| To 20 °C | Max. 6 A | Load resistance range | 12 Ω to 4 k Ω | |
| To 55 °C | Max. 4 A | Lamp load | Max 10 W | |
| Electrical isolation | | Parallel connection of two | | |
| Between backplane bus and all other circuit | Yes | outputs | Possible | |
| Between channels | No | load | (outputs in same aroup only) | |
| Permissible potential diffe- rence | | For performance improvement | Not possible | |
| Between different circuits | 75 VDC, 60 VAC | Driving a digital input | Possible | |
| Insulation tested with | 500 VDC | Switching frequency | | |
| Power input | | Resistive load | Max. 100 Hz | |
| From backplane bus (11 +) | Max. 28.5 mA | Inductive load to IEC 947-5-1, DC13 | Max. 0.5 Hz | |
| From load voltage 2I + | Max 12 mA | Lamp load | Max. 1 Hz | |
| (without load) | | Limitation (internal) of vol- tage induced on circuit in- | Typ. 2L+ (– 47 V) | |
| Power loss of module | Typ. 2.1 W | terruption | | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 3 А | |

7.14 EM 142 DO 4 x DC 24V/2A expansion module (6ES7 142-1BD40-0XB0)

Hardware

The expansion module can be used together with the following basic modules:

- BM 141 DI 8×DC 24V, 6ES7 141-1BF01-0XB0, from product version 05 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01
- BM 141 DI 8 × DC 24V ECOFAST,

6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01

- BM 141 DI 8 × DC 24V ECOFAST DIAG, 6ES7 141-1BF40-0AB0, from product version 01
- BM 142 DO 4 × DC 24V/2A, 6ES7 142-1BD11-0XB0, from product version 05 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01
- BM 143-DESINA FO, 6ES7 143-1BF00-0XB0, from product version 01
- BM 143-DESINA RS485, 6ES7 143-1BF00-0AB0, from product version 01
- BM 147/CPU, 6ES7 147-1AA00-0XB0, from product version 01

Features

The EM 142 DO 4 x DC 24V/2A expansion module, order number 6ES7 142-1BD40-0XB0, has the following features:

- 4 digital outputs
- Output current 2 A per output
- Rated load voltage 24 VDC
- · Suitable for solenoids, DC contactors and indicator lights
- Parameterizable diagnostic interrupt
- Parameterizable diagnostics
- Parameterizable substitute value output
- SF LED

Pinout of the sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. You can find the layout of the sockets in Appendix C. The connector wiring is described in Section 4.4.4.

| Table 7-27 Pinout of the sockets for 4-channel digital output | Table 7-27 | for 4-channel digital outputs |
|---|------------|-------------------------------|
|---|------------|-------------------------------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front) |
|-----|-----------------------------------|----------------------------|----------------------------|----------------------------|------------------------------------|
| 1 | - | | | | |
| 2 | Output signal, channel 1* | ∞ ●2 | | | |
| 3 | Chassis ground, load power supply | | | | (◯1 ◯5 ◯3) |
| 4 | Output signal, channel 0 | Output signal, channel 1* | Output signal, channel 2 | Output signal, channel 3* | 04 |
| 5 | PE | | • | | |

Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

Basic circuit diagram

The basic circuit diagram of the expansion module is shown below.



Figure 7-14 Basic circuit diagram of expansion module EM 142 DO 4 x DC 24V/2A

Covering up unused connections

Parameters

*

The following table summarizes the parameters that you can set for the expansion module.

In Section 5.4 you will find the parameterizable diagnostics and in Section 5.5 you will find an in-depth description of diagnostic and hardware interrupt handling. You can find the layout of the parameter assignment frame and the assignment of the bits including the parameters of the digital outputs in the *configuration and parameter assignment frame for the ET 200X* at http://www.ad.siemens.de/simatic-cs.

| Table 7-28 | Parameters | of the EM | 142 DO 4 | x DC 24V/2A |
|------------|------------|-----------|----------|-------------|
| | | | | |

| Parameters | Range | Default | Area affected |
|---------------------------|---|-----------------------|------------------|
| Enable | | | Expansion module |
| Diagnostic interrupt | Yes/no | No | |
| Diagnosis | | | Channel |
| Wire break | Yes/no | No | |
| Short-circuit to M | Yes/no | No | |
| Short-circuit to L+ | Yes/no | No | |
| Behavior upon CPU STOP | Set substitute value/ maintain last value/no current or voltage | No current or voltage | Channel |
| Substitute value* | 0/1 | 0 | Channel |

Substitute values are current or voltage values that are output upon STOP of the master CPU by the expansion module to the process.

Effect of the supply voltage and the operating mode

The output values of the module are dependent on the supply voltage for the electronics/sensors and on the operating status of the PLC (CPU of the DP master).

Table 7-29
 Dependencies of digital output values on the operating status of the PLC (CPU of DP master) and L + supply voltage

| Operatin of the P of the DI | ng mode LC (CPU P master) | Supply voltage L + to ET 200X | Output value of expansion module | |
|-----------------------------------|---------------------------------|----------------------------------|---|--|
| Power | RUN | L + applied | PLC value | |
| on | | L + not applied | 0 V | |
| Power | STOP | L + applied | Substitute value/last value (default:0 V) | |
| on | | L + not applied | 0 V | |
| Power off | - | L + applied | After current operation: substitute value/last value (default: 0 V) Upon commissioning the DP slave: 0 V | |
| | | L + not applied | 0 V | |

Supply voltage on/off

A failure of the supply voltage to the electronics/sensors on the ET 200X is always displayed by the "ON" LED on the basic module and also entered in the diagnostic data area of the basic module.

| Dimensions and weight | | Status, alarms, diagnostics | | |
|---|----------------|--|--|--|
| $\begin{array}{l} \mbox{Dimensions} & 87 \times 110 \times 55 \\ \mbox{W} \times \mbox{H} \times \mbox{D (mm)} \end{array}$ | | Status display | Green LED per channel | |
| Weight Approx. 250 g | | Alarms | Diagnostic interrupt | |
| Module-spec | ific data | Diagnostic functions | Configurable | |
| Number of outputs 4 | | Group error | Red LED (SF) | |
| Cable length | | Actuator selection data | | |
| Unshielded Max. 30 m | | Output voltage | | |
| Voltages, current | s, potentials | With signal "1" Output current | Min. of 2L+ (-0.8 V) | |
| Aggregate current of out- | | With signal "1" | | |
| puts | | Rated value | 2 A | |
| All installation positions To 20 °C | Max 6 A | Permissible range | 6 mA to 2.4 A | |
| To 55 °C | Max. 4 A | With signal "0" (residual current) | Max. 0.5 mA | |
| Electrical isolation | | Load resistance range | 12 Ω to 4 k Ω | |
| Between backplane bus and all other circuit | Yes | Lamp load | Max. 10 W | |
| componentsBetween channels | No | Parallel connection of two outputs | | |
| Permissible potential diffe- rence | | For redundant control of load | Possible (outputs in same | |
| Between different circuits | 75 VDC, 60 VAC | For performance improvement | Not possible | |
| Insulation tested with | 500 VDC | | | |
| Power input | | Driving a digital input | Possible at minimum current of 6 mA | |
| From backplane bus (1L+) | Max. 40 mA | Switching frequency | | |
| From load voltage 2L+ (with put log al) | Max. 60 mA | Resistive load Inductive load to | Max. 100 Hz Max. 0.5 Hz | |
| (without load) | | IEC 947-5-1, DC13 | Max. 0.5 112 | |
| Power loss of module | Typ. 2.5 W | Lamp load | Max. 1 Hz | |
| | | Limitation (internal) of vol- tage induced on circuit in- terruption | Typ. 2L+ (– 53 V) | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 3.5 А | |

7.15 EM 142 DO 8 x DC 24V/1.2A expansion module (6ES7 142-1BF30-0XA0)

Features

The expansion module EM 142 DO 8 x DC 24V/1.2A; order number 6ES7 142-1BF30-0XA0, has the following features:

- 8 digital outputs
- Output current 1.2 A per output
- Rated load voltage 24 VDC
- Suitable for solenoids, DC contactors and indicator lights

Pinout of the sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. You can find the layout of the sockets in Appendix C. The connector wiring is described in Section 4.4.4.

Front view Pin Assignment of Assignment of Assignment of Assignment of socket X1 socket X2 socket X3 socket X4 of socket (Front) 1 not assigned 2 not assigned 2 3 Chassis ground, load power supply ○1 ○5 ○3 4 Output signal, Output signal, Output signal, Output signal, ∕04 channel 0 channel 1 channel 2 channel 3 PF 5 Pin Assignment of Assignment of Assignment of Assignment of socket X5 socket X6 socket X7 socket X8 1 not assigned 2 not assigned 3 Chassis ground, load power supply 4 Output signal, Output signal, Output signal, Output signal, channel 7 channel 4 channel 5 channel 6 5 ΡE

 Table 7-30
 Pin assignment of sockets for 8-channel digital outputs

The following Figure shows the basic circuit diagram for the expansion module.



Figure 7-15 Basic circuit diagram for expansion module EM 142 DO 8 x DC 24V/1.2A

Covering up unused connections

| Dimensions and weight | | Status, alarms, diagnostics | | |
|---|----------------------|--|------------------------------|--|
| Dimensions W \times H \times D (mm) | 87 × 180 × 55 | Status display | Green LED per channel | |
| Weight | Approx. 350 g | Alarms | None | |
| Module-spec | ific data | Actuator selec | tion data | |
| Number of outputs 8 | | Output voltage | | |
| Cable length | | With signal "1" Output current | min. 2L+ (–1.2 V) | |
| Unshielded | Max. 30 m | With signal "1" | | |
| Voltages, current | s, potentials | Rated value | 1.2 A | |
| Aggregate current of out- | | Permissible range | 5 mA to 13 A | |
| PutsAll installation positions | | With signal "0" (residual current) | Max. 0.5 mA | |
| to 20 °C to 50 °C | max. 7 A max. 5 A | Load resistance range | 21 Ω to 4 k Ω | |
| Electrical isolation | | Lamp load | Max. 10 W | |
| Between backplane bus and all other circuit | Yes | Parallel connection of two outputs | | |
| componentsBetween channels | No | For redundant control of load | Possible (outputs in same | |
| Permissible potential diffe- rence | | For performance improvement | Not possible | |
| Between different circuits | 75 VDC, 60 VAC | Driving a digital input | Possible | |
| Insulation tested with | 500 VDC | Switching frequency | | |
| Power input | | Resistive load | Max. 100 Hz | |
| From backplane bus (1L+) | Max. 35 mA | Inductive load to IEC 947-5-1, DC13 | Max. 0.5 Hz | |
| From load voltage 2L+ | Max. 12 mA | Lamp load | Max. 1 Hz | |
| (without load) Power loss of module | Тур. 1.5 W | Limitation (internal) of vol- tage induced on circuit in- terruption | Typ. 2L+ (– 47 V) | |
| | | Short-circuit protection for output | Yes, electronic | |
| | | Response threshold | Тур. 1.8 А | |
7.16 EM 143-DESINA expansion module (6ES7 143-1BF30-0XB0)

Features

The EM 143-DESINA expansion module (order number 6ES7 143-1BF30-0XB0) has the following features:

- 8 digital inputs or outputs (individually parameterizable as input or output) plus 8 diagnostic inputs or inputs with NC functionality (individually parameterizable).
- Rated input voltage of 24 VDC
- Digital inputs are suitable for switches and proximity switches (BERO switches)
- Digital outputs are suitable for solenoid valves, DC contactors and indicator lights

Pinout of the sockets for DI/DO

The tables below show the pinouts of the 8 sockets for connecting digital inputs and outputs. The connector wiring is described in Section 4.4.4. The arrangement of sockets X1 to X8 on the module in Appendix C.

| Pin | Assignment of socket X1 | Assignment of socket X3 | Assignment of socket X5 | Assignment of socket X7 | Front view of socket (Front view) |
|-----|---|---|---|---|---|
| 1 | Non-switched su | upply voltage DC | 24V-NS | | |
| 2 | Diagnostics input or input with NC functionality | <i>∞</i> 0 2 |
| 3 | Chassis ground, | power supply | | 1 | (◯1 ◯5 ◯3 |
| 4* | Digital input or output (DESINA) channel 0 | Digital input or output (DESINA) channel 2 | Digital input or output (DESINA) channel 4 | Digital input or output (DESINA) channel 6 | 04 |
| 5 | not assigned | | | | |

Table 7-31 Pinout of sockets X1, X3, X5 and X7 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-S switched supply voltage.

| Pin | Assignment of socket X2 | Assignment of socket X4 | Assignment of socket X6 | Assignment of socket X8 | Front view of socket (Front view) | | |
|-----|---|---|---|---|---|--|--|
| 1 | Non-switched su | upply voltage DC | 24V-NS | | | | |
| 2 | Diagnostics input or input with NC functionality | | | |
| 3 | Chassis ground | , power supply | | | | | |
| 4* | Digital input or output (DESINA) channel 1 | Digital input or output (DESINA) channel 3 | Digital input or output (DESINA) channel 5 | Digital input or output (DESINA) channel 7 | | | |
| 5 | not assigned | 1 | 1 | 1 | | | |

Table 7-32 Pinout of sockets X2, X4, X6 and X8 for digital inputs or outputs

* If it is parameterized as a digital output, pin 4 is fed by the DC 24V-NS non-switched supply voltage.

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Basic circuit diagram

The basic circuit diagram of the expansion module is shown below.



Figure 7-16 Basic circuit diagram of expansion module EM 143-DESINA

Parameters

The following table summarizes the parameters that you can set for the expansion module.

Table 7-33 Parameters of the EM 143-DESINA for digital inputs and outputs

| Parameters | Range | Default | Area affected |
|----------------------------------|---|---|---------------|
| Channel type for I/On (n= 07) | Digital input/ digital output | Digital output (Channel K0, K2, K4, K6) | Channel |
| | | Cligital input (Channel K1, K3, K5, K7) | |
| Functional input In | Diagnostic input/ | Diagnostic input | Channel |
| (n=815) | diagnostic input with diagnostic frame/ | | |
| | Input with NC function | | |
| Response to CPU/master STOP | Output No current or voltage hold last value/ | Output No current or voltage | Channel |
| | | - | |
| Substitute value On (n=07) | 0/1 | 0 | Channel |
| Diagnostic interrupt | Yes/no | No | Module |

| | 1 | | | |
|--|--|---|-------------------------------|--|
| Dimensions and weight | | Status, alarms, diagnostics | | |
| Dimensions W \times H \times D (mm) | 87 × 180 × 55 | Status display | Yellow LED per channel | |
| Weight Medule cross | Approx. 350 g | Indicator for functional input | Yellow/red LED per channel | |
| Module-spec | | Alarms | Diagnostic interrupt | |
| Number of channels | 8 digital inputs and outputs | Diagnostic functions | Configurable | |
| | 8 functional inputs (diagnostics | Reading diagnostic information | Possible | |
| | inputs or inputs with NC functionality) | Sensor supply | v outputs | |
| Cable length Unshielded | Max. 30 m | Outputs Output current | 8 Up to 40 °C max_1 A: | |
| Voltages, current | s, potentials | | Up to 55 °C | |
| Maximum number of inpute | o, potorniaio | Oh ant ainsuit masteration | max. 0.8 A | |
| driven simultaneously | | Short-circuit protection | Yes, electronic | |
| All installed positions | 8 | Sensor select | ion data | |
| max. 55 °C | - | Input voltage for paramete- rized DI (pin 4) | | |
| Aggregate current of out- | | Rated value | 24 VDC | |
| All installation positions | | With signal "1" | 13 to 30 V | |
| To 20 °C | Max 10 A | With signal "0" | –30 to 5V | |
| To 50 °C | Max. 6 A | Input voltage for functional | | |
| Electrical isolation | | Rated value | 24 VDC | |
| Between channels and | No | With signal "1" | 13 to 30 V | |
| backplane bus | | With signal "0" | –30 to 2 V | |
| Between channels | No | Input current | | |
| Between load voltages | No | With signal "1" | Typ. 5 mA | |
| Between load voltage and all other circuitry | No | Input delay | | |
| Permissible potential diffe- | | • From "0" to "1" | 1.2 to 4.8 ms | |
| rence | | • From "1" to "0" | 1.2 to 4.8 ms | |
| Between different circuits | 75 VDC, 60 VAC | Input characteristic | To IEC 61131, Type 2 | |
| Insulation tested with | 500 VDC | Connection of two-wire | Possible | |
| Power loss of module | Typ. 1.5 W | DERUS | | |
| L | | Permissible closed-circuit current | Max. 1.5 mA | |

| Actuator selec | tion data | Driving a digital input | Possible |
|--|------------------------|--|-------------------------|
| Output voltage | | Switching frequency | |
| With signal "1" Output current | Min. NS/S (– 0.8 V) | Resistive load Inductive load to | Max. 100 Hz Max_2 Hz |
| • With signal "1" | | IEC 947-5-1, DC13 | |
| Nominal value Permissible range | 1.2 A 7 mA to 1.3 A | Lamp load | Max. 1 Hz |
| With signal "0" (residual current) | Max. 0.5 mA | Limitation (internal) of vol- tage induced on circuit in- terruption | Typ. NS/S (– 47 V) |
| Load resistance range | 21 ohms to 4 kohms | Output short-circuit protec- | Yes electronic |
| Lamp load | Max. 10 W | tion | |
| Parallel connection of two outputs | No | Response threshold | Тур. 1.8 А |

7.17 EM 148-P DI 4 × DC 24V/DO 2 × P expansion module (pneumatic module) (6ES7 148-1DA00-0XA0)

Features

The EM 148-P DI 4 x DC 24V/DO 2 x P expansion module, order number 6ES7 148-1DA00-0XA0, has the following features:

- 4 digital inputs
- Rated input voltage of 24 VDC
- Suitable for switches and proximity switches (BEROs)
- 2 digital outputs with 2 integrated 4/2-way valves
- Permissible pressure range of 3 to 8 bars

Pinout of the sockets for DI

The following table shows the pinout of the two sockets used to connect the digital inputs. The connector wiring is described in Section 4.4.4. You can find the layout of the sockets in Appendix C.

Table 7-34 Pinout of the sockets for 2-channel digital inputs (pneumatic module)

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket |
|-----|------------------------------|-------------------------|-------------------------|
| 1 | Sensor supply output 1L+ | | |
| 2 | Input signal, channel 1 | Input signal, channel 3 | ⊘ ①2 |
| 3 | Chassis ground, power supply | (◯1 ◯5 ◯3 | |
| 4 | Input signal, channel 0 | Input signal, channel 2 | 04 |
| 5 | PE | | |

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65) is achieved.

Switch-on sequence

The 4/2-way valve is not of the contention-free type.

Consequently, it is important to switch on the compressed air supply first, and then switch on the voltage.

Basic circuit diagram



The basic circuit diagram of the expansion module is shown below.

Figure 7-17 Basic circuit diagram for EM 148-P DI 4 x DC 24V/DO 2 x P expansion module

Pneumatic connection diagram

The pneumatic connection diagram of a 4/2-way valve is shown below.



Figure 7-18 Pneumatic connection diagram of a 4/2-way valve

| Dimensions and weight | | Sensor supply outputs | | |
|---|--------------------------|--|---|--|
| Dimensions W \times H \times D (mm) | 87 × 173 × 88 | Outputs Output current* | 2 Up to 40 °C | |
| Weight | Approx. 500 g | | max. 0.9A; Up to 55 °C | |
| Module-spec | ific data | Oh ant airea it such a tion | max. 0.7A | |
| Number of inputs | 4 (electrical) | Short-circuit protection Yes, electronic | | |
| Number of outputs | 4 (pneumatic) | Sensor select | ion data | |
| Length of cable (inputs) | | Input voltage Rated value | | |
| Unshielded | Max. 30 m | With signal "1" | 13 to 30 V | |
| Voltages, currents | s, potentials | With signal "0" | – 3 to 5 V | |
| Maximum number of inputs driven simultaneously | | Input current With signal "1" | Typ. 7 mA | |
| All installation positions To 55 °C | 4 | Input delay | | |
| Permissible potential diffe- rence | | From "0" to "1"From "1" to "0" | 1.2 to 4.8 ms 1.2 to 4.8 ms | |
| Between different circuits | 75 VDC, 60 VAC | Input characteristic | To IEC 61131, Type 2 | |
| Insulation tested with | 500 VDC | Connection of two-wire BE- | Possible | |
| Power input From backplane bus (11 +) | Max. 40 mA | Permissible closed-circuit current | Max. 1.5 mA | |
| From 2L+ load voltage | Max. 130 mA | Valve outlets | | |
| (incl. valves) | | Medium | Compressed air (for | |
| Power loss of module | Тур. 3 W | | properties refer to paragraph below) | |
| Status, alarms, c | liagnostics | Pressure range | 3 to 8 bars | |
| Status display | Green LED per channel | Rated flow | 300 l/min | |
| | Green LED per valve | Valve switching timesOn, change | 20 ms | |
| Alarms | None | • Off | 20 ms | |
| | | Current input per valve | 50 mA | |

* Please note the total current per ET 200X.

Compressed air for valve outlets

You should operate the valves with filtered (40 μm), dried and oil-free compressed air of Class 5 4 3 in accordance with ISO 8573-1.

Operation with filtered, dried and oiled compressed air of Class 5 4 5 is similarly possible. For this purpose, use an oil that is included on FESTO's list of proposed oils:

| Table 7-35 | Suitable types of oil for compressed air | |
|------------|--|--|
|------------|--|--|

| Suitable oils | Features |
|---------------------------|---|
| FESTO OFSW-32 Special Oil | DIN 51 524, Part 2 hydraulic oil, viscosity |
| ARAL Vitam GF 32 | 32 mm ² /s at 40 °C (HLP 32) |
| Esso Nuto H 32 | |
| Mobil DTE 24 | |
| BP Energol HLP-HM 32 | |

Example of retrieving the 2 limits of travel of a pneumatic cylinder

In the table below you will find an excerpt from a *STEP 7* user program for retrieving the two limits of travel of a pneumatic cylinder.

Assumptions

The following assumptions apply to this STEP 7 user program:

- In the example the pneumatic module is inserted directly adjacent to the basic module. Its address is therefore 0.
- The pneumatic cylinder is controlled by means of a valve on the pneumatic module.
- The inputs I 0.0 "cylinder down" and I 0.1 "cylinder up" are used for the pneumatic cylinder limits of travel.
- The pneumatic cylinder is controlled by means of output O 0.0.

STEP 7 user program

| STL | | Description |
|-----|-------|--|
| υ | I 0.0 | When cylinder at limit of travel "down" |
| U | м 0.0 | and instruction "cylinder up" queued |
| S | 0 0.0 | the output is set, i.e. cylinder moves upwards |
| υ | I 0.1 | When cylinder at limit of travel "up" |
| υ | M 0.1 | and instruction "cylinder down" queued |
| R | 0 0.0 | the output is reset, i.e. cylinder moves downwards |
| 1 | | |

7.18 EM 148-P DO 16 × P/CPV10 expansion module (pneumatic interface module for CPV10) (6ES7 148-1EH00-0XA0)

Installation next to motor starter (EM 300...)

You can install the expansion module immediately next to a motor starter, product version ≥ 02 .

Features

The EM 148-P DO 16 x P/CPV10 expansion module, order number 6ES7 148-1EH00-0XA0, has the following features:

- 16 digital outputs
- Rated load voltage 24 VDC
- Suitable for connecting a FESTO CPV10 valve island with up to 16 valves

Basic circuit diagram

The basic circuit diagram of the expansion module is shown below.





Assigning addresses to the pneumatic interface module for the CPV10



The figure below shows the pneumatic interface module with FESTO CPV10 valve island and addresses.

Figure 7-20 Assigning addresses to the pneumatic interface module

| Dimensions and weight | | Status, alarms, diagnostics | | |
|---|---------------------------|--|--------------------------------------|--|
| Dimensions W \times H \times D (mm) | 147 × 152 × 55 | Status display | Green LED per digi- tal output | |
| Weight | Approx. 450 g | Alarms | None | |
| Module-spec | ific data | Valve island for connect | ction meets following | |
| Number of outputs | 16 | Conditi | ions^ | |
| Voltages, current | s, potentials | Medium | Compressed air filtered (40 um) | |
| Electrical isolation | | | Oiled (oil: VG 32) Unoiled/vacuum | |
| Between extension interface and channels | Yes, optocouplers | Pressure range | 3 to 8 bars | |
| Between channels | No | Rated flow | 400 l/min | |
| In groups of Insulation tested with | 16 500 VDC | Valve switching timesOn, changeOff | 17 ms 25 ms | |
| From backplane bus (1L+) From 2L+ load voltage | Max. 35 mA Max. 320 mA | Current input per valve * Further details on valve islar | 20 mA | |
| (incl. CPV10 valves) Power loss of module (incl. valves) | Тур. 6 W | documentation on valve isla | ands. | |

7.19 EM 148-P DO 16 × P/CPV14 expansion module (pneumatic interface module for CPV14) (6ES7 148-1EH10-0XA0)

Installation next to motor starter (EM 300...)

You can install the expansion module immediately next to a motor starter, product version ≥ 02 .

Features

The EM 148-P DO 16 x P/CPV14 expansion module, order number 6ES7 148-1EH10-0XA0, has the following features:

- 16 digital outputs
- Rated load voltage 24 VDC
- Suitable for connecting a FESTO CPV14 valve island with up to 16 valves

Basic circuit diagram

The basic circuit diagram of the expansion module is shown below.



Figure 7-21 Basic circuit diagram for EM 148-P DO 16 x P/CPV14 expansion module

Address assignment for pneumatic interface module for CPV14



The figure below shows the pneumatic interface module with FESTO CPV 14 valve island and addresses.

Figure 7-22 Assigning addresses to the pneumatic interface module

| Dimensions and weight | | Status, alarms, diagnostics | | |
|--|-------------------|--|--------------------------------------|--|
| Dimensions W \times H \times D (mm) | 147 × 152 × 55 | Status display | Green LED per digi- tal output | |
| Weight | Approx. 450 g | Alarms | None | |
| Module-spec | ific data | Valve island for connect | ction meets following | |
| Number of outputs | 16 | Condit | ions^ | |
| Voltages, currents | s, potentials | Medium | Compressed air filtered (40 µm) | |
| Electrical isolation | | | Oiled (oil: VG 32) Unoiled/vacuum | |
| Between extension interface and channels | Yes, optocouplers | Pressure range | 3 to 8 bars | |
| Between channels | No | Rated flow | 800 I/min | |
| In groups of Insulation tested with | 16 500 VDC | Valve switching timesOn, changeOff | 24 msec 30 msec | |
| From backplane bus (1L+) From 2L + load valtage | Max. 45 mA | Current input per valve * Further details on valve islar | 32 mA | |
| (incl. CPV14 valves) | wax. 520 mA | documentation on valve isla | ands. | |
| Power loss of module (incl. valves) | Тур. 9 W | | | |

7.20 PM 148 DO 4 × DC 24V/2A power module (6ES7 148-1CA00-0XB0)

Hardware

The power module can be used together with the following basic modules:

| • | BM 141 DI 8×DC 24V, | 6ES7 141-1BF01-0XB0, from product version 05 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01 |
|---|---------------------------|--|
| • | BM 141 DI 8 × DC 24V ECOF | AST, 6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01 |
| • | BM 141 DI 8×DC 24V ECO | FAST DIAG, 6ES7 141-1BF40-0AB0, from product version 01 |
| • | BM 142 DO 4×DC 24V/2A, | 6ES7 142-1BD11-0XB0, from product version 05 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01 |
| • | BM 143-DESINA FO, | 6ES7 143-1BF00-0XB0, version 01 or later |
| • | BM 143-DESINA RS485, | 6ES7 143-1BF00-0AB0, version 01 or later |
| • | BM 147/CPU, | 6ES7 147-1AA00-0XB0, version 01 or later |

Features

The PM 148 DO 4 x DC 24V/2A power module, order number 6ES7 148-1CA00-0XB0, has the following features:

- Connection for load voltage supply
- 4 digital outputs
- Output current 2 A per output
- Rated load voltage 24 VDC
- Suitable for solenoids, DC contactors and indicator lights
- Parameterizable diagnostic interrupt
- Parameterizable diagnostics
- Parameterizable substitute value output
- Indicator for system fault (SF LED)
- Indicator for load voltage (DC 24V LED)

Pinout of sockets for DO

The following table shows the pinout of the four sockets used to connect the digital outputs. You can find the layout of the sockets in Appendix C. The connector wiring is described in Section 4.4.4.

| Table 7-36 | Pin assignmen | t of sockets for | · 4-channel | digital | outputs |
|------------|---------------|------------------|-------------|---------|---------|
|------------|---------------|------------------|-------------|---------|---------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Assignment of socket X3 | Assignment of socket X4 | Front view of socket (Front) |
|-----|----------------------------|----------------------------|----------------------------|----------------------------|------------------------------------|
| 1 | - | | | | |
| 2 | Output signal, channel 1* | _ | Output signal, channel 3* | _ | Ø 0 2 |
| 3 | Chassis ground, | | (◯1 ◯5 ◯3 | | |
| 4 | Output signal, channel 0 | Output signal, channel 1* | Output signal, channel 2 | Output signal, channel 3* | 04 |
| 5 | PE | | | | |

Note: Channel 1 and channel 3 are only allowed to be used at one socket (X1/X2 or X3/X4).

Basic circuit diagram

The basic circuit diagram of the power module is shown below.



Figure 7-23 Basic circuit diagram of power module PM 148 DO 4 x DC 24V/2A (6ES7 148-1CA00-0XB0)

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

Parameters

The following table summarizes the parameters that you can set for the power module.

In Section 5.4 you will find the parameterizable diagnostics and in Section 5.5 you will find an in-depth description of diagnostic and hardware interrupt handling. You can find the layout of the parameter assignment frame and the assignment of the bits including the parameters of the digital outputs in the *configuration and parameter assignment frame for the ET 200X* at http://www.ad.siemens.de/simatic-cs.

Parameters Default Area affected Range Enable Expansion module Diagnostic interrupt Yes/no No Diagnosis Channel Wire break Yes/no No ٠ Short-circuit to M Yes/no No . • Short-circuit to L+ Yes/no No Behavior upon CPU Set substitute value/ No current or voltage Channel STOP maintain last value/no current or voltage 0 Substitute value* 0/1 Channel

Table 7-37 Parameters of the PM 148 DO 4 x DC 24V/2A

Substitute values are current or voltage values that are output upon STOP of the master CPU by the expansion module to the process.

Effect of the supply voltage and the operating mode

The output values of the module are dependent on the supply voltage for the electronics/sensors and on the operating status of the PLC (CPU of the DP master).

Table 7-38
 Dependencies of digital output values on the operating status of the PLC (CPU of DP master) and L + supply voltage

| Operating mode of the PLC (CPU of the DP master) | | Supply voltage L + to ET 200X | Output value of power module |
|--|------------------|----------------------------------|---|
| Power RUN | | L + applied | PLC value |
| on | | L + not applied | 0 V |
| Power | Power STOP on | L + applied | Substitute value/last value (default:0 V) |
| on | | L + not applied | 0 V |
| Power off | _ | L + applied | After current operation: substitute value/last value (default: 0 V) Upon commissioning the DP slave: 0 V |
| | | L + not applied | 0 V |

Supply voltage On/Off

A failure of the supply voltage to the electronics/sensors on the ET 200X is always displayed by the "ON" LED on the basic module and also entered in the diagnostic data area of the basic module.

| Dimensions and weight | | | Status, alarms, diagnostics | | |
|--|--|-------------------------------------|--|-----------------------------|--|
| Dimensions W \times H \times D (mm) | | 87 × 165 × 67 | Status display | Green LED per channel | |
| We | eight | Approx. 250 g | Alarms | Diagnostic interrupt | |
| | Module-speci | fic data | Diagnostic functions | Configurable | |
| Νι | mber of outputs | 4 | Group error | Red LED (SF) | |
| Ca | ble length | | Load voltage monitor | Green LED | |
| • | Unshielded | Max. 30 m | Actuator salas | (DC 24V) | |
| | Voltages, currents | s, potentials | Actuator Selec | | |
| Ra | ted load voltage 2L + | 24 VDC | • With signal "1" | Min of $2I \pm (-0.8 \)$ | |
| Ma fro | ax. perm. power input m load | Up to 40 °C 10 A Up to 55 °C 8 A | With signal "1" With signal "1" | WIIT. 01 2L+ (-0.0 V) | |
| Ao | areaate current of out- | - | Rated value | 2 A | |
| pu | ts | | Permissible range | 6 mA to 2.4 A | |
| • | All installation positions | | • With signal "0" (residual | Max. 0.5 mA | |
| | Up to 20 °C | Max. 6 A | current) | | |
| | Up to 55 °C | Max. 4 A | Load resistance range | 12 Ω to 4 k Ω | |
| Ele | ectrical isolation | | Lamp load | Max. 10 W | |
| • | Between backplane bus and all other circuit components | Yes | Parallel connection of two outputs | | |
| • | Between channels | No | For redundant control of | Possible | |
| • | Between load power | Yes | loau | group only) | |
| | supply and all other circuit components | | For performance improvement | Not possible | |
| Pe rer | rmissible potential diffe- nce | | Driving a digital input | Possible at minimum | |
| • | Between different circuits | 75 VDC, 60 VAC | Switching frequency | current of o mA | |
| Ins | sulation tested with | 500 VDC | Resistive load | Max. 100 Hz | |
| Po | wer input | | Inductive load to IEC 947-5-1, DC13 | Max. 0.5 Hz | |
| • | From backplane bus (1L+) | Max. 40 mA | Lamp load | Max. 1 Hz | |
| • | From load voltage 2L+ (without load) | Max. 60 mA | Limitation (internal) of vol- tage induced on circuit in- terruption | Typ. 2L+ (– 53 V) | |
| Po | wer loss of module | Тур. 2.5 W | Short-circuit protection for | Yes, electronic | |
| | | | Response threshold | Тур. 3.5 А | |

7.21 Expansion modules with analog inputs and outputs

Hardware

The expansion module can be used together with the following basic modules:

| • | BM 141 DI 8×DC 24V, | 6ES7 141-1BF01-0XB0, from product version 05 6ES7 141-1BF11-0XB0, from product version 01 6ES7 141-1BF12-0XB0, from product version 01 |
|---|---------------------------|--|
| • | BM 141 DI 8 × DC 24V ECOF | AST, 6ES7 141-1BF00-0AB0, from product version 01 6ES7 141-1BF01-0AB0, from product version 01 |
| • | BM 141 DI 8×DC 24V ECO | FAST DIAG, 6ES7 141-1BF40-0AB0, from product version 01 |
| • | BM 142 DO 4×DC 24V/2A, | 6ES7 142-1BD11-0XB0, from product version 05 6ES7 142-1BD21-0XB0, from product version 01 6ES7 142-1BD22-0XB0, from product version 01 |
| • | BM 143-DESINA FO, | 6ES7 143-1BF00-0XB0, version 01 or later |
| • | BM 143-DESINA RS485, | 6ES7 143-1BF00-0AB0, from product version 01 |
| • | BM 147/CPU, | 6ES7 147-1AA00-0XB0, from product version 01 |

EM with analog inputs

By means of expansion modules with analog inputs, continuously changing signals, such as those that occur when measuring temperature or pressure, can be recorded, evaluated and converted to digital values for further processing.

Features of the analog inputs

The expansion modules with analog inputs have the following features:

- Different measuring ranges:
 - $-\pm10~V$
 - ± 20 mA, 4 to 20 mA (four-wire measuring transducer, parameterizable)
 - 4 to 20-wire measuring transducer)
 - Pt100 resistance thermometer (two-, three- or four-conductor connection possible)
- SIMATIC S7 and SIMATIC S5 data format (parameterizable)
- Resolution of 12 bits plus sign
- 2 channels (same measuring range and data format for both channels of an expansion module)
- 24 VDC supply voltage for expansion module and sensor via backplane bus
- Analog inputs not isolated from the internal electronic components
- Integration time 16.7 ms/20 ms (parameterizable)

EM with analog outputs

The expansion modules with analog outputs allow digital values inputted by means of a controller to be converted in an expansion module to corresponding analog signals (current or voltage) that control actuators (setpoint input for speed controllers, temperature controllers, etc.).

Features of the analog outputs

The expansion modules with analog outputs have the following features:

- Different measuring ranges:
 - $-\pm10~V$
 - \pm 20 mA, 4 to 20 mA (parameterizable)
- SIMATIC S7 and SIMATIC S5 data format (parameterizable)
- Resolution of 11 bits plus sign
- 2 channels (same measuring range and data format for both channels of an expansion module)
- 24 VDC supply voltage
- Analog outputs not isolated from the internal electronic components

Measuring ranges in SIMATIC S7 and S5 format

The following table compares the measuring ranges (rated ranges) in SIMATIC S7 and SIMATIC S5 format:

| Table 7-39 | Representation o | f measuring i | ranges for | analog inputs |
|------------|------------------|---------------|------------|---------------|
|------------|------------------|---------------|------------|---------------|

| Measuring range | Representation of the rated ranges in SIMATIC S7 format | Representation of the rated ranges in SIMATIC S5 format | |
|-----------------|---|---|--|
| ±10 V | -27648 to +27648 | -2048 to +2048 | |
| \pm 20 mA | | | |
| 4 to 20 mA | 0 to +27648 | 512 to +2560 | |
| PT100 Standard | 0.1 °C/digit | 0.5 °C/digit | |
| -100 to +850 °C | | -200 to +1700 | |
| –200 to +850 °C | -2000 to +8500 | | |

 Table 7-40
 Representation of measuring ranges for analog outputs

| Output range | Representation of the rated ranges in SIMATIC S7 format | Representation of the rated ranges in SIMATIC S5 format |
|--------------|---|---|
| ± 10 V | -27648 to +27648 | -1024 to +1024 |
| ± 20 mA | | |
| 4 to 20 mA | 0 to +27648 | 0 to +1024 |

7.21.1 Parameters of the analog inputs and outputs

Parameter assignment

You set the parameters of the analog inputs/outputs using either the *STEP* 7 or *COM PROFIBUS* parameter assignment software.

Parameters

The tables below give an overview of the of the parameters that you can set for the analog inputs and analog outputs.

You can find the layout of the parameter assignment frame and the assignment of the bits including the parameters of the analog inputs and outputs in the **configuration and parameter assignment frame of the ET 200X** at http://www.ad.siemens.de/simatic-cs. In Section 5.4 you will find the parameterizable diagnostics and in Section 5.5 you will find an in-depth description of diagnostic and hardware interrupt handling.

| Expansion modules with | Parameters | Range | Default | Area affected |
|--|---|---|----------------------|---|
| All | Format | SIMATIC S7 format/ SIMATIC S5 format | SIMATIC S7 format | Expansion Module |
| All | Enable | | | Expansion module |
| | Diagnostic interrupt | Yes/no | No | |
| | Hardware interrupt upon limit value violation | Yes/no | No | |
| All | Diagnosis | | | Channel |
| | Group diagnosis | Yes/no | No | |
| EM 144 AI 2 × I | Diagnosis | | | Channel |
| (6ES7 144-1GB31-0XB0 and 6ES7 144-1GB41-0XB0) | With wire break check | Yes/no | No | |
| EM 144 AI 2 × RID | | | | |
| (0E37 144-13B31-0AB0) | Macauring | $20 m \Lambda/4 to$ | 4 to 20 m 4 | Channel |
| (6ES7 144-1GB31-0XB0) | range | 20 mA/4 to 20 mA | 4 to 20 ma | Channel |
| EM 145 AO 2 × I (6ES7 145-1GB31-0XB0) | Measuring range | 20 mA/4 to 20 mA | 4 to 20 mA | Channel |
| All | Reset time ¹ | 16.7 ms/20 ms | 20 ms | Channel (module channels must be identically set) |

Table 7-41 Parameters of analog inputs

| Expansion modules with | Parameters | Range | Default | Area affected |
|------------------------|--|--|---------|---------------|
| All | Trigger for hardware interrupt • Upper limit value • Lower limit value | From 32511 to -32512 From -32512 to 32511 | - | Channel |

| Table 7-41 | Parameters of | analog inputs, | Fortsetzung |
|------------|---------------|----------------|-------------|
|------------|---------------|----------------|-------------|

¹ For optimum interference suppression of the analog modules as a function of the system frequency (at 50 Hz, 20 msec reset time; at 60 Hz, 16.7 msec reset time)

| Table 7-42 Parameters of analog |
|---------------------------------|
|---------------------------------|

| Expansion modules with AOs | Parameters | Range | Default | Area affected |
|----------------------------------|---|--|-----------------------|------------------|
| All | Format | SIMATIC S7 format/ SIMATIC S5 format | SIMATIC S7 format | Expansion module |
| All | Enable Diagnostic interrupt | Yes/no | No | Expansion module |
| All | Diagnosis Group diagnosis | Yes/no | No | Channel |
| All | Behavior upon CPU STOP | Set substitute value/ maintain last value/no current or voltage | No current or voltage | Channel |
| All | Substitute value* | 0/1 | 0 | Channel |

* Substitute values are current or voltage values that are output upon STOP of the master CPU by the module with analog outputs to the process.

7.21.2 Analog value representation for measuring ranges with SIMATIC S7

Analog value representation

The digitized analog value for input and output values in the same rated range is the same.

The analog values are represented in the form of a twos complement.

The following table shows the analog value representation of the expansion modules with analog inputs and outputs:

| Table 7-43 | Analog value representation | (SIMATIC S7 format) |
|------------|------------------------------|---------------------|
| | , malog value representation | |

| Resolution | Analog value | | | | | | | | | | | | | | | |
|--------------------------|--------------|-----------------|-----------------|-----------------|-----------------|-----------------|----------------|----------------|----|----------------|----------------|----|----------------|----------------|----------------|----------------|
| Bit number | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Significance of the bits | +/ _ | 2 ¹⁴ | 2 ¹³ | 2 ¹² | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 27 | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ |

Sign

The sign (+/-) of the analog value is always in bit number 15:

- "0" → +
- "1" → −

Measured-value resolution

In the table below you will find the representation of the binary analog values and the associated decimal and hexadecimal representation of the units of the analog values.

The analog inputs have a resolution of 12 bits + plus/minus sign, whereas the analog outputs have a resolution of 11 bits + plus/minus sign. Each analog value is entered in the accumulator with left justification. The bits marked "x" are set to "0".

Note: This resolution does not apply to temperature values. The converted temperature values are the result of a conversion in the expansion module (see Table 7-47).

Table 7-44 Measured-value resolution of the analog values (SIMATIC S7 format)

| Decelution in | Ur | nits | Analog value | | |
|----------------------|---------|------------------|--------------|-----------------|--|
| bits (plus +/-) | Decimal | Hexadeci- mal | High byte | Low byte | |
| 11 | 16 | 10 _H | +/-0000000 | 0001xxxx | |
| 12 | 8 | 8 _H | +/-0000000 | 0 0 0 0 1 x x x | |

7.21.3 Analog value representation for the measuring ranges of the analog inputs and outputs (SIMATIC S7 Format)

The tables in this chapter contain the digitized analog values for the measuring ranges of the expansion modules with analog inputs and outputs.

The binary representation of the analog values is always the same, so these tables only compare the measuring ranges and the units.

Input ranges \pm 10 V \pm 20 mA

The following table contains the representation of the digitized measured value for the:

- For the voltage measuring range \pm 10 V and
- For the current measuring range \pm 20 mA.

Table 7-45 SIMATIC S7 format: representation of the digitized measured value +/-10 V; +/-20 mA (expansion modules with analog inputs)

| Measuring Measuring | | Ur | nits | _ |
|---------------------|-------------------|---------|-------------------|-------------|
| range \pm 10 V | range \pm 20 mA | Decimal | Hexadecimal | Range |
| > 11.7589 | > 23.515 | 32767 | 7FFF _H | Overflow |
| 11.7589 | 23.515 | 32511 | 7EFF _H | |
| : | : | : | : | Overrange |
| 10.0004 | 20.0007 | 27649 | 6C01 _H | |
| 10.00 | 20.000 | 27648 | 6C00 _H | |
| 7.50 | 14.998 | 20736 | 5100 _H | |
| : | : | : | : | Rated range |
| - 7.50 | - 14.998 | -20736 | AF00 _H | |
| - 10.00 | - 20.000 | -27648 | 9400 _H | |
| - 10.0004 | - 20.0007 | -27649 | 93FF _H | |
| : | : | : | : | Underrange |
| - 11.759 | - 23.516 | -32512 | 8100 _H | |
| <- 11.759 | <- 23.516 | -32768 | 8000 _H | Underflow |

Input range 4 to 20 mA

The following table contains the representation of the digitized measured value for the:

• Current measuring range 4 to 20 mA

 Table 7-46
 SIMATIC S7 format: representation of the digitized measured value 4 to 20 mA (expansion module with analog inputs)

| Measuring range | Un | its | _ |
|-----------------|---------|-------------------|-------------|
| to 20 mA | Decimal | Hexadecimal | Range |
| >22.810 | 32767 | 7FFF _H | Overflow |
| 22.810 | 32511 | 7EFF _H | |
| : | : | : | Overrange |
| 20.0005 | 27649 | 6C01 _H | |
| 20.000 | 27648 | 6C00 _H | |
| 16.000 | 20736 | 5100 _H | Detedees |
| : | : | : | Rated range |
| 4.000 | 0 | 0 _H | |
| 3.9995 | -1 | FFFF _H | |
| : | : | : | Underrange |
| 1.1852 | -4864 | ED00 _H | |
| 1.1852 | -32768 | 8000 _H | Underflow |

Relationship between "Wire break" and measuring range

If the "wire break" parameter is deactivated in the configuration software and the measuring range ≤ 1.1 mA, then "8000_H" is output and bit 6 "measuring range underflow" is set in byte 21 of the station diagnosis.

If the "wire break" parameter is activated and the measuring range ≤ 3.6 mA, then "8000_H" is output and bit 4 "wire break" is set in byte 21 of the station diagnosis.

Standard temperature range, Pt 100

In the following table you will find the representation of the digitized measured value for the standard temperature range of the Pt 100 sensor. The characteristic linearization applies to the following temperature ranges: – 200 °C to + 850 °C (in increments of 0.1 °C).

| Table 7-47 | SIMATIC S7 format: representation of the digitized measured value for the |
|------------|---|
| | standard temperature range, Pt 100 (expansion module with analog inputs) |

| Measured va- lue in °C | Decimal | Hexadeci- mal | Range | |
|---------------------------|---------|-------------------|-------------|--|
| > 1000.0 | 32767 | 7FFF _H | Overflow | |
| 1000.0 | 10000 | 2710 _H | | |
| : | : | : | Overrange | |
| 850.1 | 8501 | 2135 _H | | |
| 850.0 | 8500 | 2134 _H | | |
| : | : | : | Rated range | |
| -200.0 | -2000 | F830 _H | | |
| -200.1 | -2001 | F82F _H | | |
| : | : | : | Underrange | |
| -243.0 | -2430 | F682 _H | | |
| <-243.0 | -32768 | 8000 _H | Underflow | |

Tables for output ranges

As of Table 7-48 you will find the analog output ranges of the expansion modules with analog outputs.

Output ranges $\pm\,10$ V $\pm\,20$ mA

The following table contains the representation of the output ranges for the:

- For the voltage output range \pm 10 V and
- For the current output range \pm 20 mA.

Table 7-48 SIMATIC S7 format: representation of the analog output range +/–10 V; +/–20 mA

| Output range Output range | | Un | its | - |
|---------------------------|----------|---------|--------------------|-------------|
| ± 10 V | ± 20 mA | Decimal | Hexadecimal | Range |
| 0 | 0 | >32511 | >7EFF _H | Overflow |
| 11.7589 | 23.515 | 32511 | 7EFF _H | |
| : | : | : | : | Overrange |
| 10.0004 | 20.0007 | 27649 | 6C01 _H | |
| 10.00 | 20.000 | 27648 | 6C00 _H | |
| 7.50 | 14.998 | 20736 | 5100 _H | |
| : | : | : | : | Rated range |
| - 7.50 | - 14.998 | -20736 | AF00 _H | |
| - 10.00 | - 20.000 | -27648 | 9400 _H | |
| - 10.0004 | -20.0007 | -27649 | 93FF _H | |
| : | : | : | : | Underrange |
| - 11.7589 | - 23.515 | -32512 | 8100 _H | |
| 0 | 0 | <-32512 | <8100 _H | Underflow |

Output range 4 to 20 mA

The following table contains the representation of the current output range 4 to 20 mA.

| Table 7-49 | SIMATIC S7 format: representation of the analog current output range 4 to |
|------------|---|
| | 20 mA |

| Output range | Un | iits | Range |
|--------------|---------|------------------------|-------------|
| 4 to 20 mA | Decimal | Hexadecimal | |
| 0 | >32511 | >7EFF _H | Overflow |
| 22.8142 | 32511 | 7EFF _H | |
| : | : | : | Overrange |
| 20.0005 | 27649 | 6C01 _H | |
| 20.000 | 27648 | 6C00 _H | |
| : | : | : | Rated range |
| 4.000 | 0 | 0 _H | |
| 3.9995 | -1 | FFFF _H | |
| : | : | : | Underrange |
| 0 | - 6912 | E500 _H | |
| 0 | <-6913 | <e4ff<sub>H</e4ff<sub> | Underflow |

7.21.4 Analog value representation for measuring ranges with SIMATIC S5

Analog value representation

The analog inputs have a resolution of 12 bits + plus/minus sign, whereas the analog outputs have a resolution of 11 bits + plus/minus sign. Each analog value is entered in the accumulator with left justification.

The analog values are represented in the form of a twos complement.

Analog inputs

The following table shows the analog value representation of the expansion modules with analog inputs:

Table 7-50 Analog value representation of the analog inputs (SIMATIC S5 format)

| Resolution | | | | | | | Ar | alog | valu | e | | | | | | |
|--------------------------|----|-----------------|-----------------|----------------|----------------|----|----------------|----------------|------|----------------|----------------|----------------|----|---|---|---|
| Bit number | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Significance of the bits | +/ | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 27 | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 20 | х | F | Ü |
| | - | | | | | | | | | | | | | | | |

Sign

The sign (+/-) of the analog value is always in bit number 15:

- "0" → +
- "1" → -

Irrelevant bits

Irrelevant bits are marked "x".

Diagnostic bits

Bit numbers 0 and 1 are reserved for diagnostic functions, whereas bit number 2 does not have a function.

- E = error bit (0 = no wire break; 1 = wire break)
- O = overflow bit

Analog outputs

The following table shows the analog value representation of the expansion modules with analog outputs:

Table 7-51 Analog value representation of the analog outputs (SIMATIC S5 format)

| Resolution | | | | | | | Α | nalog | y valu | le | | | | | | |
|--------------------------|----|-----------------|----------------|----------------|----------------|----------------|----------------|-------|----------------|----------------|----------------|----------------|---|---|---|---|
| Bit number | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Significance of the bits | +/ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | х | х | х | х |

7.21.5 Analog value representation for the measuring ranges of the analog inputs and outputs (SIMATIC S5 format)

The tables in this chapter contain the digitized analog values for the measuring ranges of the expansion modules with analog inputs and outputs.

Format calculation

The SIMATIC S5 format is calculated in the analog module from the SIMATIC S7 format. The overrange in the two formats is therefore the same size (approx. 17.6 %).

Input ranges \pm 10 V

The following table contains the representation of the digitized measured value for the:

• For the voltage measuring range \pm 10 V

Table 7-52 SIMATIC S5 format: representation of the digitized measured value +/-10 V (expansion module with analog inputs)

| Measuring | Units | its Data word | | | | | | | | | | | | | | | Range | |
|-----------------|--------|-----------------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|---|---|-------|-----------|
| range ± 10 V | (dec.) | 2 ¹² | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 2 ⁴ | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | F | Ü | |
| >11.7578 | 2409 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | Overflow |
| 11.7589 | 2408 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | Overrange |
| 10.005 | 2049 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | |
| 10.00 | 2048 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 5 | 1024 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 0.000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Rated |
| -5 | -1024 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | range |
| -10.00 | -2048 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| -10.005 | -2049 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | Under- |
| -11.7578 | -2408 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | range |
| <-11.7578 | -2409 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | Underflow |

Input range ± 20 mA

The following table contains the representation of the digitized measured value for the:

• For the current measuring range \pm 20 mA.

Table 7-53 SIMATIC S5 format: representation of the digitized measured value +/–20 mA (expansion module with analog inputs)

| Measuring | Units | Data word | | | | | | | | | | | | | | | Range | |
|------------------|--------|-----------------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|----|----------------|----------------|----------------|----------------|---|---|-------|-----------|
| range ± 20 mA | (dec.) | 2 ¹² | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | F | Ü | |
| >23.5156 | 2409 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | Overflow |
| 23.5156 | 2408 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | Overrange |
| 20.0097 | 2049 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | |
| 20.000 | 2048 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 0.0097 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | |
| 0.000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Rated |
| -0.0097 | -1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | range |
| -20.000 | -2048 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| -20.0097 | -2049 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | Under- |
| -23.5156 | -2408 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | range |
| <-23.5156 | -2409 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | Underflow |

Input range 4 to 20 mA

The following table contains the representation of the digitized measured value for the:

• Current measuring range 4 to 20 mA

Table 7-54 SIMATIC S5 format: representation of the digitized measured value 4 to 20 mA (expansion module with analog inputs)

| Measuring | Units | Data word | | | | | | | | | | | | | | | Range | |
|---------------------|--------|-----------------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|----|----------------|----------------|----------------|----------------|---|---|-------|-------------|
| range 4 to 20 mA | (dec.) | 2 ¹² | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | F | Ü | |
| >22.8125 | 2921 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | Overflow |
| 22.8125 | 2920 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | Overrange |
| 20.0078 | 2561 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | |
| 20.000 | 2560 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 4.0078 | 513 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | Rated range |
| 4.000 | 512 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 3.9922 | 511 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | Under- |
| 1.1852 | 151 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | range |
| <1.1797 | 4095 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | Underflow |

Relationship between "Wire break" and measuring range

The \leq 3.6 mA measuring range according to Table 7-54 can be used only if the "wire break" parameter has been deactivated in the software.

When "wire break" has been activated and the measuring range is \leq 3.6 mA, then "4095" is output and the error and overflow bits are set.

Standard temperature range, Pt 100

In the following table you will find the representation of the digitized measured value for the standard temperature range of the Pt 100 sensor. The characteristic linearization applies to the following temperature ranges: -200 °C to +850 °C (in increments of 0.5 °C).

| Measured | Units | Data word | | | | | | | | | | | | | | Range | | |
|----------------|--------|-----------------|-----------------|-----------------|----------------|----------------|----|----------------|----------------|----|----------------|----------------|----------------|----------------|---|-------|---|-----------------|
| value in °C | (dec.) | 2 ¹² | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 27 | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | F | Ü | |
| >1000.0 | 2001 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | Overflow |
| 1000.0 | 2000 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Over- |
| 851.0 | 1702 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | range* |
| 850.0 | 1700 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | |
| 100 | 200 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | |
| 0.0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Rated |
| -20 | - 40 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | range |
| -100.0 | - 200 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | |
| -101.0 | - 202 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | Under- |
| -243.0 | - 486 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | range |
| <-243.0 | - 487 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | Under- flow* |

Table 7-55 SIMATIC S5 format: representation of the digitized measured value for the standard temperature range, Pt 100 (expansion module with analog inputs)

In the overrange and underrange, the gradient of the characteristic curve at the point where the linearized rated range is left is retained.

Tables for output ranges

As of Table 7-56 you will find the analog output ranges of the expansion modules with analog outputs.

Output range \pm 10 V

The following table contains the representation of the voltage output range \pm 10 V.

| Output | Units | | | | | | I | Data | wo | rd | | | | | | | | Range |
|-----------------|--------|-----------------|-----------------|----------------|----------------|----|----------------|----------------|----|----------------|----------------|----------------|----------------|---|---|---|---|-----------|
| range ± 10 V | (dec.) | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 27 | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | x | x | x | |
| 0 | ≥1205 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | х | Х | х | Х | Overflow |
| 11.7578 | 1204 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | х | х | х | Х | Overrange |
| 10.0098 | 1025 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | х | х | х | х | |
| 10.0000 | 1024 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | х | х | х | |
| 0.0098 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | х | х | х | х | |
| 0.000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | х | х | х | Rated |
| -0.0098 | -1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | х | х | х | range |
| -10.0000 | -1024 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | x | х | х | х | |
| -10.0098 | -1025 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | х | х | Х | Under- |
| -11.7578 | -1204 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | х | х | х | х | range |
| 0 | ≤1205 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | х | Х | Х | х | Underflow |

Table 7-56 SIMATIC S5 format: representation of the analog voltage output range +/-10 V
Output range \pm 20 mA

The following table contains the representation of the current output range \pm 20 mA.

| Output | Units | Data word | | | | | | Range | | | | | | | | | | |
|------------------|--------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|----|----------------|----------------|----------------|----------------|---|---|---|---|-----------------|
| range ± 20 mA | (dec.) | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | x | x | x | |
| 0 | ≥1205 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | х | Х | Х | Х | Overflow |
| 23.5156 | 1204 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | х | Х | Х | Х | Overrange |
| 20.0195 | 1025 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | x | х | х | х | |
| 20.000 | 1024 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | Х | Х | Х | |
| 0.0195 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | х | х | х | х | |
| 0.000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | х | х | х | Rated range |
| -0.0195 | -1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | х | х | х | |
| -20.000 | -1024 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | х | х | х | |
| -20.0195 | -1025 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | Х | Х | Х | |
| -23.5156 | -1204 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | х | х | х | х | Under- range |
| 0 | ≤−1205 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | х | Х | Х | х | Underflow |

Table 7-57 SIMATIC S5 format: representation of the analog current output range +/-20 mA

Output range 4 to 20 mA

The following table contains the representation of the current output range 4 to 20 mA.

| Output | Units | | Data word | | | | | | | | Range | | | | | | | |
|---------------------|--------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|----|----------------|----------------|----------------|----------------|---|---|---|---|-------------|
| range 4 to 20 mA | (dec.) | 2 ¹¹ | 2 ¹⁰ | 2 ⁹ | 2 ⁸ | 2 ⁷ | 2 ⁶ | 2 ⁵ | 24 | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ | x | x | x | x | |
| 0 | ≥1205 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | х | Х | х | х | Overflow |
| 22.8125 | 1204 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | х | Х | х | х | Overrange |
| 20.0156 | 1025 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | х | х | х | х | |
| 20.000 | 1024 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | Х | х | х | |
| 4.0156 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | х | х | х | х | Rated range |
| 4.000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | x | х | х | х | |
| 3.9844 | -1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | Х | х | х | Underrange |
| 0 | -256 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | х | х | х | х | |
| 0 | -257 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | х | Х | х | х | Underflow |
| 0 | ≤−1205 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | х | х | х | х | |

Table 7-58 SIMATIC S5 format: representation of the analog current output range 4 to 20 mA

7.21.6 Behavior of the analog inputs and outputs during operation and in the event of faults

This chapter deals with the following topics:

- The dependency of the analog input and output values on the supply voltage of the expansion module and the operating modes of the PLC
- The behavior of the analog expansion modules as a function of the position of the analog values in the relevant value range
- The effect of errors on the analog inputs/outputs

Effect of the supply voltage and the operating mode

The input and output values of the analog modules are dependent on the supply voltage for electronic components/sensors and on the operating mode of the PLC (CPU of the DP master).

Table 7-59 How the analog input/output values depend on the operating mode of the PLC (CPU of the DP master) and the supply voltage L +

| Operating mode of the PLC (CPU of the DP master) | | Supply vol- tage L + to ET 200X | Input value of the expansion module with analog inputs and (evaluation possible in the CPU of the DP master) | Output value of the expan- sion module with analog out- puts |
|--|------|---------------------------------------|---|---|
| Power | RUN | L + applied | Process value | PLC value |
| on | | | $7FFF_H$ until the first conversion after the module is switched on or after the module is parameterized | Until the first conversion after the module is switched on, a signal of 0 mA or 0 V is output. after the module is parameterized, the previous value is output. |
| | | L + not applied | 0 mA/0 V | 0 mA/0 V |
| Power on | STOP | L + applied | 0 mA/0 V | Substitute value/last value (default: 0 mA/0 V) |
| | | L + not applied | 0 mA/0 V | 0 mA/0 V |
| Power | - | L + applied | - | 0 mA/0 V |
| off | | L + not applied | - | 0 mA/0 V |

Supply voltage On/Off

A failure of the supply voltage to the electronics/sensors on the ET 200X is always displayed by the "ON" LED on the basic module and also entered in the diagnostic data area of the basic module.



Caution

When the supply voltage for electronic components/sensors on the ET 200X is switched on/off, incorrect interim values may be obtained temporarily at the analog outputs.

Effect of the value range for the analog input

The behavior of the expansion modules with analog inputs depends on where the input values are in the value range. The following table indicates this:

| T-LL 7 00 | Delession of the second states | and a shall a set of the set | | 1 | and a state state state of a second state of the second state of t |
|-------------|--------------------------------|------------------------------|--------------------|--------------------|--|
| Iania /-hii | Renavior of the analog | modulide de ditin | notion of the hoei | חובתב בתז זה תחוזו | |
| | | | | | |
| | | | | | |

| Measured va- lue in | Input value in SIMATIC S7 format | Input value in SIMATIC S5 format | SF LED | Diagnostic data area of the module | Interrupt |
|---|--|---|--------|--|-----------------------------|
| in the rated range | Measured value | Measured value | - | - | _ |
| in the over- range/under- range | Measured value | Measured value | _ | - | _ |
| in the overflow | 7FFF _H | End of the overrange +1 plus overflow bit | On* | Entry per- formed* | Diagnostic in- terrupt** |
| in the under- flow | 8000 _H | End of the un- derrange –1 plus overflow bit | On* | Entry per- formed* | Diagnostic in- terrupt** |
| Outside the up- per or lower limit value | Measured value | Measured value | - | - | Hardware inter- rupt** |
| Before parame- terization or in the event of in- correct para- meterization | 7FFF _H | 7FFF _H | On* | _ | _ |

* When the "group diagnosis" parameter has been enabled in the configuration software

** When the diagnostic or hardware interrupt has been enabled in the configuration software

EM 144 AI 2 x RTD, response in the event of a wire break

If a wire break occurs on one of the EM 144 AI 2 x RTD expansion module's channels, the measured values on the expansion module's other channel may be corrupted. When this happens in S5 format, the overflow bit is set and the value $06E6_{\rm H}$ is loaded; in S7 format the value $7FFF_{\rm H}$ is loaded.

Effect of the value range for the analog output

The behavior of the expansion modules with analog outputs depends on where the output values are in the value range. The following table indicates this:

 Table 7-61
 Behavior of the analog modules depending on the position of the analog output value in the value range

| Output value in | Output value in SIMATIC S 5/S7 format | SF LED | Diagnostic data area of the module | Interrupt |
|---|--|--------|--|-----------|
| Rated range | Value from DP master | _ | _ | _ |
| Overrange/underrange | Value from DP master | _ | _ | _ |
| Overflow | 0 signal | _ | _ | _ |
| Underflow | 0 signal | - | _ | _ |
| Before parameterization or in the event of incor- rect parameterization | 0 signal | On* | _ | _ |

7.21.7 Connecting measuring sensors to the analog inputs

You can connect different measuring sensors to the analog inputs depending on the type of measurement involved:

- Voltage sensors
- Current sensors as:
 - Two-wire measuring transducers
 - Four-wire measuring transducers
- Resistance thermometers

Abbreviations used

The following abbreviations are used in the figures in this section:

- I_{C+}: Constant-current line (positive)
- I_C.: Constant-current line (negative)
- M₊: Measuring line (positive)
- M_: Measuring line (negative)
- 1M: Frame connection for sensor
- 1L₊: Supply voltage connection for DC 24 V sensor

Connecting voltage sensors

The figure below shows how voltage sensors are connected to an expansion module with analog inputs.



Figure 7-24 Connection of voltage sensors to analog inputs (EM with order number 6ES7 144-1FB31-0XB0)

Connecting current sensors as two- and four-wire measuring transducers

The supply voltage is fed to the two-wire measuring transducer and is inherently short circuit-proof. The two-wire measuring transducer then converts the fed measured value into a current. Four-wire measuring transducers have a separate supply voltage connection.

The two-wire measuring transducers must be insulated measuring sensors.

The figure below shows how current sensors are connected as two-wire measuring transducers to an EM 144 Al 2 \times I expansion module (4 to 20 mA).



Figure 7-25 Connection of current sensors (two-wire measuring transducers) to analog inputs (EM with order number 6ES7 144-1GB41-0XB0)

Four-wire measuring transducer at the EM 144 AI 2 imes I (±20 mA)

The figure below shows how current sensors are connected as four-wire measuring transducers to an EM 144 Al 2 \times I expansion module (±20 mA).



Figure 7-26 Connection of current sensors (four-wire measuring transducers) to analog inputs (EM with order number 6ES7 144-1GB31-0XB0)

Four-wire measuring transducer to EM 144 AI 2 \times I (4 to 20 mA)

The figure below shows how current sensors are connected as four-wire measuring transducers to an EM 144 Al 2 \times I expansion module (4 to 20 mA). **Note:** There is no L+ available at pin 1 on the expansion module. You therefore have to feed the supply voltage for the current sensor from an external source.



Figure 7-27 Connection of current sensors (four-wire measuring transducers) to analog inputs (EM with order number 6ES7 144-1GB41-0XB0)

Connecting Pt 100 resistance thermometers

The resistance thermometers are measured in a four-conductor connection. Constant current is fed to the resistance thermometers via connections I_{C+} and I_{C-} . The voltage generated at the resistance thermometer is measured via connections M_+ and M_- . This ensures highly accurate measurement results with the four-conductor connection. The figure below shows how resistance thermometers are connected to an EM 144 Al 2 \times RTD expansion module.





In the case of a two- or three-wire connection, you have to create appropriate bridges in the connector to form connections between M_+ and I_{C+} and M_- and I_{C-} on the expansion module. However, you must reckon with a lost of accuracy in the measurement results.

7.21.8 Connecting loads to the analog outputs

When you use expansion modules with analog outputs, you can supply loads/actuators with current or voltage.

Abbreviations used

The following abbreviations are used in the figures in this section:

- Q_I: Analog output current
- Q_V: Analog output voltage
- 1M: Frame connection/reference potential of the analog circuit
- R_L: Load/actuator

Connecting loads to a voltage output

You have to connect loads to a current output at Q_V and the reference point of the analog circuit 1M (see Figure 7-29).

Four-conductor connection

If you connect a load with a 4-core cable to a voltage output, use only 2 of the cable's cores and connect them to pins 1 and 3.

Connecting loads to a current output

You have to connect loads to a current output at Q_I and the reference point of the analog circuit 1M.

The figure below shows how loads are connected to a voltage or current output of an expansion module with analog outputs.



Figure 7-29 Connection of loads to a voltage or current output (analog output; EM with order number 6ES7 145-1FB31-0XB0; 6ES7 145-1GB31-0XB0)

7.21.9 EM 144 AI 2 x U expansion module (6ES7 144-1FB31-0XB0)

Features

The EM 144 AI 2 \times U expansion module with the order number 6ES7 144-1FB31-0XB0 has the following features:

- 2 inputs for voltage measurement (2 channels with the same measuring range and data format)
- Input range ± 10 V
- Resolution of 12 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable hardware interrupt
- Parameterizable diagnostics
- SF LED

Pinout of the sockets for AI

The following table shows the pinout of the two sockets used to connect the analog inputs. You can find the layout of the sockets in Appendix C.

| Table 7-62 | Pinout of the socket | s for 2-channe | l analog inputs | (voltage) |
|------------|----------------------|----------------|-----------------|-----------|
|------------|----------------------|----------------|-----------------|-----------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|------------------------------|-----------------------------|---|
| 1 | Sensor supply output 1L+ | | \frown |
| 2 | Input signal "+", channel 0 | Input signal "+", channel 1 | |
| 3 | Chassis ground, power supply | | |
| 4 | Input signal "", channel 0 | Input signal "", channel 1 | |

The basic circuit diagram of the expansion module is shown below.



Figure 7-30 Basic circuit diagram of expansion module EM 144 AI 2 x U

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimension | is and weight | Voltages, current | Voltages, currents, potentials | | | |
|----------------------------|---------------|--|--------------------------------|--|--|--|
| Dimensions | 87 × 110 × 55 | Electrical isolation | No | | | |
| $W \times H \times D$ (mm) | | Permissible potential diffe- | | | | |
| Weight | Approx. 250 g | rence | 2.0 VDC; AC _{SS} | | | |
| Module-s | pecific data | Between input (frame connection) and Marce | | | | |
| Number of inputs | 2 | (U _{CM}) | 0 VAC; DC | | | |
| Cable length | | Between M _{ANA} and | | | | |
| Shielded | Max. 30 m | centralized grounding | | | | |
| | | Power input | Max. 40 mA | | | |
| | | From supply voltage L+ | Turn 0.014/ | | | |
| | | Power loss of the module | Typ. 0.9 W | | | |

| Analog value f | Analog value formation | | | ±0.01 %/K |
|--|------------------------|-----------|---|---------------------------|
| Measurement principle | Integra | tive | ference to input range) | |
| Integration and cycle time/ | | | Crosstalk between inputs | > 45 dB |
| resolution per channel: | | | Linearity error (with refe- | ±0.05 % |
| Integration time parameterizable | Yes | | rence to input range) | |
| Integration time in ms | 16 7 | 20 | Repeat accuracy | ± 0.05 % |
| Cycle time in ms | 134 | 160 | reference to input range) | |
| (all channels) | | | Status, alarms, d | liagnostics |
| Interference voltage | 60 | 50 | Alarms | Diagnostic |
| suppression for interference frequency | | | | interrupt |
| f1 in Hz | 12 bits | plus sign | | Hardware |
| Resolution (including | | | | interrupt |
| overrange) | | | Diagnostic functions | Configurable |
| Rated value in units: SIMATIC S7 format: | 6912 | | Group error | Red LED (SF) |
| SIMATIC S7 Ionnat. SIMATIC S5 format: | 4096 | | Sensor supply | outputs |
| | sion err | or limits | Outputs | 2 |
| | | | | Up to 40 °C max. 0.9A: |
| pression | | | | Up to 55 °C |
| Common-mode | > 60 dl | 3 | Oh ant sine vit must a stirm | max. 0.7A |
| interference | > 40 dl | 3 | Short circuit protection | Yes, electronic |
| Series-mode | | | Sensor select | ion data |
| interference (peak interference | | | Input range (rated value)/in- put resistance | \pm 10 V/100 k Ω |
| input range) | | | Permissible input voltage (destruction limit) | 30 V |
| Operational limit (entire | ±1.2 % | 6 | Sensor connection | |
| ference to input range) | | | For voltage | Possible |
| Basic error (operational limit | ±1.0 % | 6 | measurement | |
| at 25 °C with reference to input range) | | | * Please note the total current p | er ET 200X. |

7.21.10 EM 144 AI 2 x I expansion module (+/-20 mA) (6ES7 144-1GB31-0XB0)

Features

The EM 144 Al 2 \times I expansion module with the order number 6ES7 144-1FB31-0XB0 has the following features:

- 2 inputs for current measurement (2 channels with the same measuring range and data format)
- Parameterizable input range, ± 20 mA or 4 to 20 mA
- Connection of sensors as four-wire measuring transducers
- Resolution of 12 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable hardware interrupt
- Parameterizable diagnostics
- SF LED

Pinout of the sockets for AI

The following table shows the pinout of the two sockets used to connect the analog inputs. You can find the layout of the sockets in Appendix C.

| Table 7-63 | Pinout of the sockets for 2-cha | annel analog inputs (EM 144 AI 2 x I) |
|------------|---------------------------------|---------------------------------------|
|------------|---------------------------------|---------------------------------------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|------------------------------|-----------------------------|---|
| 1 | Sensor supply output 1L+ | | \bigcirc |
| 2 | Input signal "+", channel 0 | Input signal "+", channel 1 | |
| 3 | Chassis ground, power supply | | |
| 4 | Input signal "", channel 0 | Input signal "", channel 1 | |

The basic circuit diagram of the expansion module is shown below.



Figure 7-31 Basic circuit diagram of expansion module EM 144 AI 2 x I

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimension | ns and weight | Voltages, current | s, potentials |
|----------------------------|---------------|--|---------------------------|
| Dimensions | 87 × 110 × 55 | Electrical isolation | No |
| $W \times H \times D (mm)$ | | Permissible potential diffe- | |
| Weight | Approx. 250 g | rence | 2.0 VDC; AC _{SS} |
| Module-s | specific data | Between input (frame | |
| Number of inputs | 2 | (U _{CM}) | 0 VAC: DC |
| Cable length | | Between M _{ANA} and | , |
| Shielded | Max. 30 m | centralized grounding point (U _{ISO}) | |
| | | Power input | |
| | | From supply voltage L+ | Max. 40 mA |
| | | Power loss of the module | Typ. 0.9 W |

| Analog value f | ormatio | n | Crosstalk between inputs | > 45 dB |
|--|------------|-----------|--|--|
| Measurement principle | Integra | tive | Linearity error (with refe- | ±0.05 % |
| Integration and cycle time/ resolution per channel: | N/ | | Repeat accuracy | ±0.05 % |
| Integration time parameterizable | Yes | | reference to input range) | |
| Integration time in ms | 16.7 | 20 | Status, alarms, | diagnostics |
| Cycle time in ms (all channels) | 134 | 160 | Alarms | Diagnostic interrupt |
| Interference voltage suppression for interference frequency | 60 | 50 | | Hardware interrupt |
| f1 in Hz | | | Diagnostic functions | Configurable |
| Resolution (including | 12 bits | plus sign | Group error | Red LED (SF) |
| Overrange) Actod value in units: | | | Sensor supply outputs | |
| SIMATIC S7 format: | 6012 | | Outputs | 2 |
| - SIMATIC S7 format: | 10912 | | Output current* | Up to 40 °C |
| | ion or | ar limita | | max. 0.9A; Up to 55 °C |
| Interference suppress | sion, erre | or limits | - | max. 0.7A |
| Interference voltage sup- | | | Short circuit protection | Yes, electronic |
| Common-mode | > 60 di | 3 | Sensor selec | tion data |
| interference | > 10 di | 3 | Input range (rated | \pm 20 mA/25 Ω |
| Series-mode | 2 40 UL | | range)/input resistance | |
| interference | | | parameterizable | 4 to 20 mA |
| (peak interference value < rated value of input range) | | | Permissible input voltage (destruction limit) | 40 mA |
| | | , | Sensor connection | |
| Operational limit (entire temperature range with re- ference to input range) | ±1.2 % | 6 | For current measurement:-wire measuring transducer** | Not possible Possible |
| Basic error (operational limit at 25 °C with reference to input range) | ±1.0 % | 6 | * Please note the total current ** 1L+ of module must be used | per ET 200X. since a possible broken wire |
| Temperature error (with re- ference to input range) | ±0.01 | %/K | signal is possible only with available by the module. | the sensor supply made |

7.21.11 EM 144 AI 2 x I expansion module (4 to 20 mA) (6ES7 144-1GB41-0XB0)

Features

The EM 144 AI 2 \times I expansion module with the order number 6ES7 144-1GB41-0XB0 has the following features:

- 2 inputs for current measurement (2 channels with the same measuring range and data format)
- Input range 4 to 20 mA
- · Connection of sensors as two- or four-wire measuring transducers
- Resolution of 12 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable hardware interrupt
- Parameterizable diagnostics
- SF LED

Pinout of the sockets for AI

The following table shows the pinout of the two sockets used to connect the analog inputs. You can find the layout of the sockets in Appendix C.

| Table 7-64 | Pinout of the sockets | for 2-channel analog | g inputs (EM 14 | 14 AI 2 x I, 4 to 20 mA) |
|------------|-----------------------|----------------------|-----------------|--------------------------|
|------------|-----------------------|----------------------|-----------------|--------------------------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|------------------------------|-----------------------------|---|
| 1 | Sensor supply output 1L+*; | Sensor supply output 1L+*; | |
| | Input signal "+", channel 0 | Input signal "+", channel 1 | Ø ● 2 |
| 2 | Input signal "", channel 0 | Input signal "", channel 1 | (◯1 ◯ ◯3 |
| 3 | Chassis ground, power supply | | 4 |
| 4 | - | | |

^t L+ is not available at pin 1 for connecting **four-wire measuring transducers**. You therefore have to feed the sensor supply voltage from an external source (see also Section 7.21.7).

The basic circuit diagram of the expansion module is shown below.



Figure 7-32 Basic circuit diagram of Expansion module EM 144 AI 2 x I (4 to 20 mA)

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimensions a | nd weigh | nt | Interference suppress | ion, error limits |
|--|---------------|---------------------|---|-------------------|
| Dimensions W \times H \times D (mm) | 87 × 1 | 10 × 55 | Interference voltage sup- pression | |
| Weight | Approx | . 250 g | Common-mode interference | > 60 dB |
| Module-spec | ific data | | Series-mode | > 40 dB |
| Number of inputs | 2 | | interference | |
| Cable length | | | value < rated value of | |
| Shielded | Max. 3 | 0 m | input range) | |
| Voltages, current | s, poten | tials | Operational limit (entire | ±1.2 % |
| Electrical isolation | No | | temperature range with re- ference to input range) | |
| Permissible potential diffe- rence • Between input (frame | 2.0 VD | C; AC _{SS} | Basic error (operational limit at 25 °C with reference to input range) | ±1.0 % |
| connection) and M _{ANA} (U _{CM}) ● Between M _{ANA} and | 0 VAC: | DC | Temperature error (with re- ference to input range) | ±0.01 %/K |
| centralized grounding | | | Crosstalk between inputs | > 45 dB |
| point (U _{ISO}) Power input | | | Linearity error (with refe- rence to input range) | ±0.05 % |
| From supply voltage L+ | Max. 8 | 0 mA | Repeat accuracy (steady state at 25 °C with | ± 0.05 % |
| Power loss of the module | Typ. 11 | /V | reference to input range) | |
| | ormatio | n | Status, alarms, diagnostics | |
| Measurement principle | Integra | itive | Alarms | Diagnostic |
| Integration and cycle time/ resolution per channel: | | | | Hardware |
| Integration time parameterizable | Yes | | Diagnostic functions | |
| Integration time in ms | 16.7 | 20 | Group error | Red I FD (SF) |
| Cycle time in ms | 134 | 160 | Sensor select | ion data |
| (all channels) | 60 | 50 | Input range (rated value)/in- | 4 to 20 mA/25 Q |
| suppression for interference frequency | 60 | 50 | put resistance Permissible input voltage | 40 mA |
| Resolution (including | 12 hits | nlus sign | (destruction limit) | |
| overrange) | 12 0113 | plus sign | Short circuit protection | Yes |
| Rated value in units: | | | Short-circuit current | Approx. 65 mA |
| SIMATIC S7 format: | 6912 | | Sensor load | Max. 750 Ω |
| SIMATIC S5 format: | 4096 | | Sensor connection | |
| | | | For current measurement: As 2-wire measuring transducer | Possible |
| | | | As 4-wire measuring transducer | Possible |

7.21.12 EM 144 AI 2×RTD expansion module (6ES7 144-1JB31-0XB0)

Features

The EM 144 AI 2 \times RTD expansion module with the order number 6ES7 144-1JB31-0XB0 has the following features:

- 2 inputs for Pt 100 resistance thermometer (2 channels with the same measuring range and data format)
- Input range for Pt 100
- Resolution of 12 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable hardware interrupt
- Parameterizable diagnostics
- SF LED

Pinout of the sockets for AI

The following table shows the pinout of the two sockets used to connect the analog inputs. You can find the layout of the sockets in Appendix C.

| Table 7-65 | Pinout of the sockets for 2-channel | analog inputs (Pt 100) |
|------------|-------------------------------------|------------------------|
|------------|-------------------------------------|------------------------|

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|----------------------------------|-----------------------------|---|
| 1 | Sensor supply output current (ap | | |
| 2 | Input signal "+", channel 0 | Input signal "+", channel 1 | |
| 3 | Chassis ground, power supply | | |
| 4 | Input signal "", channel 0 | Input signal "", channel 1 | 4 |

The basic circuit diagram of the expansion module is shown below.



Figure 7-33 Basic circuit diagram of expansion module EM 144 AI 2 x RTD

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimensions an | d weight | | Interference suppress | sion, error limits |
|--|-------------|--------------------|--|--------------------|
| Dimensions W \times H \times D (mm) | 87 × 11 | 0 × 55 | Interference voltage sup- pression | |
| Weight | Approx. | 250 g | Common-mode interference | > 60 dB |
| Module-speci | fic data | | Series-mode | > 40 dB |
| Number of inputs | 2 | | interference | |
| Cable length | | | (peak interference value < rated value of | |
| Shielded | Max. 30 | m | input range) | |
| Voltages, currents | s, potentia | als | Operational limit (entire | \pm 1.2 % |
| Electrical isolation | No | | temperature range with re- ference to input range) | |
| Permissible potential diffe- rence • Between input (frame | 2.0 VDC | ; AC _{SS} | Basic error (operational limit at 25 °C with reference to input range) | ±1.0 % |
| connection) and M _{ANA} (U _{CM}) | | | Temperature error (with re- ference to input range) | ±0.01 %/K |
| centralized grounding | 0 770, 1 | | Crosstalk between inputs | > 45 dB |
| point (U _{ISO}) Power input | | | Linearity error (with refe- rence to input range) | ±0.05 % |
| From supply voltage L+ | Max. 40 | mA | Repeat accuracy (steady state at 25 °C with | ± 0.05 % |
| Power loss of the module | Typ. 0.9 | W | reference to input range) | |
| Analog value fo | ormation | | Status, alarms, diagnostics | |
| Measurement principle | Integrati | ve | Alarms | Diagnostic |
| Integration and cycle time/ resolution per channel: | | | | Hardware |
| Integration time parameterizable | Yes | | Diagnastia functiona | Configurable |
| Integration time in ms | 16.7 | 20 | Group error | Red I FD (SF) |
| Cycle time in ms | 134 | 160 | Sensor select | ion data |
| (all channels) Interference voltage suppression for | 60 | 50 | Input range (rated value)/in- put resistance | Pt 100/10 MΩ |
| f1 in Hz | 12 bits p | lus sign | Characteristic curve lineari- zation | Yes |
| Resolution (including overrange) | | | Permissible input voltage (destruction limit) | 30 V |
| Rated value in units: SIMATIC S7 formatic | 6912 | | Measurement current Ic. | Max. 1.5 mA |
| SIMATIC S7 Ionnat. SIMATIC S5 format: | 4096 | | Sensor connection | - |
| | | | Two-conductor connection | Possible |
| | | | Three-conductor connection | Possible |
| | | | Four-conductor | Possible |

connection

7.21.13 EM 145 AO 2×U expansion module (6ES7 145-1FB31-0XB0)

Features

The EM 145 AO 2 \times U expansion module with the order number 6ES7 145-1FB31-0XB0 has the following features:

- 2 outputs for voltage output (2 channels with the same measuring range and data format)
- Output range ±10 V
- Resolution of 11 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable diagnostics
- Parameterizable substitute value output
- SF LED

Pinout of sockets for AO

The following table shows the pinout of the two sockets used to connect the analog outputs. You can find the layout of the sockets in Appendix C.

Table 7-66 Pinout of the sockets for 2-channel analog outputs (voltage)

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|---------------------------------|---------------------------------|---|
| 1 | Output signal Q_V , channel 0 | Output signal Q_V , channel 1 | |
| 2 | - | - | |
| 3 | Chassis ground, power supply | | |
| 4 | - | - | |

The basic circuit diagram of the expansion module is shown below.



Figure 7-34 Basic circuit diagram of expansion module EM 145 AO 2 x U

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimensions ar | nd weight | Interference suppress | sion, error limits |
|---|-------------------|--|--------------------|
| $\begin{array}{l} \text{Dimensions} \\ \text{W} \times \text{H} \times \text{D} \text{ (mm)} \end{array}$ | 87 × 110 × 55 | Operational limit (entire temperature range with re- | ±1% |
| Weight | Approx. 250 g | | |
| Module-spec | ific data | at 25 °C with reference to | ± 0.9 % |
| Number of outputs | 2 | output range) | |
| Cable length | | Temperature error (with re- | ±0.01 %/K |
| Shielded | Max. 30 m | ference to output range) | |
| Voltages, currents | s, potentials | Crosstalk between outputs | > 45 dB |
| Electrical isolation | No | Linearity error (with refe- rence to output range) | ±0.08 % |
| Permissible potential diffe- rence • Between coil (frame | 0 VAC; DC | Repeat accuracy (steady state at 25 °C with reference to output range) | ±0.05 % |
| connection) and centralized grounding point (U _{ISO}) | | Output ripple (with reference to output range, | ±0.05 % |
| Power input | | Status alarms d | liagnostics |
| From supply voltage L+ | Max. 75 mA | | |
| Power loss of the module | Typ. 1.5 W | Alarms | |
| Analog value f | ormation | | Configurable |
| Resolution (including over- | 11 bits plus sign | | tion data |
| range) | 1 0 | | |
| Rated value in units: | | Output range (rated value) | -10 to 10 V |
| SIMATIC S7 format: | 1728 | Load resistance | Min. 1.0 kΩ |
| SIMATIC S5 format: | 1024 | With capacitive load | Max. 0.1 μF |
| Cycle time (all channels) | 1 ms | Short circuit protection Short circuit current | Yes |
| Settling time | | | |
| For resistive load | 0.6 ms | Permissible input voltage | 15 V |
| For capacitive load | 6.0 ms | tion limit) | |
| Replacement values can be | No | Actuator connection | |
| applied | | Two-conductor connection | Possible |
| | | Four-conductor connection | Possible |

7.21.14 EM 145 AO 2×I expansion module (6ES7 145-1GB31-0XB0)

Features

The EM 145 AO 2 \times I expansion module with the order number 6ES7 145-1GB31-0XB0 has the following features:

- 2 outputs for current measurement (2 channels with the same measuring range and data format)
- Parameterizable output range, ± 20 mA or 4 to 20 mA
- Resolution of 11 bits plus sign
- 24 VDC supply voltage
- Non-isolated
- Parameterizable diagnostic interrupt
- Parameterizable diagnostics
- Parameterizable substitute value output
- SF LED

Pinout of sockets for AO

The following table shows the pinout of the two sockets used to connect the analog outputs. You can find the layout of the sockets in Appendix C.

Table 7-67 Pinout of the sockets for 2-channel analog outputs (current)

| Pin | Assignment of socket X1 | Assignment of socket X2 | Front view of socket (Front view) |
|-----|--|--|---|
| 1 | Output signal Q _I , channel 0 | Output signal Q _I , channel 1 | |
| 2 | - | | |
| 3 | Chassis ground, power supply | | |
| 4 | - | | |

The basic circuit diagram of the expansion module is shown below.



Figure 7-35 Basic circuit diagram of expansion module EM 145 AO 2 x I

Covering up unused connections

You must seal off any connections which are not required with M12 screw caps, in order to ensure that the degree of protection (IP 65, IP 66 or IP 67) is achieved.

| Dimensions an | d weight | Interference suppress | ion, error limits |
|--|-------------------|---|----------------------------|
| Dimensions W \times H \times D (mm) | 87 × 110 × 55 | Operational limit (entire temperature range with re- | ±1% |
| Weight | Approx. 250 g | | |
| Module-speci | fic data | Basic error (operational limit at 25 °C with reference to | ± 0.9 % |
| Number of outputs | 2 | output range) | |
| Cable length | | Temperature error (with re- | ±0.01 %/K |
| Shielded | Max. 30 m | referice to output range) | |
| Voltages, currents | s, potentials | Crosstalk between outputs | > 45 dB |
| Electrical isolation | No | Linearity error (with refe- rence to output range) | ±0.08 % |
| Permissible potential diffe- rence Between coil (frame | 0 VAC; DC | Repeat accuracy (steady state at 25 °C with reference to output range) | ±0.05 % |
| centralized grounding point (U _{ISO}) | | Output ripple (with refe- rence to output range, bandwidth 0 to 50 kHz) | ±0.05 % |
| Power input | | Status, alarms, d | iagnostics |
| From supply voltage L+ | Max. 110 mA | Alormo | Diagnostia interrunt |
| Power loss of the module | Typ. 2.3W | | |
| Analog value fo | ormation | | Configurable |
| Resolution (including over- | 11 bits plus sign | | |
| range) | | Actuator select | lion data |
| Rated value in units: | | Output range (rated va- lues), parameterizable | –20 to 20 mA 4 to 20 mA |
| – SIMATIC S7 format: | 1728 | Load resistance | Max. 500 Ω |
| SIMATIC S5 format: | 1024 | Inductive load | Max. 0.1 mH |
| Cycle time (all channels) | 1 ms | Current output | |
| Settling time | | No-load voltage | Max. 15 V |
| For resistive load | 0.6 ms | Permissible input current for | 40 mA |
| For capacitive load | 6.0 ms | current output (destruction | - |
| Replacement values can be applied | NO | Actuator connection | |
| | | Two-conductor connection | Possible |

7.22 SITOP power power supply 24V/10A (6EP1 334-2CA00)

Properties

The SITOP power 24V/10A power supply, order number 6EP1 334-2CA00, has the following features:

- Primary switched-mode power supply
- Rated input voltage 120/230 VAC
- Rated output voltage 24 VDC, floating, short-circuit-proof and stable at no load
- Rated output current up to 10 A
- Output voltage optionally as supply voltage for electronics/sensors and/or load voltage of ET 200X
- Parameterizable behavior in the event of an error: restart or shutdown following short circuit on the output
- LEDs for operating mode

Basic circuit diagram

The figure below shows the basic circuit diagram of the SITOP power power supply.



Figure 7-36 Basic circuit diagram for SITOP power supply

| Dimensions a | nd weight | Output voltage | |
|---|---|--|--|
| | | Rated value Llass | 24 VDC |
| $W \times H \times D (mm)$ | 146.5 X 265 X 134 | Overall tolerance, static | + 3% |
| Weight | Approx 17 kg | Posidual rippla | 15 m |
| Voltagos curront | | | Max. 15 mv _{ss} |
| voltages, current | is, potentiais | Setting range | 22.8 V to 25.2 V |
| Input voltage | 400/000 \/4 0 | Output current | |
| Rated value U _{EN} | 120/230 VAC | Rated value I_{AN} | 10 A |
| Permissible range | 93 V to 132 VAC | • To 40 °C | Max. 10A |
| Erequency | 107 V 10 204 VAC | • To 55 °C | Max. 8A |
| Mains | Min. 20 ms | Overcurrent limitation | Typ. 1.1 to 1.3 x I ₄ |
| buffering (at UE= 93/187 V: IAN) | | Output short-circuit | Yes |
| Rated input current I _{EN} | 4.3 A/2.6 A | Outputs stable at no load | Yes |
| (at 120 V/230 V) | | Electrical isolation | |
| Current at make (at U _E = 230 V; 25 °C) | <55 A; 2.5 A ² s | Primary/secondary | Yes (SELV as per EN 60950) |
| Recommended circuit- breaker in the supply lead | 16 A, Characteristic C | Status, alarms, diagnostics | |
| Power consumption | 270\\/ | Status display | Green LEDs for |
| | 270W | | 24 V at output terminals |
| Efficiency at full load | Approx. 89% | | Supply voltage |
| Device protection | Internal line-side fuse T 6.3 A/250 V | | available at bu for electronics/ sensors |
| | | | Load voltage available at but |
| | | | Red LED for shut- down on account excess temperatu |

A

Order Numbers

Should you require additional ET 200X components or PROFIBUS accessories for use with the ET 200X, you will find all the order numbers here.

Basic modules

| Designation | Order number |
|---|---------------------|
| BM 141 DI 8 DC 24V basic module | 6ES7 141-1BF12-0XB0 |
| BM 141 DI 8 × DC 24V ECOFAST basic module with large designation labels | 6ES7 141-1BF01-0AB0 |
| BM 141 DI 8 × DC 24V ECOFAST DIAG basic module | 6ES7 141-1BF40-0AB0 |
| BM 142 DO 4 DC 24V/2A basic module | 6ES7 142-1BD22-0XB0 |
| BM 143-DESINA FO basic module with large designation labels | 6ES7 143-1BF00-0XB0 |
| BM 143-DESINA RS485 basic module with large designation labels | 6ES7 143-1BF00-0AB0 |

Table A-1 Basic modules – order numbers

Expansion modules

| Description | Order number |
|---|---------------------|
| EM 141 DI 4×DC 24V expansion module | 6ES7 141-1BD31-0XA0 |
| EM 141 DI 8 DC 24V expansion module | 6ES7 141-1BF31-0XA0 |
| EM 141 DI 8 × DC 24V DIAG expansion module | 6ES7 141-1BF30-0XB0 |
| EM 141 DI $8 \times$ DC 24V expansion module with large designation labels | 6ES7 141-1BF41-0XA0 |
| EM 141 DI 8 × DC 24V DIAG expansion module | 6ES7 141-1BF40-0XB0 |
| EM 142 DO 4×DC 24V/0.5A expansion module | 6ES7 142-1BD30-0XA0 |
| EM 142 DO 4 DC 24V/2A expansion module | 6ES7 142-1BD40-0XA0 |
| EM 142 DO 4 DC 24V/2A expansion module | 6ES7 142-1BD40-0XB0 |
| EM 142 DO $8 \times$ DC 24V/1.2A expansion module with large designation labels | 6ES7 142-1BF30-0XA0 |
| EM 143-DESINA expansion module with large designation labels | 6ES7 143-1BF30-0XB0 |
| EM 144 AI 2×U expansion module | 6ES7 144-1FB31-0XB0 |
| EM 144 AI 2×I expansion module | 6ES7 144-1GB31-0XB0 |
| EM 144 AI 2×I expansion module | 6ES7 144-1GB41-0XB0 |
| EM 144 AI 2×RTD expansion module | 6ES7 144-1JB31-0XB0 |
| EM 145 AO 2×U expansion module | 6ES7 145-1FB31-0XB0 |
| EM 145 AO 2×I expansion module | 6ES7 145-1GB31-0XB0 |
| EM 148-P DI 4×DC 24V/ DO 2 x P expansion module | 6ES7 148-1DA00-0XA0 |
| EM 148-P DO 16 × P/CPV10 expansion module | 6ES7 148-1EH01-0XA0 |
| EM 148-P DO 16 × P/CPV14 expansion module | 6ES7 148-1EH11-0XA0 |
| PM 148 DO 4×DC 24V/2A power module | 6ES7 148-1CA00-0XB0 |
| SITOP power 24V/10A power supply unit | 6EP1 334-2CA00 |
| CP 142-2 communication processor | 6GK7 142-2AH00-0XA0 |

Table A-2 Expansion modules – order numbers

Accessories for ET 200X

| Description | Order number |
|---|---------------------|
| Connector assembly for PROFIBUS-DP, supply voltage for electronic components/sensors and load voltage (protective shell with 6-pin connector, 2 M16 cable glands and 2 lock nuts) | 6ES7 194-1AA01-0XA0 |
| Cover plate (for sealing off unused connectors for PROFIBUS-DP and supply/load voltage; 10 units) | 6ES7 194-1JB00-0XA0 |
| M12 coupler plug, 5-pin (for connecting actuators and sensors) | On request |
| M12 angular coupler plug, 5-pin (for connecting actuators and sensors; cannot be used in conjunction with an M12 Y connector) | On request |
| M12 Y connector, 5-pin (for dual connection of actuators/sensors to digital inputs/outputs) | 6ES7 194-1KA01-0XA0 |
| AS interface, M12 screw cap (for sealing off unused inputs and outputs of the ET 200X; 10 units) | 3RX9 802-0AA00 |
| Silencer for pneumatic module | 6ES7 194-1EA00-0XA0 |
| DIN rail, narrow, length 400 mm for ET 200X electronic submodule | 6ES7 194-1GA00-0XA0 |
| DIN rail, narrow, length 640 mm for ET 200X electronic submodule | 6ES7 194-1GA10-0XA0 |
| DIN rail, narrow, length 2000 mm for ET 200X electronic submodule | 6ES7 194-1GA20-0XA0 |
| DIN rail, wide, length 520 mm for ET 200X electronic module and motor starter/frequency converter | 6ES7 194-1GB00-0XA0 |
| DIN rail, wide, length 1000 mm for ET 200X electronic submodule and motor starter/frequency converter | 6ES7 194-1GB10-0XA0 |
| Screws with washer assemblies (100 screws M5 x 20, crossed recessed head with washer) for fitting ET 200X modules onto DIN rail | 6ES7 194-1KC00-0XA0 |

Table A-3 Accessories for ET200X – order numbers

Accessories for ET 200X-DESINA / ET 200X-ECOFAST

Table A-4 Accessories for ET 200X-DESINA / ET 200X-ECOFAST – order numbers

| Description | | Order number |
|--|--|--|
| Configuration connector | | 6ES7 194-1KB00-0XA0 |
| ECOFAST hybrid cables (2 copper conductors and 2×2 copper wires) complete with ECOFAST | | |
| connectors: | 1.5 m | 6XV1 830-7BH15 |
| | 3.0 m | 6XV1 830-7BH30 |
| | 5.0 m | 6XV1 830-7BH50 |
| | 10.0 m | 6XV1 830-7BN10 |
| | 15.0 m | 6XV1 830-7BN15 |
| | 20.0 m | 6XV1 830-7BN20 |
| | 25.0 m | 6XV1 830-7BN25 |
| | 30.0 m | 6XV1 830-7BN30 |
| | 35.0 m | 6XV1 830-7BN35 |
| | 40.0 m | 6XV1 830-7BN40 |
| | 45.0 m | 6XV1 830-7BN45 |
| | 50.0 m | 6XV1 830-7BN50 |
| Unprepared ECOFAST hybrid cable (2 copper conductors and 2×2 copper wires) in various | | |
| lengths: | 20.0 m | 6XV1 830-7AN20 |
| | 50.0 m | 6XV1 830-7AN50 |
| 1 | 00.0 m | 6XV1 830-7AT10 |
| ECOFAST hybrid cable, in meters (2 copper conductors and 2×2 copper wires) | | 6XV1 830-7AH10 |
| ECOFAST hybrid cable, fiber-optic cable fiber-optic cables and 2×2 copper wires) with ECOFAST connectors in various len | (2 complete gths: 1.5 m 3.0 m 5.0 m 10.0 m 15.0 m | 6XV1 830-6DH15 6XV1 830-6DH30 6XV1 830-6DH50 6XV1 830-6DN10 6XV1 830-6DN15 |
| Unprepared ECOFAST hybrid cable, fiber-optic cable | | |
| (2 fiber-optic cables and 2×2 copper wire | es) in | |
| various lengths: | 20.0 m | 6XV1 830-6CN20 |
| | 50.0 m | 6XV1 830-6CN50 |
| 1 | 00.0 m | 6XV1 830-6C110 |
| ECOFAST hybrid cable, fiber-optic cable, in metres (2 fiber-optic cables and 2×2 copper wires) | | 6XV1 830-6CH10 |
| Cover plate (to seal off unused DESINA/ECOFAST connection sockets); 10 units | | 6ES7 194-1JB10-0XA0 |

Table A-4 Accessories for ET 200X-DESINA / ET 200X-ECOFAST – order numbers, continued

| Descriptio | on | | Order number |
|--|----------------|----------------|----------------|
| DESINA/ECOFAST terminating | g resistor for | | |
| PROFIBUS-DP with copper conductors: 1 unit | | 6GK1 905-0DA10 | |
| | | 5 units | 6GK1 905-0DA00 |
| For preparing the cables: | | | |
| PROFIBUS ECOFAST Hybrid Plug 180 (ECOFAST | | | |
| Cu, 5 units) | With pin inser | t | 6GK1 905-0CA00 |
| | With socket in | sert | 6GK1 905-0CB00 |
| PROFIBUS ECOFAST Cyberoptic Hybrid Plug 180 (ECOFAST fiber-optic cable, 5 units) DESINA-compatible | | 6GK1 905-0BA00 | |
| | With pin inser | t | 6GK1 905-0BB00 |
| | With socket in | sert | |

For the connection between controller and power supply we recommend Harting accessories:

| Description | Order number |
|---|----------------|
| For the link between the controller and power supply: | |
| Media Converter PROFIBUS MCP12P | 20 40 004 3647 |

Address for ordering:

HARTING Vertrieb für Steckverbinder und Systemtechnik GmbH & Co. KG Postfach 2451 D-32381 Minden Tel. + 49 5 71 88 96 - 0 Fax + 49 5 71 88 96 - 2 82 E-mail: de.sales@HARTING.com Internet: http://www.HARTING.com

Connectors for Als/AOs

To connect actuators/sensors to the analog inputs/outputs of the corresponding expansion modules, use 4- or 5-pin M12 coupler plugs. We recommend the following connectors from Binder.

Table A-5 Connectors manufactured by Binder – order numbers

| Description | | Order number |
|-----------------|--------------------------|----------------|
| Connector 4-pin | Outgoing cable unit PG 7 | 99-1429-814-04 |
| Connector 4-pin | Outgoing cable unit PG 9 | 99-1429-812-04 |
| Connector 5-pin | Outgoing cable unit PG 7 | 99-1437-814-05 |
| Connector 5-pin | Outgoing cable unit PG 9 | 99-1437-812-05 |

Address for ordering:

Franz Binder GmbH + Co.-74172 Neckarsulm
Spare parts for ET 200X

| Description | Order number |
|--|-------------------------|
| Labels for ET 200X (10 \times 8 mm) (20 strips of 40 labels) | 6ES7 194-1BA00- 0XA0 |
| Labels for ET 200X, ET 200X-DESINA and ET 200X-ECOFAST (20 \times 9 mm) (19 strips of 20 labels) | 3RT 1900-1SB50 |
| Plugs for pneumatic module | 6ES7 194-1JA00-0XA0 |
| Connector plate (for BM 141, BM 142) | 6ES7 194-1FC00-0XA0 |

Table A-6 Spare parts for ET 200X – order numbers

Cables for the ET 200X

Table A-7 lists all the cables for the ET 200 distributed I/O system which you may require in conjunction with the ET 200X.

| Table A-7 | Network components for the ET 200 distributed I/O system |
|-----------|--|
|-----------|--|

| | Network components | Order number |
|---------------------------|---|---------------------|
| Cables: | | |
| • 2-core | e, shielded cable (bus cable) | 6XV1 830-0AH10 |
| 2-core haloge | e, shielded cable (bus cable) en free | 6XV1 830-0CH10 |
| • 2-core with F | e, shielded cable (bus cable) PUR sheath | 6XV1 830-0DH10 |
| • 2-core | e, shielded cable (bus cable) with PE sheath | 6XV1 830-0BH10 |
| • 2-core | e, shielded cable (bus cable) for festooning | 6XV1 830-3CH10 |
| • Drum | cable | 6XV1 830-3BH10 |
| Direct | -buried cable | 6XV1 830-3AH10 |
| Cable with F | , 5-core, uncut (for bus and sensor supply; VC sheath) | 6ES7 194-1LY00-0AA0 |
| Cable condit supply | , 5-core, uncut; oil-resistant, drum-capable, ionally welding-resistant (for bus and sensor y; with PUR sheath) | 6ES7 194-1LY10-0AA0 |

MOBY modules

The following expansion module can be used with the ET 200X.

Table A-8 MOBY modules

| Network components | Order number |
|-----------------------------------|----------------|
| ASM 473 interface module for MOBY | 6GT2 002-0HA10 |

Manuals for STEP 7 and SIMATIC S7

You require one of the manuals listed below to program and commission the ET 200X with *STEP 7*.

Table A-9 Manuals for STEP 7 and SIMATIC S7

| Manual | Contents |
|---|---|
| S7-300 Programmable Controller Hardware and Installation | etc. Description of the PROFIBUS-DP master interface of CPU 315-2 DP Installing a PROFIBUS-DP network RS 485 repeater |
| S7-400/M7-400 Programmable Controllers Hardware and Installation | etc. Description of the PROFIBUS-DP master interface in S7-400 and M7-400 Installing a PROFIBUS-DP network RS 485 repeater |
| System software for S7-300/400 Program design Programming Manual | etc. Description of addressing and diagnostics on SIMATIC S7 |
| System software for S7-300/400 System and standard functions Reference Manual | Description of the SFCs in STEP 7 |

Manual for the ET 200 in SIMATIC S5

You require the manual listed below to program and commission the ET 200X with *COM PROFIBUS*.

Table A-10 Manual for ET 200 in SIMATIC S5

| Manual | Order number | Contents |
|---------------------------|----------------|---|
| ET 200 distributed I/O | 6ES5 998-3ES.2 | Description of master interface IM 308-C for S5-115U/H, S5-135U and S5-155U/H |
| system | | Description of the S5-95U with the PROFIBUS-DP master interface |
| | | Description of the procedure for installing a DP system and an FMS system with the CP 5412 (A2) as master |
| | | Handling COM PROFIBUS |
| | | Handling FB IM308C/FB 230 |

Technical guide to PROFIBUS-DP with SIMATIC S7 and STEP 7

Table A-11 Technical Guide to PROFIBUS-DP and SIMATIC S7

| Technical guide | Order number | Contents |
|--|---|--|
| Decentralization with PROFIBUS-DP | In bookshops: ISBN 3-89578-123-1 | Instruction manual for a simple introduction to |
| Architecture and Fundamentals, Configuration and Use with SIMATIC S7 – Josef Weigmann, Gerhard Kilian Publicis MCD Verlag, 2nd Edition, 2000 | From your Siemens agent: A19100-L531-B772 | PROFIBUS-DP and implementation of automation tasks with PROFIBUS-DP and SIMATIC S7. Use of PROFIBUS-DP is illustrated for the SIMATIC-related examples. |

B

Device Master Files

Device master file

A device master file contains all the slave-specific features. The structure of the DDB file is specified in IEC 61784-1:2002 Ed1 CP 3/1.

You can download the device master files from the Internet. You will find all device master files under "Downloads" on the SIMATIC Customer Supports website at http://www.ad.siemens.de/csi/gsd.

Other features

| Table B-1 | Other features of the modules of the ET 200X |
|-----------|--|
|-----------|--|

| Basic/expansion module | Order number | Manufac- turer iden- tification | Consis- tency | Ad- dress scope (bytes) | Ad- dress range |
|--|---------------------|---------------------------------------|------------------|----------------------------------|-----------------------|
| BM 141 DI 8×DC 24V | 6ES7 141-1BF12-0XB0 | 803D _H | Byte | 1 | Digital |
| BM 141 DI 8×DC 24V ECOFAST | 6ES7 141-1BF01-0AB0 | 80D2 _H | Byte | 1 | Digital |
| BM 141 DI 8×DC 24V ECOFAST DIAG | 6ES7 141-1BF40-0AB0 | 80D3 _H | Byte | 1 | Digital |
| BM 142 DO 4×DC 24V/2A | 6ES7 142-1BD22-0XB0 | 803C _H | Byte | 1 | Digital |
| BM 143-DESINA FO | 6ES7 143-1BF00-0XB0 | 809A _H | Byte | 2* | Digital |
| BM 143-DESINA RS485 | 6ES7 143-1BF00-0AB0 | 809A _H | Byte | 2* | Digital |
| EM 141 DI 4×DC 24V | 6ES7 141-1BD31-0XA0 | - | Byte | 1 | Digital |
| EM 141 DI 8×DC 24V | 6ES7 141-1BF31-0XA0 | - | Byte | 1 | Digital |
| EM 141 DI 8×DC 24V DIAG | 6ES7 141-1BF30-0XB0 | - | Byte | 1 | Digital |
| EM 141 DI 8×DC 24V | 6ES7 141-1BF41-0XA0 | - | Byte | 1 | Digital |
| EM 141 DI 8×DC 24V DIAG | 6ES7 141-1BF40-0XB0 | - | Byte | 1 | Digital |
| EM 142 DO 4×DC 24V/0.5A | 6ES7 142-1BD30-0XA0 | - | Byte | 1 | Digital |
| EM 142 DO 4×DC 24V/2A | 6ES7 142-1BD40-0XA0 | - | Byte | 1 | Digital |
| EM 142 DO 4×DC 24V/2A | 6ES7 142-1BD40-0XB0 | - | Byte | 1 | Digital |
| EM 142 DO 8×DC 24V/1.2A | 6ES7 142-1BF30-0XA0 | - | Byte | 1 | Digital |
| EM 143-DESINA | 6ES7 143-1BF30-0XB0 | - | Byte | 2* | Digital |
| EM 144 AI 2×U | 6ES7 144-1FB31-0XB0 | _ | Word | 4 | Analog |
| EM 144 AI 2×I (±20 mA) | 6ES7 144-1GB31-0XB0 | - | Word | 4 | Analog |
| EM 144 AI 2×I (4 to 20 mA) | 6ES7 144-1GB41-0XB0 | - | Word | 4 | Analog |
| EM 144 AI 2×RTD | 6ES7 144-1JB31-0XB0 | - | Word | 4 | Analog |
| EM 145 AO 2×U | 6ES7 145-1FB31-0XB0 | - | Word | 4 | Analog |
| EM 145 AO 2×I | 6ES7 145-1GB31-0XB0 | - | Word | 4 | Analog |
| EM 148-P DI $4 \times$ DC 24V/DO $2 \times$ P expansion module | 6ES7 148-1DA00-0XA0 | - | Byte | 1* | Digital |
| EM 148-P DO 16×P/CPV10 expansion module | 6ES7 148-1EH01-0XA0 | - | Byte | 2 | Digital |
| EM 148-P DO 16×P/CPV14 expansion module | 6ES7 148-1EH11-0XA0 | - | Byte | 2 | Digital |

* for inputs and outputs

С

Dimesioned Drawings and Pinouts

You will find dimensioned drawings of the most important components of the ET 200X below. You will also find essential pinout information for the ET 200X.

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C.1 Dimensioned drawings – basic modules

BM 141, BM 142 and BM 147/CPU basic modules

Figure C-1 below is a dimensioned drawing of a BM 141, BM 142, BM 147/CPU basic module with bus connectors. You must add the length of the M16 cable glands and the bending radius of your particular cable to the overall width and depth specified.



Figure C-1 Dimensioned drawing of BM 141, BM 142, BM 147/CPU basic module

DESINA and ECOFAST basic modules

The following figure C-2 shows you the dimensioned drawing of the basic modules BM 141-ECOFAST and BM 143-DESINA with DESINA connectors.

You have to add the bending radius of the DESINA hybrid cable to the specified overall height. You might have to add the length of the coupler plugs and the bending radius of your particular cable to the specified overall depth.



Figure C-2 Dimensioned drawing of the BM 141-ECOFAST, BM 143-DESINA basic modules

C.2 Dimensioned drawings – expansion modules

The following figure C-3 shows you the dimensioned drawing of the expansion modules EM 141, EM 142, EM 144, and EM 145. You must add the length of the coupler plugs/Y busbar connection pieces and the bending radius of your particular cable to the overall depth specified.





Figure C-4 below is a dimensioned drawing of EM 141 (high design), EM 142 DO 8 x DC 24V/1.2A and EM 143-DESINA expansion modules.

You must add the length of the coupler plugs and the bending radius of your particular cable to the specified overall depth.





C.3 Dimensioned drawing – pneumatic module EM 148-P DI 4 \times DC 24 V/DO 2 \times P

The dimensioned drawing of the pneumatic module is shown below. You have to add the length and bending radius of the tubing to the specified overall height.



Figure C-5 Dimensioned drawing of the pneumatic module

C.4 Dimensioned drawing – pneumatic interface module EM 148-P DO 16 × P/CPV10 and ...14

The dimensioned drawing of the pneumatic interface module is shown below. You must add the depth of the FESTO valve island, and the length and bending radius of the tubing to the specified overall depth.



Figure C-6 Dimensioned drawing of the pneumatic interface module

C.5 Dimensioned drawing – power module

The diagram below is a dimensioned drawing of a power module. You must add the length of the coupler plugs/Y connectors and the bending radius of your particular cables to the specified overall depth. You must add the bending radius of your particular cable to the specified overall height if the load voltage is looped through.



Figure C-7 Dimensioned drawing – power module

C.6 Dimensioned drawing – SITOP power supply unit

The figure below shows the dimensioned drawing of the SITOP power power supply. You must add the bending radius of your particular cable to the specified overall height.



Figure C-8 Dimensioned drawing of SITOP power



C.7 Dimensioned drawings – DIN rails

Figure C-9 Dimensioned drawings of the Narrow DIN rails

Note

You must cut the narrow DIN rail (with a length of 2000) to suit your requirements and drill the mounting holes for M8 screws.

To ensure that all the ET 200X modules have the specified vibration resistance, the mounting holes should be spaced at even intervals of a maximum 200 mm after initial spacing of 12 mm.



Figure C-10 Dimensioned drawings of the wide DIN rails

C.8 Pinout of the ET 200X

Figure C-11 below shows the pinout of the ET 200X on a BM 141, BM 142, BM 147/CPU basic module. The arrangement of sockets X1 to X4 is the same on all basic and expansion modules (BM 141, BM 142, EM 141, EM 142, EM 144, EM 145) with digital inputs and outputs.



Figure C-11 Pinout of the ET 200X (BM 141, BM 142, BM 147/CPU)

| Socket | Pinout of 8-channel DI | Pinout of 4-channel DI | Pinout of 4-channel DO | Pinout of pneumatic module (4-channel DI) |
|--------|---|---|--|---|
| X1 | Sensor supply output L+ Input signal, channel 4 Grounding supply voltage Input signal, channel 0 PE | Sensor supply output L+ Input signal, channel 1 Grounding supply voltage Input signal, channel 0 PE | 1 – 2 Output signal, channel 1 3 Grounding Load current power supply 4 Output signal, channel 0 5 PE | Sensor supply output L+ Input signal, channel 1 Grounding supply voltage Input signal, channel 0 PE |
| X2 | Sensor supply output L+ Input signal, channel 5 Grounding supply voltage Input signal, channel 1 PE | Sensor supply output L+ - Grounding supply voltage Input signal, channel 1 PE | 1 – 2 – 3 Grounding Load current power supply 4 Output signal, channel 1 5 PE | Sensor supply output L+ Input signal, channel 3 Grounding supply voltage Input signal, channel 2 PE |

| Socket | Pinout of 8-channel DI | Pinout of 4-channel DI | Pinout of 4-channel DO | Pinout of pneumatic module (4-channel DI) |
|--------|---|---|---|---|
| Х3 | Sensor supply output L+ Input signal, channel 6 Grounding supply voltage Input signal, channel 2 PE | Sensor supply output L+ Input signal, channel 3 Grounding supply voltage Input signal, channel 2 PE | 1 – 2 Output signal, channel 3 3 Grounding Load current power supply 4 Output signal, channel 2 5 PE | _ |
| X4 | Sensor supply output L+ Input signal, channel 7 Grounding supply voltage Input signal, channel 3 PE | Sensor supply output L+ - Grounding supply voltage Input signal, channel 3 PE | 1 – 2 – 3 Grounding Load current power supply 4 Output signal, channel 3 5 PE | _ |

C.9 Pinout of the 8-channel expansion modules

Figure C-12 below shows the pinout of the 8-channel DI/DO expansion modules of the ET 200X on an expansion module (high design). The arrangement of sockets X1 to X8 is the same on all expansion modules with digital inputs and outputs.



Figure C-12 Pinout of the 8-channel DI/DO expansion module

| Socket | Pinout 8-channel DI | Pinout 8-channel DO |
|----------|---|--|
| X1 to X8 | Sensor supply output L+ not assigned Grounding supply voltage Input signal channel n PE | not assigned not assigned Grounding load current power supply Output signal channel n PE |

C.10 Pinout of the ET 200X-DESINA

Figure C-13 shows you the pinout of the ET 200X-DESINA using the example of the BM 143-DESINA FO basic module.

The BM 143-DESINA RS485 basic module has the same pinout on the PROFIBUS-DP connection (pins 5 and 6) but has copper conductors instead of fiber-optic cables. The arrangement of sockets X1 to X8 is identical for all DESINA basic and expansion modules with digital inputs and outputs.



Figure C-13 Pinout of the ET 200X-DESINA

| Socket | Pinout of the 8-channel DI/DO | | | |
|--------|---|--|--|--|
| X1 | 1 Sensor supply output L+ (NS) | | | |
| X3 | 2 Diagnostic input or input with NC function. | | | |
| X5 | Grounding supply voltage Digital input or output (DESINA) channels 0, 2, 4 and 6 | | | |
| X7 | 5 not assigned | | | |
| X2 | 1 Sensor supply output L+ (NS) | | | |
| X4 | 2 Diagnostic input or input with NC function. | | | |
| X6 | Grounding supply voltage Digital input or output (DESINA) channels 1, 3, 5 and 7 | | | |
| X8 | 5 not assigned | | | |

C.11 Pinout of the ET 200X-ECOFAST



Figure C-14 shows the pinout of the BM 141-ECOFAST 8DI basic module.

Figure C-14 Pinout of the BM 141-ECOFAST 8DI basic module

| Socket | Pinout of the BM 141-ECOFAST 8DI | | | | |
|----------------------|--|--|--|--|--|
| X1 X3 X5 X7 | Sensor supply output L+ (NS) not assigned Grounding supply voltage Digital input channels 0, 2, 4 and 6 not assigned | | | | |
| X2 X4 X6 X8 | Sensor supply output L+ (NS) not assigned Grounding supply voltage Digital input channels 1, 3, 5 and 7 not assigned | | | | |

C.12 Pinout of analog inputs/outputs

Figure C-15 below shows the pinout of the inputs/outputs of the ET 200X on an expansion module. The arrangement of the sockets is identical for all expansion modules with analog inputs and outputs.



Figure C-15 Pinout of expansion module with analog inputs/outputs

| Socket | Pinout of 2-channel AI | | Pinout of 2-channel AO | |
|--------|---------------------------|--------------------------|--------------------------|--------------------------|
| | Voltage/current | Current | Voltage | Current |
| | ±10 V ±20 mA Pt 100 | 4 to 20 mA | ±10 V | ±20 mA 4 to 20 mA |
| X1 | 1 L+ | 1 L+; channel 0 (+) | 1 Qv channel 0 | 1 QI channel 0 |
| | 2 Channel 0 (+) | 2 Channel 0 (-) | 2 – | 2 – |
| | 3 Ground power supply | 3 Ground power supply | 3 Ground power supply | 3 Ground power supply |
| | 4 Channel 0 (-) | 4 – | 4 – | 4 – |
| X2 | 1 L+ | 1 L+; channel 1 (+) | 1 Qv channel 1 | 1 QI channel 1 |
| | 2 Channel 1 (+) | 2 Channel 1 (-) | 2 – | 2 – |
| | 3 Ground power supply | 3 Ground power supply | 3 Ground power supply | 3 Ground power supply |
| | 4 Channel 1 (-) | 4 – | 4 – | 4 – |

Glossary

Aggregate current

Aggregate of the currents of all output channels of a digital output module.

Automation system

An automation system is a programmable logic controller consisting of at least one CPU, various input and output modules and operator interfaces.

Bus

Common transmission channel to which all stations are connected; a bus has two defined ends.

In the case of the ET 200, the bus is a two-wire or fiber-optic cable.

Bus connector

The physical link between bus node and bus cable. There is a special bus connector for ET 200X (= connector for PROFIBUS-DP) with a degree of protection rating of IP 65.

Chassis ground

Chassis ground refers to all the interconnected inactive parts of a piece of equipment that, even in the event of a fault, cannot carry voltage that is dangerous to the touch.

Configure

Configuring means planning individual components in a distributed I/O system.

Device master file

A device master file contains all the DP-slave-specific features. The format of the DDB file is specified in *IEC 61784-1:2002 Ed1 CP 3/1*.

DESINA

Distributed and Standardized INstAllation technique for machine tools DESINA is an all-inclusive general concept for standardization of installation-relevant components in terms of function and connection technology. End-to-end usage of DESINA-compliant components can produce significant savings in the costs of system planning, implementation and operation.

Diagnostic interrupt

Diagnostics-compatible modules use diagnostic interrupts to notify the central CPU of system errors.

In SIMATIC S7/M7: When an error is detected or disappears (e.g. wire break), ET 200X triggers a diagnostic interrupt, provided the interrupt is enabled. The CPU of the DP master interrupts the processing of the user program and lower priority classes and processes the diagnostic interrupt block (OB 82).

In SIMATIC S5: The diagnostic interrupt appears in the station diagnosis. Using cyclical querying of the diagnostic bits in the station diagnosis you can detect errors such as a wire break.

Diagnostics

Diagnostics means the detection, localization, classification, reporting and evaluation of faults, malfunctions and messages.

Diagnostics incorporates monitoring functions which run automatically while the system is in operation. This enhances system availability by reducing setup times and outages.

Direct starter

A direct starter is a \rightarrow Motor starter which switches a motor on or off directly. It consists of a power circuit-breaker and a contactor.

Distributed I/O devices

These are input/output units that are not located in the base unit; instead, they are distributed at some distance from the CPU. The following are examples of such units:

- ET 200M, ET 200B, ET 200C, ET 200U, ET 200X, ET 200L
- DP/AS-I Link
- S5-95U with PROFIBUS-DP slave interface
- Other DP slaves from either Siemens or other vendors

The distributed I/O devices are connected to the DP master via PROFIBUS-DP.

DP address

 \rightarrow PROFIBUS address

DP master

A \rightarrow master that complies with *IEC 61784-1:2002 Ed1 CP 3/1* is described as a DP master.

DP slave

A \rightarrow slave that is operated on PROFIBUS with the PROFIBUS-DP protocol and that complies with *IEC 61784-1:2002 Ed1 CP 3/1* standard is called a DP slave.

DP standard

The DP standard is the bus protocol of the ET 200 distributed I/O system based on *IEC 61784-1:2002 Ed1 CP 3/1*.

DPV0

Cyclic data transfer between the DP master and DP slaves.

DPV1

Extension of DPV0 with an acyclic data transfer between the DP master and DP slaves.

Equipotential bonding

Electrical connection (equipotential bonding conductor) that brings the parts of electrical equipment and other conductive parts to the same or approximately the same potential in order to prevent troublesome or dangerous voltages arising between these parts.

Error handling

 \rightarrow Diagnostics

External power supply

Power supply for the ET 200X distributed I/O device and the process peripherals connected to it.

FREEZE

This is a control command of the DP master to a group of DP slaves.

When a DP slave receives the FREEZE control command, it freezes the current status of the **inputs** and transfers them cyclically to the DP master.

After each subsequent FREEZE control command, the DP slave freezes the status of the **inputs** again.

The input data is not transferred from the DP slave to the DP master again cyclically until the DP master sends the UNFREEZE control command.

Frequency converter

On the ET 200X the frequency converter is used for infinitely variable adjustment of the speed and adaptation of the power of asynchronous motors up to 1.5 kW rated power. Temperature monitoring device and motor brake are integrated.

The converter is parameterized appropriately for the connected motor. Operation of the frequency converter is controlled by the software.

Ground

The conductive mass of earth, the electrical potential of which can be set to zero at any point. In the vicinity of grounding electrodes the potential may not be zero. The term "reference ground" is often used here.

Grounding

Grounding means to connect a conductive component with the grounding electrode via a ground system.

Isolated

In the case of isolated input/output modules, the reference potentials of the control and load circuit are galvanically isolated – by means of optical isolators or relay contacts, for example. Input/output circuits can be grouped.

Master

When they are in possession of the token, masters can send data to and request data from other nodes (= active node). The CPU 315-2 DP and the IM 308-C are examples of DP masters.

Motor starter

Motor starter is the overall term for \rightarrow Direct and \rightarrow Reversing Starters. Motor starters determine the start-up and direction of rotation of a motor (= load).

Node

A device that can send, receive or amplify data via the bus, such as a DP master, DP slave, RS 485 repeater or active star coupler.

Node address

 \rightarrow PROFIBUS address

Non-isolated

In the case of non-isolated input/output modules, the reference potentials of the control and load circuit are electrically connected.

Parameterize

Parameterizing means sending slave parameters from the DP master to the DP slave.

PROFIBUS

PROcess Fleld BUS – German process and field bus standard that is defined in *IEC 61784-1:2002 Ed1 CP 3/1*. It defines the functional, electrical and mechanical properties of a bit-serial field bus system.

PROFIBUS is available with the protocols DP (the German abbreviation for distributed I/O), FMS (= field bus message specification), PA (= process automation), or TF (= technology functions).

PROFIBUS address

Each bus node must receive a PROFIBUS address to uniquely identify it on the PROFIBUS bus system.

The PC/programming device has the PROFIBUS address "0".

PROFIBUS addresses 1 to 125 are permissible for the ET 200X distributed I/O device.

Reference potential

Potential from which the voltages of the circuits involved can be observed and/or measured.

Reversing starter

A reversing starter is a \rightarrow motor starter which determines a motor's direction of rotation. It consists of a power circuit-breaker and two contactors.

Segment

The bus line between two terminating resistors forms a segment. A segment contains 0 to $32 \rightarrow$ nodes. Segments can be interconnected by means of RS 485 repeaters.

Slave

A slave can only exchange data with a \rightarrow master when requested by it to do so. By slaves we mean, for example, all DP slaves, such as ET 200B, ET 200X, ET 200M etc.

Station number

 \rightarrow PROFIBUS address

SYNC

This is a control command of the DP master to a group of DP slaves.

By means of the SYNC control command the DP master causes the DP slave to freeze the current statuses of the **outputs**. In the subsequent frames, the DP slave stores the output data, but the statuses of the outputs remain unchanged.

After each new SYNC control command, the DP slave sets the outputs that it has stored as output data. The outputs are not cyclically updated again until the DP master sends the UNSYNC control command.

Terminating resistor

The terminating resistor is a resistor for adjusting the power on the bus cable; terminating resistors must be used on the cable and segment ends.

The terminating resistors in the ET 200X are switched on and off in the basic module.

The ET 200X-DESINA connects to the bus by means of a fiber-optic waveguide, so no terminating resistors are required.

Transmission rate

The transmission rate of a data transfer is measured in bits transmitted per second (transmission rate = bit rate).

In the case of the ET 200X, transmission rates of 9.6 kbps to 12 Mbps are possible.

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